# On the functions with values in $[\alpha(G), \bar{\chi}(G)]$ 

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#### Abstract

Let $$
\mathcal{B}(G)=\left\{X: X \in \mathbb{R}^{n \times n}, X=X^{T}, I \leq X \leq I+A(G)\right\}
$$


and

$$
\mathcal{C}(G)=\left\{X: X \in \mathbb{R}^{n \times n}, X=X^{T}, I-A(G) \leq X \leq I+A(G)\right\}
$$

be classes of matrices associated with graph $G$. Here $n$ is the number of vertices in graph $G$, and $A(G)$ is the adjacency matrix of this graph. Denote $r(G)=$ $\min _{X \in \mathcal{C}(G)} \operatorname{rank}(X), r_{+}(G)=\min _{X \in \mathcal{B}(G)} \operatorname{rank}(X)$. We have shown previously that for every graph $G, \alpha(G) \leq r_{+}(G) \leq \bar{\chi}(G)$ holds and $\alpha(G)=r_{+}(G)$ implies $\alpha(G)=\bar{\chi}(G)$. In this article we show that there is a graph $G$ such that $\alpha(G)=r(G)$ but $\alpha(G)<\bar{\chi}(G)$. In the case when the graph $G$ doesn't contain two chordless cycles $C_{4}$ with a common edge, the equality $\alpha(G)=r(G)$ implies $\alpha(G)=\bar{\chi}(G)$. Corollary: the last statement holds for $d(G)$ - the minimal dimension of the orthonormal representation of the graph $G$.

Let $G$ be a graph with vertex set $V(G)=\{1, \ldots, n\}$ and edge set $E(G)$. We are interested in studying the functions of the graph $G$ whose values belong to the interval $[\alpha(G), \bar{\chi}(G)]$. Here $\alpha(G)$ is the size of the largest stable set in $G$ and $\bar{\chi}(G)$ is the smallest number of cliques that cover the vertices of $G$.

It is well known (see, for example, [1]) that for some $\epsilon>0$ it is impossible to approximate in polynomial time $\alpha(G)$ and $\bar{\chi}(G)$ within a factor of $n^{\epsilon}$, assuming $P \neq N P$. We suppose that better approximation could be obtained for narrow classes of graphs determined on the basis of a system of functions of graph $G$ "sandwiched" between $\alpha(G)$ and $\bar{\chi}(G)$.

One such function is the well known Lovász function $\theta(G)[7]$, which has many alternative definitions. One of them is based on the notion of the orthonormal labeling of the graph. Orthonormal labeling of dimension $k$ of the graph $G$ is a mapping

$$
f: V(G) \rightarrow \mathbb{R}^{k}
$$

such that $\|f(v)\|_{2}=1$ for all $v \in V(G)$ and $f\left(v_{i}\right) \cdot f\left(v_{j}\right)=0$ if $\left\{v_{i}, v_{j}\right\} \notin E(G)$.

Let $e_{i} \in \mathbb{R}^{k}$ be a unit vector which is 0 in all coordinates except the $i$ th coordinate which is equal 1. Then

$$
\theta(G)=\min _{f} \max _{v \in V(G)} \frac{1}{\left(e_{1} \cdot f(v)\right)^{2}}
$$

and

$$
\alpha(G) \leq \theta(G) \leq d(G) \leq \bar{\chi}(G)
$$

where $d(G)$ is the minimum dimension of the orthonormal labeling of the graph $G$.
Let

$$
\mathcal{B}(G)=\left\{X: X \in \mathbb{R}^{n \times n}, X=X^{T}, I \leq X \leq I+A(G)\right\}
$$

and

$$
\mathcal{C}(G)=\left\{X: X \in \mathbb{R}^{n \times n}, X=X^{T}, I-A(G) \leq X \leq I+A(G)\right\}
$$

be classes of matrices associated with graph $G$. Here $n$ is the number of vertices of graph $G, I$ is identity matrix and $A(G)$ is the adjacency matrix of this graph. Consider two functions of graph $G$ based on these classes:

$$
\begin{aligned}
r(G) & =\min _{X \in \mathcal{C}(G)} \operatorname{rank}(X) \\
r_{+}(G) & =\min _{X \in \mathcal{B}(G)} \operatorname{rank}(X)
\end{aligned}
$$

The function $r_{+}(G)$ was studied in [2]. It was shown that for every graph $G$

$$
\alpha(G) \leq r_{+}(G) \leq \bar{\chi}(G)
$$

holds and

$$
\begin{equation*}
\alpha(G)=r_{+}(G) \quad \text { implies } \quad \alpha(G)=\bar{\chi}(G) \tag{1}
\end{equation*}
$$

It is obvious that

$$
\alpha(G) \leq r(G) \leq d(G), r_{+}(G) \leq \bar{\chi}(G)
$$

It is was shown in[3] that for $i=1,2,3 \quad r(G)=i$ iff $d(G)=i$.
Recent results on well known related problem concerning upper bound on $\chi(G)$ in terms of rank of adjacency matrix $A(G)$ are presented in $[4,5,6]$.

In this paper we are interested in the following question: can we use the functions $\theta(G), r(G)$ and $d(G)$ in (1) instead of $r_{+}(G)$ ? In the common case the answer is negative. The proof is based on the following lemmas.

Lemma 1 If $\alpha(G)=d(G)$ implies $\alpha(G)=\bar{\chi}(G)$ for every graph $G$ then for every set of unit vectors $S=\left\{s_{1}, \ldots, s_{n}\right\}$ with $s_{i} \in \mathbb{R}^{k}$ there exists an orthogonality-preserving mapping

$$
\varphi: S \rightarrow \mathbb{R}_{+}^{k}
$$

of vectors from $S$ into non-negative unit vectors from $\mathbb{R}^{k}$ such that $s_{i} \cdot s_{j}=0$ implies $\varphi\left(s_{i}\right) \cdot \varphi\left(s_{j}\right)=0$.

Proof. Suppose that $\alpha(G)=d(G)$ implies $\alpha(G)=\bar{\chi}(G)$ for every graph $G$. Then we can construct above mentioned mapping $\varphi$ for every vector set $S$.

Let $S=\left\{s_{1}, \ldots, s_{n}\right\}, \quad s_{i} \in \mathbb{R}^{k}$ be a given vector set. Then we can construct graph $G=(V(G), E(G))$, where $V(G)=A \cup B, A \cap B=\emptyset, A=\left\{a_{1}, \ldots, a_{k}\right\}, B=\left\{b_{1}, \ldots, b_{n}\right\}$. Assign unit vector $e_{i} \in \mathbb{R}^{k}$ to vertex $a_{i} \in A$ and vector $s_{j}$ to vertex $b_{j} \in B$ for $i=$ $1, \ldots, k, \quad j=1, \ldots, n$.

To form edge set $E(G)$ :

- join every vertex from $A$ with every vertex from $B$;
- join $b_{i}$ and $b_{j}$ from $B$ iff $s_{i} \cdot s_{j} \neq 0$.

It is obvious that $A$ is a maximum stable set of the graph $G$ and $\alpha(G)=d(G)=k$. Our assumption implies that $\alpha(G)=\bar{\chi}(G)$ and there exists a decomposition

$$
B=B_{1} \cup \cdots \cup B_{k},
$$

such that every $B_{i}$ induces a clique in $G$. So $\varphi: \varphi\left(s_{i}\right)=e_{j}$ when $b_{i} \in B_{j}$, is the required orthogonality-preserving mapping of $S$ into $\mathbb{R}_{+}^{k}$.

Now we'll construct a system of unit vectors from $\mathbb{R}^{3}$ such that orthogonal-preserving mapping of this set into $\mathbb{R}_{+}^{3}$ does not exists.

Lemma 2 Let

$$
S=\left\{a, b_{1}, b_{2}, b_{3}, c_{1}, c_{2}, c_{3}, d_{1}, d_{2}, d_{3}, e_{1}, e_{2}, e_{3}\right\}
$$

be a system of vectors from $\mathbb{R}^{3}$, where

$$
\begin{gathered}
a=(1,1,1)^{T}, \\
b_{1}=(-1,1,0)^{T}, b_{2}=(1,0,-1)^{T}, b_{3}=(0,-1,1)^{T}, \\
c_{1}=(1,1,0)^{T}, c_{2}=(1,0,1)^{T}, c_{3}=(0,1,1)^{T} \\
d_{1}=(-1,1,1)^{T}, d_{2}=(1,-1,1)^{T}, d_{3}=(1,1,-1)^{T}, \\
e_{1}=(1,0,0)^{T}, e_{2}=(0,1,0)^{T}, e_{3}=(0,0,1)^{T} .
\end{gathered}
$$

Then orthogonality-preserving mapping $\varphi$ of the set $S$ into a set of unit vectors from $\mathbb{R}_{+}^{3}$ does not exists.

Proof. Suppose that the above mentioned mapping $\varphi$ exists. Then $\varphi$ can be chosen in such a way that every vector from $S$ is mapped into one of the vectors from $\left\{e_{1}, e_{2}, e_{3}\right\}$.

Indeed, let $\varphi^{\prime}$ be a orthogonality-preserving mapping from $S$ into a set of unit vectors from $\mathbb{R}_{+}^{3}$. Then for every $s \in S$ and any $i$ such that $e_{i} \cdot \varphi^{\prime}(s)>0$ let $\varphi(s)=e_{i}$.

We may suppose without loss of generality that $\varphi\left(e_{i}\right)=e_{i}, i=1,2,3$.
Let's suppose that $\varphi(a)=e_{1}$. This implies $\varphi\left(b_{1}\right)=e_{2}, \varphi\left(b_{2}\right)=e_{3}, \varphi\left(c_{1}\right)=e_{1}, \varphi\left(c_{2}\right)=$ $e_{1}, \varphi\left(d_{2}\right)=e_{2}, \varphi\left(d_{3}\right)=e_{3}$. But then $\varphi\left(c_{3}\right)$ has to be orthogonal to every vector from $\left\{e_{1}, e_{2}, e_{3}\right\}$.

Let's suppose that $\varphi(a)=e_{2}$. This implies $\varphi\left(b_{1}\right)=e_{1}, \varphi\left(b_{3}\right)=e_{3}, \varphi\left(c_{1}\right)=e_{2}, \varphi\left(c_{3}\right)=$ $e_{2}, \varphi\left(d_{1}\right)=e_{1}, \varphi\left(d_{3}\right)=e_{3}$. But then $\varphi\left(c_{2}\right)$ has to be orthogonal to every vector from $\left\{e_{1}, e_{2}, e_{3}\right\}$.

Let's suppose that $\varphi(a)=e_{3}$. This implies $\varphi\left(b_{2}\right)=e_{1}, \varphi\left(b_{3}\right)=e_{2}, \varphi\left(c_{2}\right)=e_{3}, \varphi\left(c_{3}\right)=$ $e_{3}, \varphi\left(d_{1}\right)=e_{1}, \varphi\left(d_{2}\right)=e_{2}$. But then $\varphi\left(c_{1}\right)$ has to be orthogonal to every vector from $\left\{e_{1}, e_{2}, e_{3}\right\}$.

Lemmas 1 and 2 imply the following theorem.
Theorem 1 There exists a graph $G$ such that $\alpha(G)=d(G)$ and $\alpha(G)<\bar{\chi}(G)$.
Corollary 1 There exists graphs $G$ such that $\alpha(G)=\theta(G)=r(G)$ and $\alpha(G)<\bar{\chi}(G)$.
The following theorem shows that implication (1) holds for the function $r(G)$ (and, hence, for $d(G))$ in some cases.

Theorem 2 If the graph $G$ is free of two chordless cycles $C_{4}$ with a common edge then $\alpha(G)=r(G)$ implies $\alpha(G)=\bar{\chi}(G)$.

Proof. Suppose that $\alpha(G)=r(G)$ and $\alpha(G)=\operatorname{rank}(X), X \in \mathcal{C}(G)$. Without loss of generality $M=\{1, \ldots, \alpha(G)\}$ is the maximum stable set of the graph $G$ with $n$ vertices. Then

$$
X=\left(\begin{array}{cc}
I_{\alpha(G)} & Y \\
Y^{T} & Z
\end{array}\right)
$$

and $Z=Y^{T} Y$.
This means that the following orthonormal labeling $f$ of dimension $\alpha(G)$ of the graph $G$ exists. If vertex $i \in M$ then $f(i)=e_{i} \in \mathbb{R}^{\alpha(G)}$, if vertex $j \in V \backslash M$ then $f(j)$ is equal to the $(j-\alpha(G))$ th column of the matrix $Y$.

Let's show that for any three vertices $l, i, j$ such that $l \in M, i, j \in V \backslash M$, if vertices $i$ and $j$ are non-adjacent and $e_{l} \cdot f(i) \neq 0, e_{l} \cdot f(j) \neq 0$ (hence, $l$ is adjacent to $i$ and $j$ ), then a vertex $m \in M(m \neq l)$ exists such that $e_{m} \cdot f(i) \neq 0$ and $e_{m} \cdot f(j) \neq 0$ (hence, $m$ is adjacent to vertices $i$ and $j$ also).

Because $i$ and $j$ are non-adjacent, we have

$$
f(i) \cdot f(j)=\sum_{s=1}^{\alpha(G)}\left(e_{s} \cdot f(i)\right)\left(e_{s} \cdot f(j)\right)=0
$$

But the summand $\left(e_{l} \cdot f(i)\right)\left(e_{l} \cdot f(j)\right)$ isn't equal 0 in the last sum. Hence, at least one more non-zero summand exists. Let it be $m$ th summand

$$
\left(e_{m} \cdot f(i)\right)\left(e_{m} \cdot f(j)\right) \neq 0
$$

Hence, vertex $m \in M$ is adjacent to vertices $i$ and $j$.
Let

$$
V(G)=V_{1} \cup \cdots \cup V_{q}, q \geq \alpha(G)
$$

be a decomposition of the vertex set of the graph $G$ into $q$ non-empty subsets such that

- $l \in V_{l}, l=1, \ldots, \alpha(G)$;
- if $i \in V(G) \backslash M, i \in V_{l}, 1 \leq l \leq \alpha(G)$, then $e_{l} \cdot f(i) \neq 0$;
- if $i, j \in V_{l}, 1 \leq l \leq q$, then vertices $i$ and $j$ are adjacent.

It is obvious that such a decomposition exists. For example, $V(G)$ can be decomposed into $n$ non-empty subsets.

Every $V_{i}$ induces a clique in the $G$ and, hence, $\bar{\chi}(G) \leq q$.
We suppose without loss of generality that no set $V_{i}$ from $\left\{V_{1}, \ldots, V_{\alpha(G)}\right\}$ can be extended with vertices from $V_{\alpha(G)+1}, \ldots, V_{q}$.

Let's suppose that $\alpha(G)<\bar{\chi}(G)$. Then $S=V_{\alpha(G)+1} \cup \cdots \cup V_{q} \neq \oslash$. Let $x \in S$ be an arbitrary vertex from $S$. Then vertex $l \in M$ exists such that $e_{l} \cdot f(x) \neq 0$ (because $f(x) \neq 0)$. The set $V_{l}$ can't be extended with vertex $x$. Hence the vertex $x_{l} \in V_{l}$ exists that isn't adjacent to $x$. Then the vertex $m \in M, m \neq l$ should exist that is adjacent to $x$ and $x_{l}$ and $e_{m} \cdot f(x) \neq 0, e_{m} \cdot f\left(x_{l}\right) \neq 0$.

A vertex $x_{m} \in V_{m}$ exists that is non-adjacent to $x$ because the set $V_{m}$ can't be extended with $x$. Then vertex $y \in M$ exists such that $y \neq m$ and $y$ is adjacent to $x$ and $x_{m}$. Note, that vertices $l$ and $y$ may coincide.

If $y \neq l$, then there are two chordless cycles $C_{4}$ with common edge in $G:\left(l, x_{l}, m, x, l\right)$ and $\left(m, x, y, x_{m}, m\right)$. If $y=l$, then such cycles exist also. They are $\left(l, x_{l}, m, x, l\right)$ and $\left(l, x, m, x_{m}, l\right)$.

Corollary 2 Let the graph $G$ be free of two chordless cycles $C_{4}$ with a common edge. Then $\alpha(G)=d(G)$ implies $\alpha(G)=\bar{\chi}(G)$.

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