# A Generalization of Tokuyama's Formula to the Hall-Littlewood Polynomials

Vineet Gupta

Department of Mathematics Stanford University Stanford, CA, U.S.A.

vineetg@stanford.edu

Uma Roy
PROMYS
Boston, MA, U.S.A

uma.roy.us@gmail.com

Roger Van Peski

Department of Mathematics Princeton University Princeton, NJ, U.S.A

rpeski@princeton.edu

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### Abstract

A theorem due to Tokuyama expresses Schur polynomials in terms of Gelfand-Tsetlin patterns, providing a deformation of the Weyl character formula and two other classical results, Stanley's formula for the Schur q-polynomials and Gelfand's parametrization for the Schur polynomials. We generalize Tokuyama's formula to the Hall-Littlewood polynomials by extending Tokuyama's statistics. Our result, in addition to specializing to Tokuyama's result and the aforementioned classical results, also yields connections to the monomial symmetric function and a new deformation of Stanley's formula.

**Keywords:** Hall-Littlewood polynomials; Tokuyama's formula; Gelfand-Tsetlin patterns

### 1 Introduction

Schur polynomials, a special class of symmetric polynomials, play an important role in representation theory. They encode the characters of irreducible representations of general linear groups, which may be computed via the Weyl character formula. Tokuyama [16] gave a deformation of the Weyl character formula for  $GL_n(\mathbb{C})$  (Cartan type  $A_n$ ). This formula expresses Schur polynomials in terms of statistics obtained from strict Gelfand-Tsetlin (GT) patterns and includes two other classical results as specializations, the Gelfand parameterization formula for Schur polynomials [7] and Stanley's formula for the Schur q-polynomials [14].

The ideas in [16] have been extended to other Cartan types. For example, combinatorial expressions of deformations of the Weyl denominator for Cartan types  $B_n$ ,  $C_n$ , and  $D_n$  were given by Okada [11] and Simpson [13], [12]. Hamel and King [8] replicate Tokuyama's deformation of the Weyl character formula in type  $C_n$ , Friedberg and Zhang [4] derive a similar result for type  $B_n$ , and Friedlander et al. [5] conjecture a Tokuyamatype formula for type  $G_2$ . These results are also often expressed using other combinatorial objects such as Young tableaux [6], alternating sign matrices [16], [11], [9], and 6-vertex or ice-type models [2, Chapter 19], [3], [15]. Hamel and King express the type  $A_n$  case [9]

and type  $C_n$  case [8] using 6-vertex partition functions, and Brubaker and Schultz [1] give Tokuyama-type deformations for types  $A_n$ ,  $B_n$ ,  $C_n$ , and  $D_n$  using modified ice models. One can also try to generalize Tokuyama's ideas to other symmetric polynomials, such as the Hall-Littlewood polynomials, and this is the problem we consider.

The Hall-Littlewood polynomials are a class of symmetric polynomials which may be viewed as a generalization of the Schur polynomials by a deformation along a parameter t. The Hall-Littlewood polynomials also interpolate between the dual bases of the Schur polynomials and the monomial symmetric functions at t=0 and t=1, respectively. These polynomials are used to determine characters of Chevalley groups over local and finite fields [16]. Stanley's formula expresses the Hall-Littlewood polynomials at the singular value t=-1 (commonly known as the Schur q-polynomials [10, Chapter III]) as a summation over strict GT patterns. However, there does not exist an analogue of Tokuyama's formula expressing the Hall-Littlewood polynomials as a summation over combinatorial statistics from GT patterns. In this paper we provide such a result. Theorem 21, in addition to linking the classical specializations of Tokuyama, reduces to a different deformation of Stanley's formula at t=-1, and a formula for the monomial symmetric functions in terms of GT patterns at t=1.

# 2 Preliminary Notation and a Theorem due to Tokuyama

A partition  $\lambda = (\lambda_1, \lambda_2, \dots, \lambda_n)$  is a finite tuple of nonnegative integers, referred to as parts. Unless otherwise stated, a partition will be assumed to be weakly decreasing, i.e.  $\lambda_i \geq \lambda_{i+1}$  for all i. The length of a partition  $\lambda$  is the number of parts in  $\lambda$ , and the size of  $\lambda$  is defined as  $|\lambda| = \sum_{i=1}^n \lambda_i$ . Addition of partitions of equal length is done componentwise, and given two partitions  $\lambda$  and  $\mu$  of lengths n and m respectively, we express their concatenation as the tuple  $\lambda ||\mu = (\lambda_1, \dots, \lambda_n, \mu_1, \dots, \mu_m)$ .

$$\rho_n = (n - 1, n - 2, \dots, 1, 0). \tag{1}$$

We often write  $\rho$  in place of  $\rho_n$  as the value of n is clear from context. We will typically use  $\alpha$  to denote some strictly decreasing partition, often taking  $\alpha = \lambda + \rho$  when  $\lambda$  is defined.

We write the polynomial f(x) as short for  $f(x_1, \ldots, x_n)$ , and similarly  $x^{\lambda} = x_1^{\lambda_1} \ldots x_n^{\lambda_n}$ . Furthermore, a permutation  $\sigma \in S_n$  acts on f(x) by permuting the variables  $x_i$ . The Weyl denominator  $\Delta_n$  is given by the formula

$$\Delta_n = \prod_{1 \le i < j \le n} (x_i - x_j). \tag{2}$$

A deformation of the Weyl denominator  $\Delta_n(t)$  is given by the similar formula

$$\Delta_n(t) = \prod_{1 \le i < j \le n} (x_i - tx_j). \tag{3}$$

Note that  $\Delta_n(1) = \Delta_n$  and  $\Delta_n(0) = x^{\rho}$ .

Define the partition  $\rho_n$  as

**Theorem 1** (Weyl Character Formula for  $GL_n$ ). The Schur polynomial corresponding to the partition  $\lambda$  of length n is

$$s_{\lambda}(x) = \sum_{\sigma \in S_n} \sigma\left(\frac{x^{\lambda+\rho}}{\Delta_n}\right). \tag{4}$$

We may define the Hall-Littlewood polynomials analogously using the deformation of the Weyl denominator as follows.

**Definition 2.** The Hall-Littlewood polynomial for a partition  $\lambda$  of length n is

$$R_{\lambda}(x;t) = \sum_{\sigma \in S_n} \sigma \left( x^{\lambda} \frac{\Delta_n(t)}{\Delta_n} \right). \tag{5}$$

It is not difficult to see that  $R_{\lambda}(x;0) = s_{\lambda}(x)$  and  $R_{\lambda}(x;1) = \sum_{\sigma \in S_n} \sigma(x^{\lambda})$ , the monomial symmetric function  $m_{\lambda}(x)$ .

Note: The Hall-Littlewood polynomials defined in [10, Chapter III] are given by

$$P_{\lambda}(x;t) = v_{\lambda}(t)R_{\lambda}(x;t), \tag{6}$$

for a stabilizing factor  $v_{\lambda}(t)$ . Since the stabilizing factor may easily be multiplied to Theorem 21 if necessary, we choose to omit it in this paper, and refer to the polynomials  $R_{\lambda}(x;t)$  as the Hall-Littlewood polynomials.

**Definition 3.** A Gelfand-Tsetlin (GT) pattern is a triangular array of nonnegative integers of the form

$$a_{1,1}$$
  $a_{1,2}$   $a_{1,3}$  ...  $a_{1,n}$ 
 $a_{2,2}$   $a_{2,3}$  ...  $a_{2,n}$ 
...  $a_{2,n}$ 
...  $a_{n-1,n-1}$   $a_{n-1,n}$ 
 $a_{n,n}$ 

where each row  $r_i = (a_{i,i}, a_{i,i+1}, \dots, a_{i,n})$  is a weakly decreasing partition, and two consecutive rows  $r_i = (a_{i,i}, \dots, a_{i,n})$  and  $r_{i+1} = (a_{i+1,i+1}, \dots, a_{i+1,n})$  satisfy the interleaving condition:

$$a_{i-1,j-1} \geqslant a_{i,j} \geqslant a_{i-1,j}. \tag{7}$$

For a partition  $\alpha$ , let  $GT(\alpha)$  be the set of all GT patterns of top row  $\alpha = r_1$ . A strict GT pattern is one in which each row  $r_i$  is strictly decreasing. Given a partition  $\alpha$ , write  $SGT(\alpha) \subseteq GT(\alpha)$  to be the set of all strict GT patterns with top row  $\alpha$ .

**Definition 4** ([16]). An entry  $a_{i,j}$  in a GT pattern is

- left-leaning if  $a_{i,j} = a_{i-1,j-1}$ ,
- right-leaning if  $a_{i,j} = a_{i-1,j}$ , and
- special if it is neither left-leaning nor right-leaning.

The quantities l(T), r(T), and z(T) denote the number of left-leaning, right-leaning and special entries in a GT pattern respectively.

Given a GT pattern with n rows, define the statistic  $m_i(T)$  as

$$m_i(T) = \begin{cases} |r_i| - |r_{i+1}| & \text{for } 1 \le i \le n - 1 \\ |r_i| & \text{for } i = n \end{cases},$$
(8)

and m(T) as

$$m(T) = (m_1(T), \dots, m_n(T)).$$
 (9)

We now state the following theorem due to Tokuyama, which we generalize in the rest of this paper.

**Theorem 5** ([16]). For any weakly decreasing partition  $\lambda$  of length n, we have

$$\Delta_n(q) \cdot s_{\lambda}(x) = \sum_{T \in SGT(\lambda + \rho)} (1 - q)^{z(T)} (-q)^{l(T)} x^{m(T)}.$$
 (10)

# 3 Additional Statistics on Gelfand-Tsetlin Patterns

To generalize Theorem 5 to the Hall-Littlewood polynomials, the previous statistics from Definition 4 of [16] prove inadequate. Instead of only labelling each entry as left-leaning, right-leaning or special, we need to give each entry both a left-sided property  $p_l(a_{i,j})$  and a right-sided property  $p_r(a_{i,j})$ . The left-sided property encodes the relationship the entry  $a_{i,j}$  has to the entry directly above it and to its left, namely  $a_{i-1,j-1}$ . Similarly, the right-sided property encodes the relationship that  $a_{i,j}$  has to  $a_{i-1,j}$ .

The left-sided properties of an entry  $p_l(a_{i,j})$  are assigned as

$$p_l(a_{i,j}) = \begin{cases} l \text{ (left)} & \text{if } a_{i,j} = a_{i-1,j-1} \\ al \text{ (almost-left)} & \text{if } a_{i,j} = a_{i-1,j-1} - 1 \text{,} \\ s \text{ (special)} & \text{otherwise} \end{cases}$$

$$(11)$$

and similarly, the right-sided properties of an entry  $p_r(a_{i,j})$  are assigned as

$$p_r(a_{i,j}) = \begin{cases} r \text{ (right)} & \text{if } a_{i,j} = a_{i-1,j} \\ ar \text{ (almost-right)} & \text{if } a_{i,j} = a_{i-1,j} + 1 \end{cases}$$

$$s \text{ (special)} & \text{otherwise}$$

$$(12)$$

**Definition 6.** For an entry  $a_{i,j}$  with i > 1, we define

$$c(a_{i,j}) = \begin{cases} 0 & \text{if } p_l(a_{i,j}) = l \text{ or } p_r(a_{i,j}) = r\\ (1-t)(1-q) & otherwise \end{cases}$$
(13)

and for a property p, we define

$$g(p) = \begin{cases} -q & \text{if } p = l \\ t & \text{if } p = al \\ 1 & \text{if } p = r \\ -qt & \text{if } p = ar \\ 0 & \text{if } p = s \end{cases}$$

$$(14)$$

With these we define two more functions: the first is a generalization of the expressions (-q) and (1-q) from Tokuyama's formula; and the second considers the relation of an entry  $a_{i,j}$  to the two entries below it in the GT pattern.

**Definition 7.** For an entry  $a_{i,j}$  with i > 1, we define

$$w(a_{i,j}) = c(a_{i,j}) + g(p_l(a_{i,j})) + g(p_r(a_{i,j})).$$
(15)

For an entry  $a_{i,j}$  with i < j < n, we define

$$d(a_{i,j}) = g(p_r(a_{i+1,j})) \cdot g(p_l(a_{i+1,j+1})). \tag{16}$$

**Example 8.** Given the following segment of a GT pattern:

$$5 \quad 3 \quad 1 \\ 4 \quad 3$$

We see that the 4 has properties al and ar. Thus c(4) = (1-q)(1-t) and w(4) = (1-q)(1-t) + t - qt = 1 - q. Similarly, we have c(3) = 0 and w(3) = 0 - q + 0 = -q. For the entries in the second row, we find  $g(p_r(4)) = -qt$  and  $g(p_l(3)) = -q$ , thus the 3 in the first row gives  $d(3) = (-qt) \cdot (-q) = q^2t$ .

For the reader's convenience, we provide Table 1 which lists all possible values for  $w(a_{i,j})$  and  $d(a_{i,j})$  that we may need to consider. One may notice that we omit the case for  $w(a_{i,j})$  when  $(p_l(a_{i,j}), p_r(a_{i,j})) = (l, r)$ ; this is simply because we need not consider this case at any point in our work.

Table 1: Possible  $w(a_{i,j})$  and  $d(a_{i,j})$  values for an entry  $a_{i,j}$ .

	( <i>v</i> , <i>J</i> /
$(p_l(a_{i,j}), p_r(a_{i,j}))$	$w(a_{i,j})$
(l,s)	-q
(s,r)	1
(l, ar)	-q-qt
(al, r)	1+t
(s, ar)	1-q-t
(al,s)	1 - q + qt
(al, ar)	(1-q)
(s,s)	(1-q)(1-t)

	°,J
$p_l(a_{i+1,j+1})$	$d(a_{i,j})$
s	0
l, al	0
s	0
l	-q
l	$q^2t$
al	t
al	$-qt^2$
	$\begin{array}{c} s \\ l, al \\ s \\ l \\ al \end{array}$

Example 8 illustrates that to define  $w(a_{i,j})$  and  $d(a_{i,j})$ , we only need to know two consecutive rows of a GT pattern. This leads us to the following definition.

**Definition 9.** Suppose  $\alpha$  is a strictly decreasing partition. We define  $GT_2(\alpha)$  to be the set of all partitions  $\mu$  such that the length of  $\mu$  is one less than that of  $\alpha$ , and  $\alpha_i \geqslant \mu_i \geqslant \alpha_{i+1}$  for all i. For  $\alpha$  of length 1, we let  $GT_2(\alpha) = \{\emptyset\}$ .

This definition ensures that  $\alpha$  and  $\mu$  satisfy the interleaving condition, and so  $\mu$  would be a valid weakly decreasing row directly below a row  $\alpha$  in a GT pattern. Arranging  $\alpha$  and  $\mu$  in this manner, we are able to extend Definition 7 to parts of  $\mu$  and  $\alpha$ , and define  $w(\mu_i)$  and  $d(\alpha_i)$  for all appropriate i.

**Definition 10.** Let  $\alpha$  and  $\mu$  be partitions with  $\alpha$  strictly decreasing of length n and  $\mu \in GT_2(\alpha)$ . Then we define

$$M(\alpha; \mu) = \det \begin{bmatrix} w(\mu_1) & 1 & 0 & \dots & 0 & 0\\ d(\alpha_2) & w(\mu_2) & 1 & \dots & 0 & 0\\ 0 & d(\alpha_3) & w(\mu_3) & \dots & 0 & 0\\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots\\ 0 & 0 & 0 & \dots & w(\mu_{n-2}) & 1\\ 0 & 0 & 0 & \dots & d(\alpha_{n-1}) & w(\mu_{n-1}) \end{bmatrix}.$$
(17)

If  $\alpha$  is of length 1, and  $\mu = \emptyset \in GT_2(\alpha)$ , we define  $M(\alpha; \mu) = 1$ . We also extend this notation to any pair  $(\alpha; \mu)$  by defining  $M(\alpha; \mu) = 0$  whenever  $\mu \notin GT_2(\alpha)$ .

# 4 A Recursive Statement of Main Theorem

We first notice that Tokuyama's formula can be restated as a summation over the set  $GT_2(\alpha)$ , as shown in (18), where  $\alpha = \lambda + \rho$  for some weakly decreasing partition  $\lambda$ .

Let  $S_{\infty}$  denote the symmetric group on  $\mathbb{N}$  and take  $\zeta \in S_{\infty}$  to be the permutation which maps  $k \mapsto k+1$  for each  $k \in \mathbb{N}$ . Then Theorem 5 is equivalent to

$$\Delta_{n}(q) \cdot s_{\lambda}(x) = \sum_{\substack{\mu \in GT_{2}(\alpha) \\ \mu \text{ strict.}}} (-q)^{l(\alpha;\mu)} (1-q)^{z(\alpha;\mu)} x_{1}^{|\alpha|-|\mu|} \zeta \left(\Delta_{n-1}(q) \cdot s_{\mu-\rho}(x)\right). \tag{18}$$

Here, the function  $l(\alpha; \mu)$  is the number of 'left-leaning' parts of  $\mu$  with respect to  $\alpha$ , i.e. the number of parts  $\mu_i$  which satisfy  $\mu_i = \alpha_i$ . The function  $z(\alpha; \mu)$  is similarly defined with 'special' parts.

Re-expressing (10) recursively as (18) motivates the search for a generalization of Tokuyama's formula expressed as a summation over the set  $GT_2(\alpha)$ , as below. This theorem is equivalent to Theorem 21.

**Theorem 11.** Suppose  $\lambda$  is a weakly decreasing partition of length n, and set  $\alpha = \lambda + \rho$ . Then, using the notation defined in Section 3, we have

$$\Delta_n(q) \cdot R_{\lambda}(x;t) = \sum_{\mu \in GT_2(\alpha)} M(\alpha;\mu) x_1^{|\alpha|-|\mu|} \zeta \left( \Delta_{n-1}(q) \cdot R_{\mu-\rho}(x;t) \right). \tag{19}$$

It is worth noticing that unlike (18), this expression requires all partitions in  $GT_2(\alpha)$ , including those that are non-strict, distinguishing it from Tokuyama's formula.

Theorem 11 uses a determinant  $M(\alpha; \mu)$  to determine the coefficient of the expression  $x_1^{|\alpha|-|\mu|} \zeta(\Delta_{n-1}(q) \cdot R_{\mu-\rho}(x;t))$  in the relevant expansion of  $\Delta_n(q) \cdot R_{\lambda}(x;t)$ . We use induction on the length of  $\lambda$  and cofactor expansion of the determinant  $M(\alpha;\mu)$  to prove Theorem 11. We omit the computations of the base cases in which  $\lambda$  has length 1 or 2, which are easy to verify.

We move on to the general case of some weakly decreasing partition  $\lambda$  of length n > 2. For the remainder of this proof, we fix some general notation for partitions. Firstly, the partition  $\lambda$  and its length n are now fixed, and in any new notation to follow, these will remain independent of the variables in the expression. We consequently fix the partition  $\alpha = \lambda + \rho$ , also of length n. When referring to an arbitrary partition, we use  $\kappa$  of length m. Finally, the partition  $\mu$  will consistently be used as an arbitrary element of some set of the form  $GT_2(\kappa)$ .

Given a partition  $\kappa = (\kappa_1, \dots, \kappa_m)$ , we will write

$$\kappa_{\widehat{1}} = (\kappa_2, \dots, \kappa_m) \text{ and } \kappa_{\widehat{1},\widehat{2}} = (\kappa_3, \dots, \kappa_m).$$
(20)

Also, we define

$$\delta_i(x_l;t) := \prod_{\substack{1 \leqslant a \leqslant n \\ a \neq i}} x_l - tx_a,\tag{21}$$

and similarly

$$\delta_{i,j}(x_l;t) := \prod_{\substack{1 \le a \le n \\ a \ne i,j}} x_l - tx_a, \quad \text{and} \quad \delta_{i,j,k}(x_l;t) := \prod_{\substack{1 \le a \le n \\ a \ne i,j,k}} x_l - tx_a.$$
 (22)

As with  $\Delta_n$ , we define  $\delta_i(x_l) = \delta_i(x_l; 1)$  and similarly  $\delta_{i,j}(x_l) = \delta_{i,j}(x_l; 1)$  and  $\delta_{i,j,k}(x_l) = \delta_{i,j,k}(x_l; 1)$ .

Our inductive hypotheses will be

$$R_{\lambda_{\widehat{1}}}(x;t) \cdot \delta_{1,n}(x_1;q) = \sum_{\mu \in GT_2(\alpha_{\widehat{1}})} M(\alpha_{\widehat{1}};\mu) x_1^{|\alpha_{\widehat{1}}| - |\mu|} \zeta\left(R_{\mu-\rho}(x;t)\right), \tag{23}$$

and

$$R_{\lambda_{\widehat{1},\widehat{2}}}(x;t) \cdot \delta_{1,n-1,n}(x_1;q) = \sum_{\mu \in GT_2(\alpha_{\widehat{1},\widehat{2}})} M(\alpha_{\widehat{1},\widehat{2}};\mu) x_1^{|\alpha_{\widehat{1},\widehat{2}}|-|\mu|} \zeta(R_{\mu-\rho}(x;t)).$$
 (24)

Note that multiplying both sides of (23) by  $\zeta(\Delta_{n-1}(q))$  and (24) by  $\zeta_{1,2}(\Delta_{n-2}(q))$  gives the form seen in Theorem 11.

Prior to the proof, we require another operator: We generalize the notion of  $\zeta$  to  $\zeta_i \in S_{\infty}$  which is defined to take  $k \mapsto k+1$  for each  $k \in \mathbb{N}$  with  $k \geqslant i$ . Furthermore, we also define  $\zeta_{i,j} = \zeta_{j,i} = \zeta_j \zeta_i \in S_{\infty}$  when i < j. We notice that these operators act on a polynomial  $f(x) = f(x_1, \ldots, x_m)$  to obtain

$$\zeta_i(f(x)) = f(x_1, \dots, x_{i-1}, x_{i+1}, \dots, x_{m+1}), \tag{25}$$

and

$$\zeta_{i,j}(f(x)) = \zeta_{j,i}(f(x)) = f(x_1, \dots x_{i-1}, x_{i+1}, \dots x_{j-1}, x_{j+1}, \dots, x_{m+2}). \tag{26}$$

Notice that  $\zeta_1 = \zeta$ , and we shall use the latter in the proof to follow.

We begin with a series of lemmas.

**Lemma 12.** For an arbitrary partition  $\kappa$  of length m > 2, we express  $R_{\kappa}(x;t)$  recursively as

$$R_{\kappa}(x;t) = \sum_{1 \le i \le m} x_i^{\kappa_1} \left( \frac{\delta_i(x_i;t)}{\delta_i(x_i)} \right) \zeta_i \left( R_{\kappa_{\widehat{1}}}(x;t) \right), \tag{27}$$

and

$$R_{\kappa}(x;t) = \sum_{1 \leqslant i \leqslant m} \sum_{\substack{1 \leqslant j \leqslant m \\ j \neq i}} x_i^{\kappa_1} x_j^{\kappa_2} \left( \frac{\delta_i(x_i;t)}{\delta_i(x_i)} \frac{\delta_{i,j}(x_j;t)}{\delta_{i,j}(x_j)} \right) \zeta_{i,j} \left( R_{\kappa_{\widehat{1},\widehat{2}}}(x;t) \right). \tag{28}$$

*Proof.* Let the permutation  $\psi_i = (i \ i-1 \ \cdots \ 1)$ , and let H be the symmetric group acting on the (n-1) indices  $(2,3,\ldots,n)$ . Then

$$R_{\kappa}(x;t) = \sum_{1 \leqslant i \leqslant m} \sum_{\sigma \in H} \psi_i \ \sigma\left(\frac{x^{\kappa} \Delta_m(t)}{\Delta_m}\right) = \sum_{1 \leqslant i \leqslant m} \sum_{\sigma \in H} \psi_i \ \sigma\left(x_1^{\kappa_1} \frac{\delta_1(x_1;t)}{\delta_1(x_1)} \ \zeta\left(\frac{x^{\kappa_1} \Delta_{m-1}(t)}{\Delta_{m-1}}\right)\right).$$

Because  $\sigma \in H$  does not permute  $x_1$ , we have

$$R_{\kappa}(x;t) = \sum_{1 \leqslant i \leqslant m} \psi_i \left( x_1^{\kappa_1} \frac{\delta_1(x_1;t)}{\delta_1(x_1)} \zeta \left( R_{\kappa_{\widehat{1}}}(x;t) \right) \right) = \sum_{1 \leqslant i \leqslant m} x_i^{\kappa_1} \left( \frac{\delta_i(x_i;t)}{\delta_i(x_i)} \right) \zeta_i \left( R_{\kappa_{\widehat{1}}}(x;t) \right).$$

We further obtain (28) by applying (27) to the  $R_{\kappa_{\widehat{1}}}(x;t)$  in (27).

**Lemma 13.** Let  $O_i = ((x_i - tx_1)x_i^{\lambda_1} - (x_1 - tx_i)x_1^{\lambda_1 - \lambda_2}x_i^{\lambda_2})/(x_i - tx_1)$ . Then we have

$$R_{\lambda}(x;t) = \sum_{2 \leqslant i \leqslant n} O_{i} \left( \frac{\delta_{i}(x_{i};t)}{\delta_{i}(x_{i})} \right) \zeta_{i} \left( R_{\lambda_{\widehat{1}}}(x;t) \right)$$

$$- x_{1}^{\lambda_{1}-\lambda_{2}} \sum_{2 \leqslant i \leqslant n} \sum_{\substack{2 \leqslant j \leqslant n \\ j \neq i}} t x_{i}^{\lambda_{2}} x_{j}^{\lambda_{2}} \frac{\delta_{1,i}(x_{i};t)}{\delta_{1,i}(x_{i})} \frac{\delta_{1,i,j}(x_{j};t)}{\delta_{1,i,j}(x_{j})} \zeta_{i,j} \left( R_{\lambda_{\widehat{1},\widehat{2}}}(x;t) \right). \quad (29)$$

*Proof.* We begin by observing that

$$0 = \sum_{2 \le i \le n} \sum_{2 \le j \le n} (-1)^{i+j} x_i^{\lambda_2} x_j^{\lambda_2} (x_i - x_j) \zeta_{i,j} \left( \Delta_{n-2} \cdot R_{\lambda_{\widehat{1},\widehat{2}}} (x;t) \right) \delta_{1,i}(x_i;t) \delta_{1,j}(x_j;t).$$

This can easily be seen by swapping the subscripts i and j in the right hand side, revealing RHS = -RHS.

We divide through the equality above by  $\Delta_n$ , altering the products and the bounds of the summation, and multiply by  $x_1(1-t)$  to find

$$0 = \sum_{2 \le i \le n} \sum_{\substack{2 \le j \le n \\ j \ne i}} \frac{x_1(1-t)(x_j-tx_i)x_i^{\lambda_2}x_j^{\lambda_2}}{(x_j-x_1)(x_i-tx_1)} \zeta_{i,j}(R_{\lambda_{\widehat{1},\widehat{2}}}(x;t)) \frac{\delta_i(x_i;t)}{\delta_i(x_i)} \frac{\delta_{1,i,j}(x_j;t)}{\delta_{1,i,j}(x_j)}.$$

Using the identity

$$\frac{x_1(1-t)(x_j-tx_i)}{(x_j-x_1)(x_i-tx_1)} = \frac{(x_1-tx_i)(x_j-tx_1)}{(x_i-tx_1)(x_j-x_1)} + t\frac{x_i-x_1}{x_i-tx_1},$$

we break the double summation into two parts; in particular, if we take

$$L = \sum_{2 \leqslant i \leqslant n} \sum_{\substack{2 \leqslant j \leqslant n \\ j \neq i}} t x_i^{\lambda_2} x_j^{\lambda_2} \frac{\delta_{1,i}(x_i;t)}{\delta_{1,i}(x_i)} \frac{\delta_{1,i,j}(x_j;t)}{\delta_{1,i,j}(x_j)} \zeta_{i,j} \left( R_{\lambda_{\widehat{1},\widehat{2}}}(x;t) \right), \tag{30}$$

then

$$0 = L + \sum_{2 \le i \le n} \sum_{\substack{2 \le j \le n \\ i \ne i}} \frac{(x_1 - tx_i)x_i^{\lambda_2}x_j^{\lambda_2}}{(x_i - tx_1)} \zeta_{i,j}(R_{\lambda_{\widehat{1},\widehat{2}}}(x;t)) \frac{\delta_i(x_i;t)}{\delta_i(x_i)} \frac{\delta_{i,j}(x_j;t)}{\delta_{i,j}(x_j)}.$$
 (31)

Now, one can see that

$$-x_{1}^{\lambda_{2}} \frac{\delta_{1}(x_{1};t)}{\delta_{1}(x_{1})} \zeta\left(R_{\lambda_{\widehat{1}}}(x;t)\right)$$

$$= x_{1}^{\lambda_{2}} \sum_{2 \leq i \leq n} \frac{\delta_{i}(x_{i};t)}{\delta_{i}(x_{i})} \frac{\delta_{1,i}(x_{1};t)}{\delta_{1,i}(x_{1})} \frac{(x_{1} - tx_{i})x_{i}^{\lambda_{2}}}{(x_{i} - tx_{1})} \zeta_{1,i} \left(R_{\lambda_{\widehat{1},\widehat{2}}}(x;t)\right) \quad (32)$$

holds by expressing  $R_{\lambda_{\hat{1}}}(x;t)$  of the left hand side explicitly using (27) and rearranging the result.

We notice that the right hand side of (32) is equivalent to setting j = 1 in the double summation of (31). Thus, adding either side of (32) to either side of (31) respectively, we have

$$-x_{1}^{\lambda_{2}} \frac{\delta_{1}(x_{1};t)}{\delta_{1}(x_{1})} \zeta\left(R_{\lambda_{\widehat{1}}}(x;t)\right)$$

$$= L + \sum_{\substack{2 \leqslant i \leqslant n}} \sum_{\substack{1 \leqslant j \leqslant n \\ j \neq i}} \frac{(x_{1} - tx_{i})x_{i}^{\lambda_{2}}x_{j}^{\lambda_{2}}}{(x_{i} - tx_{1})} \zeta_{i,j}(R_{\lambda_{\widehat{1},\widehat{2}}}(x;t)) \frac{\delta_{i}(x_{i};t)}{\delta_{i}(x_{i})} \frac{\delta_{i,j}(x_{j};t)}{\delta_{i,j}(x_{j})}.$$

Multiplying through by  $-x_1^{\lambda_1-\lambda_2}$ , and adding

$$\sum_{2 \leqslant i \leqslant n} x_i^{\lambda_1} \frac{\delta_{i,j}(x_j;t)}{\delta_{i,j}(x_j)} \zeta_i(R_{\lambda_{\widehat{1}}}(x;t)),$$

to both sides, we may apply (27) once on either side of the equality to obtain

$$R_{\lambda}(x;t) = -x_1^{\lambda_1 - \lambda_2} L + \sum_{2 \le i \le n} \left( \frac{\delta_i(x_i;t)}{\delta_i(x_i)} \right) \left( x_i^{\lambda_1} - x_1^{\lambda_1 - \lambda_2} x_i^{\lambda_2} \frac{x_1 - tx_i}{x_i - tx_1} \right) \zeta_i(R_{\lambda_{\widehat{1}}}(x;t)).$$

Recalling  $O_i$  as

$$O_i = \frac{(x_i - tx_1)x_i^{\lambda_1} - (x_1 - tx_i)x_1^{\lambda_1 - \lambda_2}x_i^{\lambda_2}}{x_i - tx_1} = x_i^{\lambda_1} - x_1^{\lambda_1 - \lambda_2}x_i^{\lambda_2}\frac{x_1 - tx_i}{x_i - tx_1},$$

we combine the two summations on the right hand side and recall L from (30) to write

$$R_{\lambda}(x;t) = \sum_{2 \leqslant i \leqslant n} O_{i} \left( \frac{\delta_{i}(x_{i};t)}{\delta_{i}(x_{i})} \right) \zeta_{i} \left( R_{\lambda_{\widehat{1}}}(x;t) \right)$$

$$- x_{1}^{\lambda_{1}-\lambda_{2}} \sum_{2 \leqslant i \leqslant n} \sum_{\substack{2 \leqslant j \leqslant n \\ j \neq i}} t x_{i}^{\lambda_{2}} x_{j}^{\lambda_{2}} \frac{\delta_{1,i}(x_{i};t)}{\delta_{1,i}(x_{i})} \frac{\delta_{1,i,j}(x_{j};t)}{\delta_{1,i,j}(x_{j})} \zeta_{i,j} \left( R_{\lambda_{\widehat{1},\widehat{2}}}(x;t) \right). \quad \Box$$

We introduce two related functions that will be used in the upcoming lemmas. For some non-negative integers u and v, we define

$$F_{\lambda_{\widehat{1}}}(u) := \sum_{\mu \in GT_2(\alpha_{\widehat{1}})} M(\alpha_{\widehat{1}}; \mu) x_1^{|\alpha_{\widehat{1}}| - |\mu|} \zeta\left(R_{(u)||\mu - \rho}(x; t)\right), \tag{33}$$

and

$$F_{\lambda_{\widehat{1},\widehat{2}}}(u,v) := \sum_{\mu \in GT_2(\alpha_{\widehat{1},\widehat{2}})} M(\alpha_{\widehat{1},\widehat{2}};\mu) x_1^{|\alpha_{\widehat{1},\widehat{2}}|-|\mu|} \zeta\left(R_{(u,v)||\mu-\rho}(x;t)\right). \tag{34}$$

**Lemma 14.** Suppose u and v are some non-negative integers. Then, assuming the inductive hypotheses in (23) and (24), we have

$$F_{\lambda_{\hat{1}}}(u) = \sum_{2 \le i \le n} x_i^u \frac{\delta_{1,i}(x_i;t)}{\delta_{1,i}(x_i)} \zeta_i \left( R_{\lambda_{\hat{1}}}(x;t) \right) \delta_{1,i}(x_1;q), \tag{35}$$

and

$$F_{\lambda_{\hat{1},\hat{2}}}(u,v) = \sum_{2 \leqslant i \leqslant n} \sum_{\substack{2 \leqslant j \leqslant n \\ i \neq i}} x_i^u x_j^v \frac{\delta_{1,i}(x_i;t)}{\delta_{1,i}(x_i)} \frac{\delta_{1,i,j}(x_j;t)}{\delta_{1,i,j}(x_j)} \zeta_{i,j} \left( R_{\lambda_{\hat{1},\hat{2}}}(x;t) \right) \delta_{1,i,j}(x_1;q). \tag{36}$$

*Proof.* The proof of (36) is almost identical to that of (35), apart from using (28) and (24) in place of (27) and (23). For brevity, we only present the detailed proof of (35).

By applying (27) to write  $R_{(u)\parallel(\mu-\rho)}(x;t)$  in terms of u and  $R_{\mu-\rho}(x;t)$ , the left hand side of (35) becomes

$$\sum_{\mu \in GT_2(\alpha_{\widehat{1}})} M(\alpha_{\widehat{1}}; \mu) x_1^{|\alpha_{\widehat{1}}| - |\mu|} \zeta \left( \sum_{1 \leqslant i \leqslant n-1} x_i^u \frac{\delta_{i,n}(x_i; t)}{\delta_{i,n}(x_i)} \zeta_i \left( R_{\mu-\rho}(x; t) \right) \right).$$

We rearrange this expression to write this as

$$\sum_{2 \leqslant i \leqslant n} x_i^u \frac{\delta_{1,i}(x_i;t)}{\delta_{1,i}(x_i)} \zeta_i \left( \sum_{\mu \in GT_2(\alpha_{\widehat{1}})} M(\alpha_{\widehat{1}};\mu) x_1^{|\alpha_{\widehat{1}}|-|\mu|} \zeta\left(R_{\mu-\rho}(x;t)\right) \right).$$

Finally, we replace the argument of  $\zeta_i$  using the inductive hypothesis in (23) to give the desired result.

**Lemma 15.** Recall  $O_i = ((x_i - tx_1)x_i^{\lambda_1} - (x_1 - tx_i)x_1^{\lambda_1 - \lambda_2}x_i^{\lambda_2})/(x_i - tx_1)$  from Lemma 13. Then we have

$$\sum_{\mu \in GT_2(\alpha)} w(\mu_1) M(\alpha_{\widehat{1}}; \mu_{\widehat{1}}) x_1^{|\alpha| - |\mu|} \zeta(R_{\mu - \rho}(x; t))$$

$$= \sum_{2 \le i \le n} O_i \left( \frac{\delta_i(x_i; t)}{\delta_i(x_i)} \right) \zeta_i \left( R_{\lambda_{\widehat{1}}}(x; t) \right) \delta_1(x_1; q). \quad (37)$$

*Proof.* First, notice that  $(x_i - tx_1)O_i/(x_i - x_1) = Q_i/(x_1 - qx_i)$ , where

$$Q_{i} = -qx_{i}^{\lambda_{1}+1} + tx_{1}x_{i}^{\lambda_{1}} - qtx_{1}^{\lambda_{1}-\lambda_{2}}x_{i}^{\lambda_{2}+1} + x_{1}^{\lambda_{1}-\lambda_{2}+1}x_{i}^{\lambda_{2}} + \sum_{\lambda_{2} < i \leq \lambda_{1}} (1-q)(1-t)x_{1}^{\lambda_{1}+1-i}x_{i}^{i}.$$

This can be shown through simple algebraic manipulation, considering three cases for  $\lambda$ , namely (1):  $\lambda_1 = \lambda_2$ , (2):  $\lambda_1 = 1 + \lambda_2$  and (3):  $\lambda_1 > 1 + \lambda_2$ .

Substituting the above identity in the right hand side of the lemma gives

RHS = 
$$\sum_{2 \le i \le n} \frac{\delta_{1,i}(x_i;t)}{\delta_{1,i}(x_i)} \zeta_i \left( R_{\lambda_{\widehat{1}}}(x;t) \right) Q_i \ \delta_{1,i}(x_1;q).$$

Then, expanding  $Q_i$  and applying (35), we have

RHS = 
$$-q \cdot F_{\lambda_{\hat{1}}}(\lambda_{1}+1) + tx_{1} \cdot F_{\lambda_{\hat{1}}}(\lambda_{1}) - qtx_{1}^{\lambda_{1}-\lambda_{2}} \cdot F_{\lambda_{\hat{1}}}(\lambda_{2}+1)$$
  
  $+ x_{1}^{\lambda_{1}-\lambda_{2}+1} \cdot F_{\lambda_{\hat{1}}}(\lambda_{2}) + \sum_{\lambda_{2} < i \leq \lambda_{1}} (1-q)(1-t)x_{1}^{\lambda_{1}+1-i} \cdot F_{\lambda_{\hat{1}}}(i).$ 

Examining Definition 6, we see that the first two coefficients above are precisely the nonzero possibilities of  $g(p_l(\mu_1))$ ; the next two are precisely the nonzero possibilities of  $g(p_r(\mu_1))$ ; and the final summation is over all the nonzero possibilities of  $c(\mu_1)$ . Recalling from Definition 7 that  $w(\mu_1) = c(\mu_1) + g(p_l(\mu_1)) + g(p_r(\mu_1))$ , we simply have

RHS = 
$$\sum_{\mu \in GT_2(\alpha)} w(\mu_1) M(\alpha_{\widehat{1}}; \mu_{\widehat{1}}) x_1^{|\alpha|-|\mu|} \zeta(R_{\mu-\rho}(x;t)). \qquad \Box$$

Lemma 16. We have

$$\sum_{\mu \in GT_{2}(\alpha)} d(\alpha_{2}) M(\alpha_{\widehat{1},\widehat{2}}; \mu_{\widehat{1},\widehat{2}}) x_{1}^{|\alpha|-|\mu|} \zeta(R_{\mu-\rho}(x;t))$$

$$= x_{1}^{\lambda_{1}-\lambda_{2}} \sum_{2 \leq i \leq n} \sum_{\substack{2 \leq j \leq n \\ i \neq i}} t x_{i}^{\lambda_{2}} x_{j}^{\lambda_{2}} \frac{\delta_{1,i}(x_{i};t)}{\delta_{1,i}(x_{i})} \frac{\delta_{1,i,j}(x_{j};t)}{\delta_{1,i,j}(x_{j})} \zeta_{i,j} \left(R_{\lambda_{\widehat{1},\widehat{2}}}(x;t)\right) \delta_{1}(x_{1};q). \tag{38}$$

*Proof.* Expanding the factor  $(x_1 - qx_i)(x_1 - qx_j)$  from the product  $\delta_1(x_1; q)$ , the right hand side of the above equality becomes

$$\sum_{\substack{2\leqslant i\leqslant n\\j\neq i}}\sum_{\substack{2\leqslant j\leqslant n\\j\neq i}}tx_1^{\lambda_1-\lambda_2}x_i^{\lambda_2}x_j^{\lambda_2}(x_1-qx_i)(x_1-qx_j)\frac{\delta_{1,i}(x_i;t)}{\delta_{1,i}(x_i)}\frac{\delta_{1,i,j}(x_j;t)}{\delta_{1,i,j}(x_j)}\zeta_{i,j}\left(R_{\lambda_{\widehat{1},\widehat{2}}}(x;t)\right)\delta_{1,i,j}(x_1;q).$$

We see from Proposition 20 that  $F_{\lambda_{\hat{1},\hat{2}}}(\lambda_2,\lambda_2+1) = t \cdot F_{\lambda_{\hat{1},\hat{2}}}(\lambda_2+1,\lambda_2)$ . Then distributing  $(q^2x_ix_j - qx_1x_i - qx_1x_j + x_1^2)$  over the summation and applying (36) yields

$$RHS = q^{2} t x_{1}^{\lambda_{1} - \lambda_{2}} \cdot F_{\lambda_{\hat{1},\hat{2}}}(\lambda_{2} + 1, \lambda_{2} + 1) - q x_{1}^{\lambda_{1} - \lambda_{2} + 1} \cdot F_{\lambda_{\hat{1},\hat{2}}}(\lambda_{2}, \lambda_{2} + 1) - q t^{2} x_{1}^{\lambda_{1} - \lambda_{2} + 1} \cdot F_{\lambda_{\hat{1},\hat{2}}}(\lambda_{2} + 1, \lambda_{2}) + t x_{1}^{\lambda_{1} - \lambda_{2} + 2} \cdot F_{\lambda_{\hat{1},\hat{2}}}(\lambda_{2}, \lambda_{2}, \mu - \rho).$$

Recalling from Definition 6 that  $d(\alpha_2) = g(p_r(\mu_1)) \cdot g(p_l(\mu_2))$ , we notice that each of the four coefficients in the previous expression corresponds exactly to each of the four possible nonzero values for  $d(\alpha_2)$ . Thus, we have

RHS = 
$$\sum_{\mu \in GT_2(\alpha)} d(\alpha_2) M(\alpha_{\widehat{1},\widehat{2}}; \mu_{\widehat{1},\widehat{2}}) x_1^{|\alpha|-|\mu|} \zeta(R_{\mu-\rho}(x;t)). \qquad \Box$$

We return to the proof of Theorem 11.

*Proof.* Lemma 13 gave us that

$$R_{\lambda}(x;t) = \sum_{2 \leqslant i \leqslant n} O_i \left( \frac{\delta_i(x_i;t)}{\delta_i(x_i)} \right) \zeta_i \left( R_{\lambda_{\widehat{1}}}(x;t) \right)$$

$$- x_1^{\lambda_1 - \lambda_2} \sum_{2 \leqslant i \leqslant n} \sum_{\substack{2 \leqslant j \leqslant n \\ j \neq i}} t x_i^{\lambda_2} x_j^{\lambda_2} \frac{\delta_{1,i}(x_i;t)}{\delta_{1,i}(x_i)} \frac{\delta_{1,i,j}(x_j;t)}{\delta_{1,i,j}(x_j)} \zeta_{i,j} \left( R_{\lambda_{\widehat{1},\widehat{2}}}(x;t) \right).$$

Furthermore, assuming the inductive hypotheses (23) and (24), Lemmas 15 and 16 state that

$$\sum_{\mu \in GT_2(\alpha)} w(\mu_1) M(\alpha_{\widehat{1}}; \mu_{\widehat{1}}) x_1^{|\alpha| - |\mu|} \zeta\left(R_{\mu - \rho}(x; t)\right) = \sum_{2 \leqslant i \leqslant n} O_i\left(\frac{\delta_i(x_i; t)}{\delta_i(x_i)}\right) \zeta_i\left(R_{\lambda_{\widehat{1}}}(x; t)\right) \delta_1(x_1; q).$$

and

$$\sum_{\mu \in GT_{2}(\alpha)} d(\alpha_{2}) M(\alpha_{\widehat{1},\widehat{2}}; \mu_{\widehat{1},\widehat{2}}) x_{1}^{|\alpha|-|\mu|} \zeta(R_{\mu-\rho}(x;t))$$

$$= x_{1}^{\lambda_{1}-\lambda_{2}} \sum_{\substack{2 \leqslant i \leqslant n \\ j \neq i}} \sum_{\substack{2 \leqslant j \leqslant n \\ j \neq i}} t x_{i}^{\lambda_{2}} x_{j}^{\lambda_{2}} \frac{\delta_{1,i}(x_{i};t)}{\delta_{1,i}(x_{i})} \frac{\delta_{1,i,j}(x_{j};t)}{\delta_{1,i,j}(x_{j})} \zeta_{i,j} \left(R_{\lambda_{\widehat{1},\widehat{2}}}(x;t)\right) \delta_{1}(x_{1};q).$$

Hence, it is clear that

$$\begin{split} \delta_{1}(x_{1};q) \cdot R_{\lambda}(x;t) &= \sum_{\mu \in GT_{2}(\alpha)} w(\mu_{1}) M(\alpha_{\widehat{1}};\mu_{\widehat{1}}) x_{1}^{|\alpha|-|\mu|} \zeta(R_{\mu-\rho}(x;t)) \\ &- \sum_{\mu \in GT_{2}(\alpha)} d(\alpha_{2}) M(\alpha_{\widehat{1},\widehat{2}};\mu_{\widehat{1},\widehat{2}}) x_{1}^{|\alpha|-|\mu|} \zeta(R_{\mu-\rho}(x;t)). \end{split}$$

Finally, cofactor expansion gives us  $M(\alpha; \mu) = w(\mu_1)M(\alpha_{\widehat{1}}; \mu_{\widehat{1}}) - d(\alpha_2)M(\alpha_{\widehat{1},\widehat{2}}; \mu_{\widehat{1},\widehat{2}})$  and observing that  $\Delta_n(q) = \delta_1(x_1; q) \cdot \zeta(\Delta_{n-1}(q))$ , we multiply by  $\zeta(\Delta_{n-1}(q))$  to conclude

$$\Delta_n(q) \cdot R_{\lambda}(x;t) = \sum_{\mu \in GT_2(\alpha)} M(\alpha;\mu) x_1^{|\alpha|-|\mu|} \zeta(\Delta_{n-1}(q) \cdot R_{\mu-\rho}(x;t)). \qquad \Box$$

# 5 Weakly Decreasing Partitions and Raising Operators

Theorem 11 expresses the Hall-Littlewood polynomial recursively in terms of Hall-Littlewood polynomials in one fewer variables. The partitions  $\mu \in GT_2(\alpha)$  indexing these polynomials are guaranteed to be weakly decreasing by the interleaving condition, but they are not necessarily strictly decreasing.

To express  $\mu \in GT_2(\alpha)$  in terms of strictly decreasing partitions, we relate the Hall-Littlewood polynomial associated to a weakly decreasing partition to one associated to a specific strictly decreasing partition, which is related to the weakly decreasing partition through a specified sequence of Young's raising operators.

**Definition 17.** A raising operator  $\phi$  is a product of operations  $[i \ j]$  with  $i \leq j$  acting on some finite tuple  $\lambda$  of nonnegative integers such that

$$[i \ j] \cdot (\lambda_1, \dots, \lambda_n) = (\lambda_1, \dots, \lambda_i - 1, \dots, \lambda_j + 1, \dots, \lambda_n). \tag{39}$$

(Note that these are the inverses of Young's raising operators as defined in [10, Chapter I].)

The length of a raising operator  $\phi$ , denoted  $l(\phi)$ , is defined as the number of operators in the minimal decomposition of  $\phi$  into elementary operators of the form  $[i \ i+1]$ . The identity raising operator Id acts trivially on the partition and is assigned length zero.

**Definition 18.** Given a strictly decreasing partition  $\alpha$  of length n, we recursively define  $\Omega(\alpha)$  to be the set of raising operators such that

- The identity raising operator Id  $\in \Omega(\alpha)$ , and
- for all raising operators  $\phi \in \Omega(\alpha)$ , if the tuple  $\phi(\alpha) = (\alpha'_1, \dots, \alpha'_n)$  contains consecutive parts  $\alpha'_i$  and  $\alpha'_{i+1}$  such that  $\alpha'_i = \alpha'_{i+1} + 2$ , then  $[i \ i+1] \cdot \phi \in \Omega(\alpha)$ .

**Example 19.** For the partition  $\alpha = (6, 4, 3, 1)$ , we have the set

$$\Omega(\alpha) = \{ \text{Id}, [1\ 2], [1\ 3], [2\ 4], [3\ 4], [1\ 2], [3\ 4] \}.$$

**Proposition 20.** Suppose  $\lambda$  is some weakly decreasing partition and  $\alpha = \lambda + \rho$ . Then, for each  $\phi \in \Omega(\alpha)$ , the following identity holds:

$$R_{\phi(\lambda)}(x;t) = t^{l(\phi)} \cdot R_{\lambda}(x;t). \tag{40}$$

*Proof.* It is clear that (40) holds for  $\phi = \text{Id}$ . Therefore, by the recursive definition of  $\Omega$ , it suffices to prove that for an arbitrary tuple  $\lambda = (\lambda_1, \dots, \lambda_n)$  and  $\alpha = \lambda + \rho$  such that  $\alpha_i = \alpha_{i+1} + 2$ , or equivalently  $\lambda_i = \lambda_{i+1} + 1$ , we have

$$R_{[i\ i+1](\lambda)}(x;t) = t \cdot R_{\lambda}(x;t). \tag{41}$$

To prove (41), let  $g(x) = \Delta_n(t)/(x_i - tx_{i+1})$  and  $f(x) = x_1^{\lambda_1} \cdots x_{i-1}^{\lambda_{i-1}} \cdot x_{i+2}^{\lambda_{i+2}} \cdots x_n^{\lambda_n}$ , noting that both g(x) and f(x) are invariant under the permutation  $(i \ i + 1)$ . Then, if we take  $\lambda_{i+1} = a$  and  $\lambda_i = a + 1$  for some integer a, and let  $\operatorname{sgn} \sigma$  be the standard  $\operatorname{sign}$  function for a permutation  $\sigma \in S_n$ , we see that

$$\sum_{\sigma \in S_n} \left( \operatorname{sgn} \, \sigma \right) \sigma \left( x^{\lambda} \Delta_n(t) \right) = \sum_{\sigma \in S_n} \left( \operatorname{sgn} \, \sigma \right) \sigma \left( f(x) g(x) x_i^{a+2} x_{i+1}^a - t f(x) g(x) x_i^{a+1} x_{i+1}^{a+1} \right).$$

If some polynomial  $h(x) = (i \ j)(h(x))$  for  $(i \ j) \in S_n$ , then  $\sum_{\sigma \in S_n} (\operatorname{sgn} \sigma) \sigma (h(x)) = 0$ . Therefore, since  $tf(x)g(x)x_i^{a+1}x_{i+1}^{a+1}$  is invariant under the permutation  $(i \ i+1)$ , we have

$$\sum_{\sigma \in S_n} (\operatorname{sgn} \sigma) \sigma \left( x^{\lambda} \Delta_n(t) \right) = \sum_{\sigma \in S_n} (\operatorname{sgn} \sigma) \sigma \left( f(x) g(x) x_i^{a+2} x_{i+1}^a \right). \tag{42}$$

Similarly, we can find that

$$\sum_{\sigma \in S_n} (\operatorname{sgn} \sigma) \sigma \left( x^{[i \ i+1](\lambda)} \Delta_n(t) \right) = (-t) \cdot \sum_{\sigma \in S_n} (\operatorname{sgn} \sigma) \sigma \left( f(x) g(x) x_i^a x_{i+1}^{a+2} \right)$$

$$= t \cdot \sum_{\sigma \in S} (\operatorname{sgn} \sigma) \sigma \left( f(x) g(x) x_i^{a+2} x_{i+1}^a \right), \tag{43}$$

and combining (42) and (43) returns

$$\sum_{\sigma \in S_n} (\operatorname{sgn} \, \sigma) \, \sigma \left( x^{[i \, i+1](\lambda)} \Delta_n(t) \right) = t \cdot \sum_{\sigma \in S_n} (\operatorname{sgn} \, \sigma) \, \sigma \left( x^{\lambda} \Delta_n(t) \right).$$

Dividing through by  $\Delta_n$  gives us (41), as desired.

#### A Deformation of Tokuyama's Formula 6

By enabling us to express Hall-Littlewood polynomials  $R_{\mu-\rho}(x;t)$  with nonstrict  $\mu$  in terms of those with strict  $\mu$ , Proposition 20 allows us state Theorem 11 non-recursively as Theorem 21, providing a deformation of Tokuyama's formula.

**Theorem 21.** Suppose  $\lambda$  is a weakly decreasing partition of length n. Then, the product  $\Delta_n(q) \cdot R_{\lambda}(x;t)$  of the deformed Weyl denominator and the Hall-Littlewood polynomial can be expressed as a summation over the set  $SGT(\lambda + \rho)$  of all strict Gelfand-Tsetlin patterns of top row  $\lambda + \rho$  by

$$\Delta_n(q) \cdot R_{\lambda}(x;t) = \sum_{T \in SGT(\lambda + \rho)} \prod_{i=1}^{n-1} \left( \sum_{\phi \in \Omega(r_{i+1})} t^{l(\phi)} M(r_i; \phi(r_{i+1})) \right) x^{m(T)}. \tag{44}$$

Here, the determinant  $M(r_i; \phi(r_{i+1}))$  and the set  $\Omega(r_{i+1})$  are defined in Definitions 10 and 18 respectively.

*Proof.* We use induction, where our inductive hypothesis is that (44) holds for all Hall-Littlewood polynomials in (n-1) variables. The base case formula of one variable is easy to check.

We now prove that (44) holds for a Hall-Littlewood polynomial corresponding to an arbitrary weakly decreasing partition  $\lambda$  of length n>1, assuming the inductive hypothesis. Let  $\alpha = \lambda + \rho$ . We notice that, while  $\alpha$  must be strictly decreasing, a partition  $\mu \in GT_2(\alpha)$  may be weakly decreasing. If  $\mu$  is not strictly decreasing, the computed Hall-Littlewood polynomial  $R_{\mu-\rho}(x;t)$  has an increasing partition  $\mu-\rho$ . Proposition 20 allows us to express these Hall-Littlewood polynomials in terms of some Hall-Littlewood polynomials that are obtained from strictly decreasing  $\tilde{\mu} \in GT_2(\alpha)$ . In particular, for each non-strict  $\mu \in GT_2(\alpha)$ , there exists a unique strict  $\tilde{\mu} \in GT_2(\alpha)$  and a unique element  $\phi \in \Omega(\tilde{\mu})$  such that  $\phi(\tilde{\mu}) = \mu$ . Furthermore, for each  $\phi \in \Omega(\tilde{\mu})$ , the tuple  $\phi(\tilde{\mu})$  will either be a valid element of  $GT_2(\alpha)$  or will cause  $M(\alpha; \phi(\tilde{\mu})) = 0$  and can be neglected. Hence,

we may rewrite (19) of Theorem 11 as an equivalent summation over strictly decreasing partitions in the set  $GT_2(\alpha)$ :

$$R_{\lambda}(x;t) \cdot \Delta_{n}(q) = \sum_{\substack{\mu \in GT_{2}(\alpha) \\ \mu \text{ strict}}} \sum_{\phi \in \Omega(\mu)} t^{l(\phi)} M(\alpha;\phi(\mu)) x_{1}^{|\alpha|-|\mu|} \zeta(\Delta_{n-1}(q) \cdot R_{\mu-\rho}(x;t)). \tag{45}$$

By applying the inductive hypothesis to the Hall-Littlewood polynomials  $R_{\mu-\rho}(x;t)$  of (n-1) variables in (45), we are reduced to (44).

**Example 22.** We present an example of Theorem 21 by computing the term obtained from a particular GT pattern. We take  $\lambda = (1,0,0)$ , so  $\alpha = (3,1,0)$ , and we compute the coefficient obtained from the GT pattern

Having fixed a particular  $T \in SGT(3, 1, 0)$ , we iterate i, starting with i = 1. Then we have the set  $\Omega(r_2) = \{ \mathrm{Id}, [1\ 2] \}$ . We denote  $[1\ 2]$  as  $\phi$ . Then  $\phi(r_2) = (1, 1)$  and  $l(\phi) = 1$ .

We thus have two possibilities to consider: one for each raising operator. In each case, we display the relevant  $GT_2$  patterns and compute M. To minimize confusion, we have subscripts for integers that appear multiple times in a pattern.

Below is the  $GT_2$  pattern associated to the raising operator Id:

$$\begin{array}{cccc} 3 & & 1 & & 0_1 \\ & 2 & & 0_2 \end{array}$$

These rows give the matrix and corresponding coefficient:

$$\begin{vmatrix} w(2) & 1 \\ d(1) & w(0_2) \end{vmatrix} = \begin{vmatrix} 1 - q & 1 \\ -qt^2 & 1 + t \end{vmatrix} = 1 - q + t - qt + qt^2.$$
(46)

Below is the  $GT_2$  pattern associated to the raising operator  $\phi$ :

As  $l(\phi_1) = 1$  we multiply the determinant of the associated matrix by  $t^1$  to obtain

$$t \cdot \left| \begin{pmatrix} w(1_2) & 1 \\ d(1_1) & w(1_3) \end{pmatrix} \right| = t \cdot \left| \begin{matrix} 1 & 1 \\ -q & -q - qt \end{matrix} \right| = -qt^2. \tag{47}$$

That concludes the consideration of possible second rows. We add all of the coefficients from each case of a second row, i.e. (46) and (47), to find the total coefficient of

$$1 - q + t - qt + qt^{2} - qt^{2} = (1 - q)(1 + t).$$
(48)

Now iterating to i = 2, we have that  $\Omega(r_3)$  contains only the identity. Thus the only  $GT_2$  pattern to be considered is of the following form:

$$\begin{bmatrix} 2 & 0 \\ 1 & \end{bmatrix}$$

The determinant is simply

$$|w(1)| = (1 - q). (49)$$

Finally, we take the product of all the coefficients we got from each row, i.e. (48) and (49), and multiply this with  $x^{m(T)}$  where m(T) = (2, 1, 1). Thus, by Theorem 21, the GT pattern contributes the monomial

$$(1-q)^2(1+t)x_1^2x_2x_3, (50)$$

to the summation. As this is the unique GT pattern with top row  $\alpha = (2, 1, 0)$  and m(T) = (2, 1, 1), we should find that (50) gives the coefficient of  $x_1^2 x_2 x_3$  in the expansion of  $\Delta_3(q) \cdot R_{(1,0,0)}(x;t)$ . The reader can verify that this is indeed the case.

# 7 Specializations

The results of this paper generalize Tokuyama's formula and several other existing results. We demonstrate a few of these specializations.

# 7.1 Tokuyama's formula.

Recall from Definition 2 that  $R_{\lambda}(x;0) = s_{\lambda}(x)$ . We know that for all raising operators  $\phi \neq \text{Id}$ , the length of  $\phi$  is at least 1. Therefore, setting t = 0 reduces Theorem 21 to

$$\Delta_n(q) \cdot s_{\lambda} = \sum_{T \in SGT(\alpha)} \prod_{i=1}^{n-1} M(r_i; r_{i+1}) x^{m(T)}.$$

As these are all the identity cases on strict Gelfand-Tsetlin patterns, every row is strictly decreasing. This implies that consecutive entries cannot have  $p_r(a_{i,j}) = r$  and  $p_l(a_{i,j+1}) = l$ , and consequently  $d(a_{i,j})$  cannot be -q. All the remaining possibilities of  $d(a_{i,j})$  are reduced to 0 when t = 0. Thus, if we let  $r_{i+1} = (\mu_1, \ldots, \mu_{n-i})$ , the matrix  $M(r_i; r_{i+1})$  simplifies to

$$M(r_i; r_{i+1}) = \det \begin{bmatrix} w(\mu_1) & 1 & \dots & 0 \\ 0 & w(\mu_2) & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & w(\mu_{n-i}) \end{bmatrix}$$

Therefore, we have

$$M(r_i; r_{i+1}) = \prod_{k=1}^{n-i} w(\mu_k).$$
 (51)

Finally, returning to Tokuyama's terminology of left-leaning, right-leaning and special entries from Definition 4, we find that  $w(a_{i,j})$  simplifies to

$$w(a_{i,j}) = \begin{cases} -q & \text{if } a_{i,j} \text{ is left-leaning} \\ 1 - q & \text{if } a_{i,j} \text{ is special} \\ 1 & \text{if } a_{i,j} \text{ is right-leaning} \end{cases}$$
(52)

and, substituting this into (51) from earlier, we conclude with Tokuyama's formula:

$$\Delta_n(q) \cdot s_{\lambda} = \sum_{T \in SGT(\alpha)} (-q)^{l(T)} (1-q)^{z(T)} x^{m(T)}.$$

Comparing the results of this paper with Tokuyama's formula reveals some interesting distinctions regarding the structure of the Hall-Littlewood polynomials in relation to the Schur polynomials. Theorem 11 demonstrates that when expressing  $R_{\lambda}(x;t)$  recursively in terms of  $R_{\mu-\rho}(x;t)$ , it is more natural to include several non-strictly decreasing partitions  $\mu$  in the summation. This is not an issue for Tokuyama's formula as Schur polynomials of such non-strictly decreasing partitions  $\mu$  are just  $s_{\mu-\rho}(x)=0$ .

In fact, whilst Theorem 21 is stated as summations over strict GT patterns, the use of  $\Omega$  is to allow an implicit summation over all possible non-strict rows. We thus naturally seek a way to consider the contributions of such rows directly, eliminating the more ad hoc use of  $\Omega$ . Both theorems also highlight the added complexity in a Hall-Littlewood polynomial as they account for the ordering among the entries in a GT pattern instead of simply counting entries as Tokuyama does with z(T) and l(T).

### 7.2 Stanley's formula.

In [14], Stanley gave a formula for the Hall-Littlewood polynomials at the singular value t = -1, also known as the Schur q-polynomials, as a generating function of strict GT patterns of top row  $\lambda$ :

$$R_{\lambda}(x;-1) = \sum_{T \in SGT(\lambda)} 2^{z(T)} x^{m(T)}.$$
 (53)

Tokuyama subsequently showed in [16] that his formula yields (53) when the deformation parameter q is set to -1. Theorem 21 thus specializes to (53) at t = 0 and q = -1, by virtue of specializing to Tokuyama's result. However, setting t to -1 in Theorem 21 also gives a deformation along q of (53), and we can show that this deformation reduces to (53) at q = 0.

If  $a_{i,j}$  is an entry in a GT pattern, then we call  $a_{i,j}$  a p entry (where p is a property) if either  $p_l(a_{i,j})$  or  $p_r(a_{i,j}) = p$ .

With this terminology, examining Theorem 21 at the singular values of t = -1 and q = 0, we see that any pattern containing an l entry gives an overall coefficient of zero, which is evident through cofactor expansion of  $M(r_i; r_{i+1})$ .

Thus we may simply sum over the set  $SGTl(\alpha) \subset SGT(\alpha)$  that contains all GT patterns without l entries. Furthermore, any non-trivial element  $\phi \in \Omega(r_i)$  will either cause an element of  $\phi(r_i)$  to be an l entry with respect to  $r_{i+1}$ , or result in  $\phi(r_i) \notin GT_2(r_{i-1})$ , both resulting in an overall coefficient of zero. Furthermore, we show that GT patterns with consecutive r then al entries give coefficient 0.

We define

$$D = \prod_{i=2}^{n} M(r_{i-1}; r_i). \tag{54}$$

Assume for the sake of contradiction that there is a GT pattern with consecutive r then al entries for which  $D \neq 0$ . Let  $a_{i,j}$  and  $a_{i,j+1}$  be a pair of consecutive r then al entries in the lowest row containing such pairs. Then the r entry  $a_{i,j} = u$  for some  $u \in \mathbb{N}$ , and the al entry  $a_{i,j+1} = u - 1$ . Now consider the entry  $a_{i+1,j+1}$ . Since it cannot be l, or else D = 0, we must have  $a_{i+1,j+1} = u - 1$ . Then  $w(a_{i+1,j+1}) = 0$ ; so to ensure  $M(r_i; r_{i+1}) \neq 0$  (and consequently that  $D \neq 0$ ), we must have that either  $p_r(a_{i+1,j}) = r$  or  $p_l(a_{i+1,j+2}) = al$ . But this contradicts our hypothesis. Therefore, any GT pattern containing consecutive r then al entries yields an overall coefficient of zero.

Let the set  $SGTl^*(\alpha) \subset SGTl(\alpha)$  contain all GT patterns without l entries or consecutive r then al entries. For an entry  $a_{i,j}$  in a strict GT pattern  $T \in SGTl^*(\alpha)$ , we see that the only allowable value of  $d(a_{i,j})$  is (-qt)(t). Since q = 0 we have  $d(a_{i,j}) = 0$  for all entries here, simplifying  $M(r_i; r_{i+1})$  to the product  $\prod_j w(a_{i+1,j})$ . Thus Theorem 21 simplifies to

$$\Delta_n(0) \cdot R_{\lambda}(x; -1) = \sum_{T \in SGTl^*(\alpha)} \prod w(a_{i,j}) x^{m(T)}, \tag{55}$$

where the product is taken over all possible  $a_{i,j}$ . This leads us to introduce a bijective mapping, similar to one used in [16]:

$$SGTl^*(\alpha) \longrightarrow SGT(\lambda)$$
  

$$\Theta: \quad a_{i,j} \longmapsto a_{i,j} + j - n \qquad .$$
  

$$m(T) \longmapsto m(T) - \rho \qquad (56)$$

After applying this mapping, we have that  $w(a_{i,j}) = 2$  for all *special* entries and  $w(a_{i,j}) = 1$  otherwise, and thus (55) reduces to

$$x^{\rho} \cdot R_{\lambda}(x; -1) = x^{\rho} \cdot \sum_{T \in SGT(\lambda)} 2^{z(T)} x^{m(T)}.$$

Dividing out by  $x^{\rho}$ , we obtain (53).

## 7.3 Monomial symmetric function.

Recall from Definition 2 that the monomial symmetric function

$$m_{\lambda}(x) = \sum_{\sigma \in S_n} \sigma(x^{\lambda}) \tag{57}$$

We note that, since  $R_{\lambda}(x;1) = m_{\lambda}(x)$ , we may obtain a new q-deformation of (57) by setting t = 1 in Theorem 21, although the result does not appear as elegant as the t = 0 and t = -1 cases. This specialization is, however, not difficult to prove independently.

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