Identifying codes in vertex-transitive graphs and strongly regular graphs

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Abstract

We consider the problem of computing identifying codes of graphs and its fractional relaxation. The ratio between the size of optimal integer and fractional solutions is between 1 and $2\ln(|V|) + 1$ where V is the set of vertices of the graph. We focus on vertex-transitive graphs for which we can compute the exact fractional solution. There are known examples of vertex-transitive graphs that reach both bounds. We exhibit infinite families of vertex-transitive graphs with integer and fractional identifying codes of order $|V|^{\alpha}$ with $\alpha \in \{\frac{1}{4}, \frac{1}{3}, \frac{2}{5}\}$. These families are generalized quadrangles (strongly regular graphs based on finite geometries). They also provide examples for metric dimension of graphs.

Keywords: identifying codes, metric dimension, vertex-transitive graphs, strongly regular graphs, finite geometry, generalized quadrangles

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1 Introduction

Given a discrete structure on a set of elements, a natural question is to be able to locate efficiently the elements using the structure. If the elements are the vertices of a graph, one can use the neighbourhoods of the elements to locate them. In this context, Karpovsky, Chakrabarty and Levitin [29] have introduced the notion of identifying codes in 1998. An identifying code of a graph is a dominating set having the property that any two vertices of the graph have distinct neighbourhoods within the identifying code. Hence any vertex of the graph is specified by its neighbourhood in the identifying code. Initially, identifying codes have been introduced to model fault-diagnosis in multiprocessor systems but later other applications were discovered such as the design of emergency sensor networks in facilities [38]. They are related to other concepts in graphs like locating-dominating sets [36, 37] and resolving sets [1, 35].

The problem of computing an identifying code of minimal size is NP-complete in general [11] but can be naturally expressed as an integer linear problem. Also, one can ask how good the fractional relaxation of this problem can be. We focus on vertex-transitive graphs since for these graphs, we are able to compute the optimal size of a fractional identifying code. This value depends only on three parameters of the graph: the number and degree of vertices and the smallest size of the symmetric difference of two distinct closed neighbourhoods. Moreover, the optimal cardinality of an integer identifying code is at most at a logarithmic factor (in the number of vertices |V|) of the fractional optimal value.

Identifying codes have already been studied in different classes of vertex-transitive graphs, especially in cycles [6, 21, 28, 39] and hypercubes [7, 12, 13, 27, 29]. In these examples, the order of the size of an optimal identifying code seems to always match its fractional value. However, the smallest size of symmetric differences of closed neighbour-hoods is small compared to the number of vertices: either it is constant (for cycles) or it has logarithmic order in the number of vertices (for hypercubes). Therefore we focus in this paper on vertex-transitive strongly regular graphs that are vertex-transitive graphs with the property that two adjacent (respectively non-adjacent) vertices always have the same number of common neighbours. In particular, the size of symmetric differences can only take two values and is of order at least $\sqrt{|V|}$ if the graph is not a trivial strongly regular graph.

Another interest of considering identifying codes in strongly regular graphs is that they are strongly related to resolving sets. A resolving set is a set S of vertices such that each vertex is uniquely specified by its distances to S. The minimum size of a resolving set is called the metric dimension of the graph. If a graph has diameter 2 – as is the case for non-trivial strongly regular graphs – then a resolving set is the same as an identifying code except that the vertices of the resolving set are not identified. A consequence is that the optimal size of identifying codes and the metric dimension have the same order in strongly regular graphs. Actually, Babai [1] introduced a notion equivalent to resolving sets in order to improve the complexity of the isomorphism problem for strongly regular graphs. He established an upper bound of order $\sqrt{|V|} \log_2(|V|)$ on the metric dimension of strongly regular graphs [1, 2]. He also gave a finer bound using the degree k of vertices of order $|V| \log_2(|V|)/k$ [2]. Thanks to this last bound, any family of strongly regular graphs for which |V| is linear with k have logarithmic metric dimension. This is for example the case of Paley graphs that have also been studied by Fijavž and Mohar [15] who gave a finer bound. Bailey and Cameron [5] proved that the metric dimension of some Kneser and Johnson graphs has order $\sqrt{|V|}$. Values for small strongly regular graphs have been computed [4, 30]. Recently, Bailey [3] used resolving sets in strongly regular graphs to compute the metric dimension of some distance-regular graphs.

Paley graphs give an example of an infinite family of graphs for which the optimal value of fractional identifying code is constant but the integer value is logarithmic, and so the gap between the two is also logarithmic. We consider another family of strongly regular graphs that have never been studied in the context of identifying codes nor resolving sets: the adjacency graphs of generalized quadrangles. These graphs are constructed using finite geometries. Constructing identifying codes can be seen as a way to break the inherent symmetry of these graphs. We give constructions of identifying codes with size of optimal order. This order is of the form $|V|^{\alpha}$ with $\alpha \in \{\frac{1}{4}, \frac{1}{3}, \frac{2}{5}\}$ and corresponds to the order of the fractional value.

Outline. In Section 1, we give formal definitions and classic results useful for the rest of the paper. In Section 2, we exhibit the linear program for identifying codes, compute the optimal value of the relaxation for vertex-transitive graphs and deduce a general bound. In Section 3, we review known results for identifying codes in vertex-transitive graphs and compare them to our general bound. Finally in Section 4, we study strongly regular graphs and in particular adjacency graphs of generalized quadrangles.

2 Preliminaries

All the considered graphs are undirected, finite and simple. Let G = (V, E) be a graph. Let u be a vertex of G. We denote by N(u) the open neighbourhood of u, that is the set of vertices that are adjacent to u. We denote by $N[u] = N(u) \cup \{u\}$ the closed neighbourhood of u: u and all its neighbours. The *degree* of a vertex is the number of its neighbours. A graph is *regular* if all vertices have the same degree. Given two vertices uand v, we denote by d(u, v) the distance between u and v that is the number of edges in a shortest path between u and v. The *diameter* of G is the maximum distance between any pair of vertices of the graph. An *isomorphism* $\varphi : G = (V, E) \to G' = (V', E')$ between two graphs G and G' is a bijective application from V to V' that preserves the edges of the graph: uv is an edge of G if and only if $\varphi(u)\varphi(v)$ is an edge of G'. If G = G', φ is called an *automorphism* of G. A graph is *vertex-transitive* if for any pair of vertices u and v there exists an automorphism sending u to v. A vertex-transitive graph is in particular regular.

A subset of vertices S is a *dominating set* if each vertex is either in S or adjacent to a vertex in S. In other words, for every vertex $u, S \cap N[u]$ is non-empty. A vertex c separates two vertices u and v if exactly one vertex among u and v is in the closed neighbourhood

of c. In other words, $c \in N[u]\Delta N[v]$ where Δ denotes the symmetric difference of sets. A subset of vertices S is a separating set if it separates every pair of vertices of the graph. A subset of vertices C is an *identifying code* if it is both a dominating and separating set. In other words, the set $N[u] \cap C$ is non-empty and uniquely determines u. There exists an identifying code in G if and only if G does not have two vertices u and v with N[u] = N[v]. We say that two such vertices u and v are *twin vertices* and we will only consider twin-free graphs. The size of a minimal identifying code of G is denoted by $\gamma^{\text{ID}}(G)$. We have the following general bounds.

Proposition 1 (Karpovsky, Chakrabarty and Levitin [29], Gravier and Moncel [20]). Let G be a twin-free graph with at least one edge. We have

$$\log_2(|V|+1) \leqslant \gamma^{\mathrm{ID}}(G) \leqslant |V|-1.$$

The lower bound can be found by considering that in an identifying code C of size $\gamma^{\text{ID}}(G)$, the sets $N[u] \cap C$ are all distinct and non-empty subsets of a set of size $\gamma^{\text{ID}}(G)$. Both bounds are tight and graphs reaching the lower bound are described in [32] whereas graphs reaching the upper bound are characterized in [16].

When the maximum degree of the graph is small enough, the following lower bound is better than the previous one.

Proposition 2 (Karpovsky, Chakrabarty and Levitin [29]). Let G be a graph of maximum degree k. We have

$$\gamma^{\mathrm{ID}}(G) \geqslant \frac{2|V|}{k+1}.$$

Karpovsky *et al.* prove this bound using a discharging method. We use the same method to obtain a tighter bound that we will need when $\gamma^{\text{ID}}(G)$ is smaller than the maximum degree of the graph.

Proposition 3. Let G = (V, E) be a twin-free graph of maximum degree k and C an identifying code of G with $k \ge |C| + 1$. We have

$$|V| \leqslant \frac{|C|^2}{6} + \frac{(2k+5)|C|}{6}$$

Proof. We use the same discharging method as Karpovsky *et al.* in [29]. Each vertex receives a charge 1 at the beginning. Then each vertex v gives to the vertices in $N[v] \cap C$ the charge $\frac{1}{|N[v] \cap C|}$. After this process, only vertices of C have a positive charge and the total charge is still |V|.

Let $c \in C$. Let V_i be the set of vertices of N[c] with exactly *i* neighbours in *C*. Necessarily $|V_1| \leq 1$ since vertices in V_1 have only *c* in their neighbourhood. We have $|V_2| \leq |C| - 1$. Indeed, a vertex of V_2 has *c* in its neighbourhood and a unique additional vertex of the code. But all the additional code neighbours of elements of V_2 must be different, hence there are at most |C| - 1 vertices in V_2 . Finally, there are $k+1-|V_1|-|V_2|$ other vertices giving charge at most 1/3. Therefore, *c* receives a charge at most equal to

$$|V_1| + \frac{|V_2|}{2} + \frac{k+1 - |V_1| - |V_2|}{3} \le 1 + \frac{|C| - 1}{2} + \frac{k - |C| + 1}{3} = \frac{|C|}{6} + \frac{2k + 5}{6}.$$

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Hence the total charge |V| is at most $\frac{|C|^2}{6} + \frac{(2k+5)|C|}{6}$.

The concept of identifying codes is related to other concepts such as locating-dominating sets and resolving sets. A *locating-dominating set* is a dominating set S that separates the pairs of vertices that are not in S. The size of a minimal locating-dominating set of G is denoted by $\gamma^{\text{LD}}(G)$. Note that every graph admits a locating-dominating set since the whole set of vertices is one. An identifying code is always a locating-dominating set and one can obtain an identifying code from a locating-dominating set by adding at most $\gamma^{\text{LD}}(G)$ vertices. Therefore we have the following relations between $\gamma^{\text{LD}}(G)$ and $\gamma^{\text{ID}}(G)$.

Proposition 4 (Gravier, Klasing and Moncel [19]). Let G be a twin-free graph. We have

$$\gamma^{\mathrm{LD}}(G) \leqslant \gamma^{\mathrm{ID}}(G) \leqslant 2\gamma^{\mathrm{LD}}(G).$$

A resolving set is a subset of vertices S such that for every pair of vertices u and v, there exists a vertex x in S that satisfies $d(x, u) \neq d(x, v)$. The smallest size of a resolving set of G is called the *metric dimension* and is denoted by $\beta(G)$. A locating-dominating set is always a resolving set and so $\beta(G) \leq \gamma^{\text{LD}}(G)$. When the diameter of the graph is 2, the reverse is almost true: adding a vertex to a resolving set gives a locating dominating set.

Proposition 5. Let G be a graph of diameter 2. We have

$$\beta(G) \leqslant \gamma^{\mathrm{LD}}(G) \leqslant \beta(G) + 1.$$

Proof. The first part is true for any graph since a locating-dominating set is a resolving set. Now let S be a resolving set of a graph G of diameter 2. Order the vertices of $S = \{x_1, \ldots, x_s\}$. For every vertex u, let $L(u) = (d(u, x_1), \ldots, d(u, x_s))$ be the distance vector to vertices of S. Since S is a resolving set, all the vectors L(u) are distinct. Since the diameter is 2, $L(u) \in \{0, 1, 2\}^s$. But at most one vertex u_0 can have $L(u_0) = (2, 2, \ldots, 2)$, hence all vertices except u_0 are dominated by a vertex of S. Therefore, the set $S' = S \cup \{u_0\}$ is a dominating set. Let u be a vertex not in S'. It has only values 1 and 2 in its vector L(u) and the set $N[u] \cap S$ is given by the value 1 in L(u). Hence all the sets $N[u] \cap S$ for $u \notin S'$ are distinct. Therefore, all the sets $N[u] \cap S'$ are also distinct for $u \notin S'$ and S' is a locating-dominating set. In particular, $\gamma^{\text{LD}}(G) \leq \beta(G) + 1$.

Proposition 4 together with Proposition 5 gives a relation between $\gamma^{\text{ID}}(G)$ and the metric dimension in graphs of diameter 2. In particular, they have the same order and let us derive results for identifying codes from results for resolving sets.

Corollary 6. Let G be a twin-free graph of diameter 2. We have

$$\beta(G) \leqslant \gamma^{\mathrm{ID}}(G) \leqslant 2\beta(G) + 2.$$

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3 Fractional relaxation

The problem of finding a minimal identifying code in a graph G can be expressed as a hitting set problem. Indeed an identifying code is a subset of V that intersects all the sets N[u] and $N[u]\Delta N[v]$ for $u, v \in V$. In other words, the problem of finding a minimal identifying code is equivalent to the following linear integer program P_G .

Let us denote by P_G^* the linear programming fractional relaxation of P_G where the integrality condition $x_u \in \{0, 1\}$ is replaced by a linear constraint $0 \leq x_u \leq 1$ for all vertices $u \in V$. The optimal value of P_G^* , denoted by $\gamma_f^{\text{ID}}(G)$, gives an estimation on $\gamma^{\text{ID}}(G)$ within a logarithmic factor.

Proposition 7. Let G be a twin-free graph with at least three vertices. We have

$$\gamma_f^{\rm ID}(G) \leqslant \gamma^{\rm ID}(G) \leqslant \gamma_f^{\rm ID}(G)(1+2\ln|V|).$$

Proof. The first inequality is trivial since P_G^* is a relaxation of P_G . Let \mathcal{H} be the hypergraph with vertex set V and hyperedge set

$$\mathcal{E} = \{ N[u] \mid u \in V \} \cup \{ N[u] \Delta N[v] \mid u \neq v \in V \}.$$

The identifying code problem in G is equivalent to the covering problem in \mathcal{H} that is the problem of finding a set of vertices of minimum size that intersects all the hyperedges. The linear programming formulations are the same. Using the result of Lovász [31] on the ratio of optimal integral and fractional covers, we have

$$\gamma^{\mathrm{ID}}(G) \leqslant \gamma_f^{\mathrm{ID}}(G)(1+\ln r)$$

where r is the maximal degree of \mathcal{H} , i.e. the maximum number of hyperedges a vertex is belonging to. Let $u \in V$ and k its degree in G. Then u is in k+1 hyperedges of the form N[v] and in (|V|-k-1)(k+1) hyperedges of the form $N[v]\Delta N[w]$. Indeed, we must have $v \in N[u]$ and $w \notin N[u]$. Hence the degree of u in \mathcal{H} is (|V|-k)(k+1). The maximal value of (|V|-k)(k+1) with $0 \leq k \leq |V|-1$ is obtained for $k = \frac{|V|-1}{2}$. Therefore, $r \leq \frac{(|V|+1)^2}{2} \leq |V|^2$ for $|V| \geq 3$ which leads to the upper bound of the proposition. \Box

In the case of vertex-transitive graphs, we can compute the exact value of γ_f^{ID} .

Proposition 8. Let G be a twin-free vertex-transitive graph. Let k denote the degree of G and let d denote the smallest size of symmetric differences of closed neighbourhoods $N[u]\Delta N[v]$ among all the pairs of distinct vertices u, v. We have

$$\gamma_f^{\rm ID}(G) = \frac{|V|}{\min(k+1,d)}$$

In particular

$$\frac{|V|}{\min(k+1,d)} \leqslant \gamma^{\text{ID}}(G) \leqslant \frac{|V|(1+2\ln|V|)}{\min(k+1,d)}.$$

Proof. Giving to each variable x_u the value $\frac{1}{\min(k+1,d)}$ leads to a feasible solution of P_G^* , hence

$$\gamma_f^{\rm ID}(G) \leqslant \frac{|V|}{\min(k+1,d)}$$

Since G is a vertex-transitive graph, all the vertices play the same role. Consider the finite set \mathcal{S} of extreme optimal solutions (solutions that are vertices of the polytope defined by P^*). Any linear combination of elements of \mathcal{S} , with the sum of coefficients equal to 1 is still an optimal solution of P^* . In particular, $\mathbf{x} = \frac{1}{|\mathcal{S}|} \sum_{s \in \mathcal{S}} s$ is an optimal solution. We claim that all the components of \mathbf{x} are equal. Indeed, assume that $x_u \neq x_v$ and let φ be an automorphism sending u to v. Let $s \in \mathcal{S}$, then $\varphi(s)$ and $\varphi^{-1}(s)$, obtained by permuting the value inside s following the automorphism φ are still extreme optimal solutions. Hence \mathcal{S} is stable by φ and so $\varphi(\mathbf{x}) = \mathbf{x}$, a contradiction since $x_u \neq x_v$. \Box

4 Known results on vertex-transitive graphs

We review some known results on classes of transitive graphs. In particular, we discuss the gap between γ^{ID} and γ_f^{ID} . Sometimes, not only identifying codes but also *r*-identifying codes have been studied in these classes. Instead of using the closed neighbourhoods, that are the balls of radius 1, one consider the balls of radius *r* to identify the vertices. It is equivalent to consider *r*-identifying codes in a graph *G* or to consider identifying codes in G^r , the *r*th-power of *G*, obtained by adding edges between each pair of vertices of *G* that are at distance at most *r*. In the following, we will express the results in terms of identifying codes in the power graph.

4.1 Cycles

We first consider cycles and powers of cycles. Let $n, r \in \mathbb{N}$ with $n \ge 5$ and $1 \le r < \frac{n-1}{2}$. The cycle on n vertices, \mathcal{C}_n , has vertex set $V = \{0, 1, \ldots, n-1\}$ and two distinct vertices i and j are adjacent if |i - j| = 1 (modulo n). The graph \mathcal{C}_n^r is vertex-transitive with vertex degree 2r. The smallest symmetric difference of closed neighbourhoods has size 2. It is obtained via two consecutive vertices i and i + 1 whose symmetric difference of closed neighbourhoods is the set $\{i - r, i + r + 1\}$ (modulo n). Hence the optimal value of fractional identifying codes is $\gamma_f^{\text{ID}}(\mathcal{C}_n^r) = \frac{n}{2}$. On the other hand, the study of integer identifying codes in powers of cycles had taken several years (see e.g. [6, 21, 39]) before being completed by Junnila and Laihonen [28]. We have the following results. If n is even and at least 2r + 4, then

$$\gamma^{\mathrm{ID}}(\mathcal{C}_n^r) = \frac{n}{2} = \gamma_f^{\mathrm{ID}}(\mathcal{C}_n^r).$$

If n is odd and at least 2r + 3, then

$$\frac{n+1}{2} \leqslant \gamma^{\mathrm{ID}}(\mathcal{C}_n^r) \leqslant \frac{n+1}{2} + r.$$

In particular, the difference between $\gamma^{\text{ID}}(\mathcal{C}_n^r)$ and $\gamma_f^{\text{ID}}(\mathcal{C}_n^r)$ is bounded by r. Hence the ratio is converging to 1 when r is fixed and n is large.

When n = 2r + 2, C_n^r is a complete graph where a perfect matching is removed and we have $\gamma^{\text{ID}}(\mathcal{C}_n^r) = n - 1$. Then $\frac{\gamma^{\text{ID}}(\mathcal{C}_n^r)}{\gamma_f^{\text{ID}}(\mathcal{C}_n^r)} \to 2$ when *n* is large. Finally, if n = 2r + 3, $\gamma^{\text{ID}}(\mathcal{C}_n^r) = \lfloor \frac{2n}{3} \rfloor$ and the ratio is converging to 4/3.

4.2 Hypercubes

Let $\ell \ge 3$. The vertex set of the hypercube of dimension ℓ , denoted by \mathcal{H}_{ℓ} , is the set of binary words of length ℓ , $\{0,1\}^{\ell}$. Two vertices are adjacent if the corresponding words differ on exactly one letter. Clearly, \mathcal{H}_{ℓ} is vertex-transitive with vertex degree $k = \ell$. The smallest symmetric difference of closed neighbourhoods has size $d = 2\ell - 2$ and is obtained via two adjacent vertices. Hence, by Proposition 8,

$$\gamma_f^{\rm ID}(\mathcal{H}_\ell) = \frac{2^\ell}{\ell+1}.$$

Computing the exact value of $\gamma^{\text{ID}}(\mathcal{H}_{\ell})$ seems difficult and only few exact values are known. However, we have the following bounds (see [12, Theorem 4] for the upper bound and [29] for the lower bound)

$$\frac{\ell 2^{\ell+1}}{\ell(\ell+1)+2} \leqslant \gamma^{\mathrm{ID}}(\mathcal{H}_{\ell}) \leqslant \frac{9}{2} \cdot \frac{2^{\ell}}{\ell+1}.$$

Hence the optimal values of integer and fractional identifying codes have the same order and the ratio satisfies

$$2 - \frac{4}{\ell(\ell+1) + 2} \leqslant \frac{\gamma^{\mathrm{ID}}(\mathcal{H}_{\ell})}{\gamma_{f}^{\mathrm{ID}}(\mathcal{H}_{\ell})} \leqslant \frac{9}{2}.$$

Let $1 < r < \ell$. We now consider *r*-identifying codes or equivalently identifying codes in \mathcal{H}_{ℓ}^r . The graph \mathcal{H}_{ℓ}^r is still vertex-transitive. The degree of the vertices is $k = \sum_{i=1}^r \binom{\ell}{i}$. The smallest symmetric difference of closed neighbourhoods has now size $d = 2\binom{\ell-1}{r}$ and is still obtained via two adjacent vertices of \mathcal{H}_{ℓ} . Thus, by Proposition 8,

$$\gamma_f^{\mathrm{ID}}(\mathcal{H}_{\ell}^r) = \frac{2^{\ell}}{\min\left(\sum_{i=0}^r \binom{\ell}{i}, 2\binom{\ell-1}{r}\right)}.$$

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Concerning the general behaviour of $\gamma^{\text{ID}}(\mathcal{H}_{\ell}^{r})$, we consider two cases: r is fixed or r is linearly dependent on ℓ . Assume first that r is fixed and ℓ is large. The bounds given by Karpovsky *et al.* [29] can be translated as follows. There are two constants α and β (depending on r) such that, for large ℓ ,

$$\alpha \cdot \frac{2^{\ell}}{\ell^r} \leqslant \gamma^{\mathrm{ID}}(\mathcal{H}^r_{\ell}) \leqslant \beta \cdot \frac{2^{\ell}}{\ell^r}.$$
 (1)

Thus $\gamma^{\text{ID}}(\mathcal{H}^r_{\ell})$ and $\gamma^{\text{ID}}_f(\mathcal{H}^r_{\ell})$ have the same order, that is $2^{\ell}/\ell^r$.

Assume now that $r = \lfloor \rho \ell \rfloor$ for some constant ρ . Honkala and Lobstein [27] proved that

$$\lim_{\ell \to \infty} \frac{\log_2 \gamma^{\mathrm{ID}}(\mathcal{H}_{\ell}^r)}{\ell} = 1 - h(\rho)$$

where $h(x) = -x \log_2(x) - (1-x) \log_2(1-x)$ is the binary entropy function. This result can be proved with Proposition 7. Indeed, $\frac{\log_2 \sum_{i=0}^r \binom{\ell}{i}}{\ell}$ and $\frac{\log_2 \binom{\ell}{r}}{\ell}$ tend to $h(\rho)$. Hence

$$\lim_{\ell \to \infty} \frac{\log_2 \gamma_f^{\rm ID}(\mathcal{H}_\ell^r)}{\ell} = 1 - h(\rho)$$

and

$$\lim_{\ell \to \infty} \frac{\log_2\left(\gamma_f^{\mathrm{ID}}(\mathcal{H}_\ell^r)(1+2\ln 2^\ell)\right)}{\ell} = 1 - h(\rho).$$

But we do not know if $\gamma^{\text{ID}}(\mathcal{H}_{\ell}^r)$ and $\gamma_f^{\text{ID}}(\mathcal{H}_{\ell}^r)$ have the same order in this case.

4.3 Product of graphs

One can easily obtain other vertex-transitive graphs by forming products of vertextransitive graphs such as cliques. This was already the case for the hypercube which is the Cartesian product of ℓ cliques of size 2. Identifying codes in the following products of graphs have been recently considered. Let $G = (V_G, E_G)$ and $H = (V_H, E_H)$ be two graphs. All the products we are using have vertex set $V_G \times V_H$. We follow notation and terminology of [23].

- For the Cartesian product $G \Box H$, two vertices (u_G, u_H) and (v_G, v_H) are adjacent if either $u_G = v_G$ and $u_H v_H \in E_H$ or $u_H = v_H$ and $u_G v_G \in E_G$.
- For the direct product $G \times H$, two vertices (u_G, u_H) and (v_G, v_H) are adjacent if $u_G v_G \in E_G$ and $u_H v_H \in E_H$.
- For the *lexicographic product* $G \circ H$, two vertices (u_G, u_H) and (v_G, v_H) are adjacent if either $u_G v_G \in E_G$ or $u_G = v_G$ and $u_H v_H \in E_H$.

Cartesian product of two cliques. Let $2 \leq p \leq q$ be integers. The Cartesian product $K_p \Box K_q$ of two cliques is a vertex-transitive graph with vertex degree k = p + q - 1. The

smallest symmetric difference of closed neighbourhoods has size d = 2p-2 and is obtained via two adjacent vertices. By Proposition 8,

$$\gamma_f^{\mathrm{ID}}(K_p \Box K_q) = \frac{pq}{2p-2}.$$

Identifying codes in $K_p \Box K_q$ have been studied by Gravier, Moncel and Semri [22] and by Goddard and Wash [17]. They proved that

$$\gamma^{\mathrm{ID}}(K_p \Box K_q) = \begin{cases} q + \lfloor \frac{p}{2} \rfloor & \text{if } q \leqslant \frac{3p}{2} \\ 2q - p & \text{if } q \geqslant \frac{3p}{2} \end{cases}$$

Therefore, the ratio between the optimal values of integer and fractional identifying codes is

$$\frac{\gamma^{\mathrm{ID}}(K_p \Box K_q)}{\gamma_f^{\mathrm{ID}}(K_p \Box K_q)} = \begin{cases} 2 + \frac{p}{q} - \frac{2}{p} - \frac{1}{q} & \text{if } q \leqslant \frac{3p}{2} \\ 4 - \frac{2p}{q} - \frac{4}{p} + \frac{2}{q} & \text{if } q \geqslant \frac{3p}{2} \end{cases}$$

In particular, it is bounded by a constant.

Note that the metric dimension of Cartesian product of graphs and in particular of cliques have been studied by Cáceres *et al.* [8].

Direct product of cliques. Let $2 \leq p \leq q$ be integers. The direct product $K_p \times K_q$ of two cliques is a vertex-transitive graph with vertex degree k = (p-1)(q-1). The smallest symmetric difference of closed neighbourhoods has size d = 2p and is obtained via two vertices belonging to the same copy of K_q . By Proposition 8,

$$\gamma_f^{\mathrm{ID}}(K_p \times K_q) = \begin{cases} \frac{q}{2} & \text{if } p \ge 4 \text{ or } q > p\\ \frac{pq}{(p-1)^2 + 1} & \text{if } p \le 3 \text{ and } p = q. \end{cases}$$

Rall and Wash [34] gave the exact size of optimal identifying codes in $K_p \times K_q$. Except the small values of p and q, there are two main cases. If $p \ge 3$ and $q \ge 2p$, then $\gamma^{\text{ID}}(K_p \times K_q) = q - 1$. If $p \ge 5$ and q < 2p, then $\gamma^{\text{ID}}(K_p \times K_q)$ is either $\lfloor \frac{2(p+q)}{3} \rfloor$ or $\lceil \frac{2(p+q)}{3} \rceil$ depending on the value of p+q modulo 3. Therefore, the ratio between the optimal values of integer and fractional identifying codes is either 2 - 2/q or 4/3(1 + p/q), and it is again bounded.

Lexicographic product of graphs. Let G and H be two vertex-transitive graphs that are not complete graphs. Then $G \circ H$ is also vertex-transitive. If G (respectively H) has vertex degree k_G (resp. k_H) and n_G (resp. n_H) vertices, then $G \circ H$ has $n_G n_H$ vertices and vertex degree $k = k_G n_H + k_H$. Moreover, the size of the smallest symmetric difference of closed neighbourhoods of $G \circ H$ and H are equal. Hence

$$\gamma_f^{\mathrm{ID}}(G \circ H) = \frac{n_G n_H}{d_H}$$

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where d_H is the smallest symmetric difference of closed neighbourhoods of H.

Assume that G does not have two vertices u and v such that N(u) = N(v). Feng et al. [14] proved that in this case

$$\gamma^{\mathrm{ID}}(G \circ H) = n_G s_H$$

where s_H is the minimum size of a separating set of H. Hence we have

$$\frac{\gamma^{\mathrm{ID}}(G \circ H)}{\gamma^{\mathrm{ID}}_{f}(G \circ H)} = \frac{s_{H}d_{H}}{n_{H}}.$$

If H is such that $k_H + 1 \ge d_H$, then $\gamma_f^{\text{ID}}(H) = \frac{n_H}{d_H}$. Since s_H is either equal to $\gamma^{\text{ID}}(H)$ or $\gamma^{\text{ID}}(H) - 1$, the ratio between $\gamma^{\text{ID}}(G \circ H)$ and $\gamma_f^{\text{ID}}(G \circ H)$ is the same as the ratio between $\gamma^{\text{ID}}(H)$ and $\gamma_f^{\text{ID}}(H)$. In particular, if we have a ratio α for a graph H we can obtain graphs with arbitrary sizes and still ratio α .

5 Strongly regular graphs

5.1 General remarks

The bound of Proposition 8 is helpful when the symmetric differences are large (larger than $\ln |V|$). For this reason, we now focus on the family of strongly regular graphs for which the smallest symmetric difference has, in most cases, size at least $\sqrt{|V|}$ (see Proposition 12).

A strongly regular graph $\operatorname{srg}(n, k, \lambda, \mu)$ is a k-regular graph G on n vertices for which any pair of adjacent (respectively non-adjacent) vertices have exactly λ (resp. μ) neighbours in common.

The four parameters are related in the following way

$$(n-k-1)\mu = k(k-\lambda - 1).$$
 (2)

This relation can be proved by considering one particular vertex u and the partition of $V \setminus \{u\}$ between the neighbours A = N(u) and the non-neighbours $B = V \setminus N[u]$ of u. The number of edges between A and B is $(n - k - 1)\mu = k(k - \lambda - 1)$.

The complement of a strongly regular graph is still a strongly regular graph and has parameters $\operatorname{srg}(n, n-1-k, n-2-2k+\mu, n-2k+\lambda)$. A strongly regular graph is *primitive* if the graph and its complement are connected.

Example 9. Let G be a $\operatorname{srg}(n, k, \lambda, \mu)$. A trivial non primitive case is given by $\mu = 0$. Indeed, if $\mu = 0$, then it is the disjoint union of complete graphs on k + 1 vertices. In particular, $\lambda = k - 1$.

Another non primitive case is given by $\mu = k$. Then G is a complete multipartite graph. Necessarily, all the parts have the same size, n - k. Note that the complement of G corresponds to the first graph.

The two graphs in the previous example are the only non primitive graphs.

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Lemma 10. Let G be a strongly regular graph. G is primitive if and only if $\mu \notin \{0, k\}$. In particular, all primitive strongly regular graphs have diameter 2.

Proof. As explained in Example 9, if $\mu \in \{0, k\}$ then G is not primitive. If $\mu \neq 0$, then two non-adjacent vertices have at least one vertex in common. Hence the diameter of G is two and in particular, G is connected. Assume now that $\mu \neq k$. By Equation (2), the value of μ for the complement of G, $n - 2k + \lambda$, is not 0. As before, it means that the complement of G has diameter 2 and is connected.

We now turn to results concerning identifying codes. Strongly regular graphs have been used by Gravier *et al.* [18] to provide families of graphs for which all the subsets of a given size are identifying codes. However, they did not study optimal identifying codes. As mentioned in the introduction, resolving sets and metric dimension have been studied in several contexts for strongly regular graphs. In particular, Babai [1] gave an upper bound on the size of the symmetric differences of open neighbourhood in strongly regular graphs which leads to bounds on the metric dimension. Following his ideas, we prove similar results for identifying codes.

We first compute the smallest size d of the symmetric differences of closed neighbourhoods using λ and μ and then give a general upper bound on d.

Proposition 11. Let G be a strongly regular graph $srg(n, k, \lambda, \mu)$. Let u and v be two vertices of G. If u is adjacent to v, then $|N[u]\Delta N[v]| = 2(k-1) - 2\lambda$. Otherwise, $|N[u]\Delta N[v]| = 2(k+1) - 2\mu$.

Hence, the smallest symmetric difference of closed neighbourhoods is

$$d = \min(2(k - \lambda - 1), 2(k - \mu + 1)) = 2k - 2\max(\lambda + 1, \mu - 1).$$

If G is vertex-transitive¹, we have

$$\gamma_f^{\text{ID}}(G) = \frac{n}{\min(k+1, 2(k-\lambda-1), 2(k-\mu+1))}.$$

Proof. Let u and v be two adjacent vertices. There are $k - \lambda$ neighbours of u that are not neighbours of v. But v is counted in these vertices. Hence $|N[u] \setminus N[v]| = k - 1 - \lambda$ and we obtain the results. The computation for the non-adjacent case is similar. \Box

Proposition 12. Let G be a primitive strongly regular graph $srg(n, k, \lambda, \mu)$ on n vertices, then $k \ge \sqrt{n-1}$ and the smallest symmetric difference satisfies $d > \sqrt{n-3}$.

Proof. Since G is primitive, by Lemma 10, it has diameter 2. Thus there are at most 1 + k + k(k-1) vertices in G. Hence $n \leq 1 + k^2$ and we obtain the upper bound on k.

To prove the second inequality, we use a result of Babai [1]: for every pair of vertices u, v of a primitive strongly regular graph $|N(u)\Delta N(v)| > \sqrt{n-1}$. If u and v are adjacent, $|N[u]\Delta N[v]| = |N(u)\Delta N(v)| - 2$ whereas if u and v are non adjacent, $|N[u]\Delta N[v]| = |N(u)\Delta N(v)| + 2$. Hence $d > \sqrt{n-3}$.

¹Actually, it seems that almost all the strongly regular graphs are not vertex-transitive, see for example [10]. However, all the strongly regular graphs we are considering in this paper are in fact vertex-transitive.

Using these bounds together with Proposition 8, we obtain the following general bound for strongly regular graphs when they are vertex-transitive.

Corollary 13. Let G be a primitive strongly regular graph $srg(n, k, \lambda, \mu)$. If G is vertextransitive, we have

$$\gamma^{\mathrm{ID}}(G) \leqslant \frac{n(1+2\ln n)}{\sqrt{n-3}}.$$

In particular $\gamma^{\text{ID}}(G) = O(\sqrt{n} \ln n)$.

5.2 Known results on particular families

The only strongly regular graphs for which we know optimal identifying codes are Cartesian and direct products of two cliques of the same size that we already mentioned in the previous section. The Cartesian product $K_p \Box K_p$ is a strongly regular graph $\operatorname{srg}(p^2, 2p-2, p-2, 2)$ whereas $K_p \times K_p$ (that is the complement of $K_p \Box K_p$) is a $\operatorname{srg}(p^2, (p-1)^2, (p-2)^2, (p-2)(p-1))$). We obtain results for some other families by considering previous work on metric dimension.

Kneser and Johnson graphs (of diameter 2). Let $1 \le p \le m$. The Johnson graph J(m, p) is the graph whose vertices are the subsets of size p of a set of m elements and two vertices are adjacent if the corresponding sets intersect in exactly p - 1 elements. Since the diameter of J(m, p) is $\min(p, m - p)$, the graph J(m, p) is a primitive strongly regular graph if and only if p = 2 or p = m - 2. Note that the two corresponding graphs are isomorphic and have parameters $\operatorname{srg}(\binom{m}{2}, 2(m-2), m-2, 4)$.

The Kneser graph K(m, p) is the graph whose vertices are the subsets of size p of a set of m elements and two vertices are adjacent if the corresponding sets do not intersect. The Kneser graph K(5,2) corresponds to the well known Petersen graph. The graph K(m, p) is a primitive strongly regular graph if and only if p = 2. The graph K(m, 2) is a $\operatorname{srg}\begin{pmatrix}m\\2\end{pmatrix}, \begin{pmatrix}m-2\\2\end{pmatrix}, \begin{pmatrix}m-4\\2\end{pmatrix}, \begin{pmatrix}m-3\\2\end{pmatrix}\end{pmatrix}$.

Bailey and Cameron [5] have computed the exact value of the metric dimension in J(m, 2) and K(m, 2).

Proposition 14 ([5, Corollary 3.33]). For $m \ge 6$, the metric dimension of the Johnson graph J(m, 2) and the Kneser graph K(m, 2) is $\frac{2}{3}(m-i) + i$ where $m \equiv i \pmod{3}$.

Using Corollary 6 we obtain a bound for identifying codes.

Corollary 15. Let G be K(m, 2) or J(m, 2). We have

$$\frac{2m}{3} \leqslant \gamma^{\mathrm{ID}}(G) \leqslant \frac{4(m+1)}{3}.$$

In particular, $\gamma^{\text{ID}}(G) = \Theta(\sqrt{|V|}).$

To compute the fractional identifying code number, one just has to compute the value of the smallest symmetric difference using Proposition 11. For K(m,2) and $m \ge 6$, $\mu - 1 \ge \lambda + 1$ and $2k - 2\mu + 2 = 2(m - 1) \le k + 1$. Hence, for $m \ge 6$,

$$\gamma_f^{\text{ID}}(K(m,2)) = \frac{m(m-1)}{4(m-1)} = \frac{m}{4}.$$

For J(m,2), $\lambda + 1 \ge \mu - 1$ whenever $m \ge 4$ and $2k - 2\lambda - 2 = 2(m-3) = k$. Hence

$$\gamma_f^{\text{ID}}(J(m,2)) = \frac{m(m-1)}{4(m-3)} = \frac{m}{4} + 2.$$

In all cases, we have $\gamma_f^{\text{ID}}(G) = \Theta(\sqrt{|V|})$ and the fractional and integer values have the same order for these graphs.

Paley graphs. The Paley graph P_q is defined for a prime power $q \equiv 1 \pmod{4}$. Vertices are the elements of the finite field \mathbb{F}_q on q elements, and a is adjacent to b if a - b is a square. They are strongly regular srg $\left(q, \frac{1}{2}(q-1), \frac{1}{4}(q-5), \frac{1}{4}(q-1)\right)$. Paley graphs have the particularity to have symmetric difference of closed neighbourhoods of order |V|, hence the fractional identifying code number is bounded by a constant and the identifying code number is of order $\log_2 |V|$.

Proposition 16. Let q be a prime power satisfying $q \equiv 1 \pmod{4}$ and $q \ge 9$. We have $\gamma_f^{\mathrm{ID}}(P_q) = \frac{2q}{q-1}$ and thus

$$\log_2(q+1) \leqslant \gamma^{\mathrm{ID}}(P_q) \leqslant (2+o(1))(1+2\ln q).$$

In particular, $\gamma^{\text{ID}}(P_a) = \Theta(\log_2 |V|).$

Proof. We first compute the value of d. We have

$$\max(\lambda + 1, \mu - 1) = \frac{q-1}{4}.$$

Thus $d = \frac{q-1}{2} < k+1 = \frac{q+1}{2}$ and $\gamma_f^{\text{ID}}(P_q) = \frac{2q}{q-1} \leq 2 + o(1)$. The lower bound on $\gamma^{\text{ID}}(P_q)$ is the general lower bound of Proposition 1. For the upper bound, we use the bound of Proposition 7 with $\gamma_f^{\text{ID}}(P_q)$.

Similar results were obtained for metric dimension.

Proposition 17 (Fijavž and Mohar [15]). Let q be a prime power satisfying $q \equiv 1$ (mod 4). Then the metric dimension of the Paley graph P_q satisfies

$$\log_2 q \leqslant \beta(P_q) \leqslant 2\log_2 q.$$

In particular, $\beta(P_q) = \Theta(\log_2 |V|).$

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5.3 Generalized quadrangles

The graphs obtained from generalized quadrangles form another family of strongly regular graphs. Let s, t be positive integers. A generalized quadrangle GQ(s, t) is an incidence structure, i.e. a set of points and lines, such that

- there are s + 1 points on each line,
- there are t + 1 lines passing through each point,
- for a point P that does not lie on a line L, there is exactly one line passing through P and intersecting L.

Such an incidence structure has (st + 1)(s + 1) points and (st + 1)(t + 1) lines. A trivial example is the incidence structure given by a square grid of size $s \times s$ which is a GQ(s-1, 1). The *dual* of a generalized quadrangle is obtained by reversing the role of the lines and the points. In particular, the dual of a GQ(s, t) is a GQ(t, s).

Adjacency graphs can be naturally obtained from generalized quadrangles: consider the points as vertices and two vertices are adjacent if the corresponding points belong to a common line. For example, the adjacency graph of the square grid is exactly the Cartesian product of two cliques of size s, $K_s \square K_s$, already mentioned in Section 3.3. By abuse of notation, GQ(s, t) will also denote the adjacency graph of a generalized quadrangle with parameters s and t.

Observe that a GQ(s, t) is a strongly regular graph srg((st+1)(s+1), s(t+1), s-1, t+1). Indeed, any vertex has degree k = s(t+1), any pair of adjacent vertices has s-1 common neighbours and any pair of non adjacent vertices has t+1 common neighbours. From these values, we can easily compute the smallest size of symmetric differences of closed neighbourhoods :

$$d = 2s(t+1) - 2\max(s, t).$$

We have d > k + 1 if and only if GQ(s, t) is not trivial, i.e. s > 1 and t > 1. In that case, the following inequalities, for which Cameron gave a short combinatorial proof [9], hold.

Lemma 18 (Higman's inequality [24, 25]). For a GQ(s,t), if s > 1 and t > 1, then $t \leq s^2$ and dually $s \leq t^2$.

From now on, we assume that s > 1 and t > 1. We obtain the following bounds on γ_f^{ID} for generalized quadrangles.

Proposition 19. Let G be a vertex-transitive GQ(s,t) with s > 1 and t > 1. Let n denote the number of vertices of the graph G. We have

$$2^{-5/4} \cdot n^{1/4} \leq \gamma_f^{\text{ID}}(G) \leq 2 \cdot n^{2/5}.$$

Proof. Let G be a vertex-transitive GQ(s,t) with s > 1 and t > 1. Then n = (st+1)(s+1) is the number of vertices of G. We have by Proposition 8

$$\gamma_f^{\rm ID}(G) = \frac{(st+1)(s+1)}{s(t+1)+1} = \frac{s^2t}{st+s+1} + 1.$$

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Polar space	Name	(s,t)	
$Q^+(3,q)$	Hyperbolic	(q,1)	a grid
Q(4,q)	Parabolic	(q,q)	dual of $W(3,q)$
$Q^{-}(5,q)$	Elliptic	(q,q^2)	dual of $H(3, q^2)$
$H(3,q^2)$	Hermitian	(q^2,q)	dual of $Q^{-}(5,q)$
$H(4,q^2)$	Hermitian	(q^2,q^3)	
W(3,q)	Symplectic	(q,q)	dual of $Q(4,q)$

Table 1: The finite classical polar spaces of rank 2.

As st < st + s + 1 < 2st, we obtain $\frac{1}{2}s < \gamma_f^{\text{ID}}(G) < 2s$. Moreover, using the previous lemma, we obtain

$$s^{5/2} \leqslant s^2 t < s^2 t + st + s + 1 = n \leqslant s^4 + s^3 + s + 1 < 2 \cdot s^4.$$

So $\left(\frac{1}{2}n\right)^{1/4} < s < n^{2/5}$. It follows that $\left(\frac{1}{2}\right)^{5/4} n^{1/4} < \gamma_f^{\text{ID}}(G) < 2n^{2/5}.$

So $\left(\frac{1}{2}n\right) < s < n^{-1}$. It follows that $\left(\frac{1}{2}\right) = n^{-1} < \gamma_f$ (G) $< 2n^{-1}$.

Constructions of GQ(s,t) are known only for (s,t) or (t,s) in the set

$$\{(q,q), (q,q^2), (q^2,q^3), (q-1,q+1)\}$$

where q is a prime power. Many of them are based on finite geometries. Generalized quadrangles coming from finite classical polar spaces of rank 2 are given in Table 1. For more information on these geometric structures, see e.g. [26]. It is well known that these polar spaces give rise to generalized quadrangles and they are often referred to as the classical generalized quadrangles [33]. As an example, the Cartesian product $K_{q+1} \Box K_{q+1}$ can be seen as the adjacency graph of the incidence structure $Q^+(3,q)$ obtained from the points of a hyperbolic quadric in a finite projective space (when q is a prime power).

There are other generalized quadrangles known, however they have the same parameters as the ones given in Table 1 or they have parameters (q - 1, q + 1) or (q + 1, q - 1). We provide identifying codes of optimal order for some cases. A summary of our results in generalized quadrangles is given in Table 2.

5.3.1 Identifying codes in $T_2^*(\mathcal{O})$, a particular $\mathrm{GQ}(q-1, q+1)$

Proposition 20. Let q > 2 be a power of 2. There exists a GQ(q - 1, q + 1) with an identifying code of size $3q - 3 = \Theta(n^{1/3})$ where n is the number of vertices.

Before giving the proof, we will consider a particular construction of a GQ(q-1, q+1)and give some structural properties. This construction is done in finite projective geometry. We recall some definitions for readers unfamiliar with them. For more information on finite projective geometry, see e.g. [24, 26].

GQ	(s,t)	n	Lower bound	Upper bound	Order
$T_2^*(\mathcal{O})$	(q-1,q+1)	q^3	3q - 7	3q - 3	$n^{1/3}$
Q(4,q)	(q,q)	$(q^2+1)(q+1)$	5q-2	3q-4	$n^{1/3}$
$Q^{-}(5,q)$	(q, q^2)	$(q^3+1)(q+1)$	5q	3q + 2	$n^{1/4}$
$H(3,q^2)$	(q^2,q)	$(q^3+1)(q^2+1)$	$5q^2 - 2$	$2q^2 - 2$	$n^{2/5}$

Table 2: Results obtained on optimal values of integer identifying codes of some generalized quadrangles. The number of vertices is denoted by n. Every order matches the order of the optimal value of fractional identifying codes. Note that in the first line, q must be a power of 2 whereas in the other cases, q is any prime power. Also in the first line, \mathcal{O} is a hyperconic.

Let q be a power of 2. We set ourselves in the 3-dimensional projective space PG(3,q)over the finite field \mathbb{F}_q of order q. The points of PG(3,q) can be described using four coordinates $(X_0, X_1, X_2, X_3) \in \mathbb{F}_q^4 \setminus \{\mathbf{0}\}$ where two coordinates that are proportional refer to the same point. Consider the hyperplane H_∞ of equation $X_0 = 0$ in PG(3,q) and the conic \mathcal{C} of equation $X_1X_3 - X_2^2 = 0$ in the hyperplane H_∞ . Any line of H_∞ intersects \mathcal{C} in 0, 1 or 2 points. A line intersecting \mathcal{C} in one point is *tangent* to \mathcal{C} . There is a special point, N(0, 0, 1, 0), called the *nucleus* of \mathcal{C} , that lies on all tangents of \mathcal{C} . Then any other point of H_∞ lies on exactly one tangent of \mathcal{C} . The set $\mathcal{O} = \mathcal{C} \cup \{N\}$ is a *hyperconic*. This set has the property that each line of H_∞ intersects \mathcal{O} in 0 or 2 points.

Now consider the following incidence structure $T_2^*(\mathcal{O}) = (\mathcal{P}, \mathcal{L})$, where the set \mathcal{P} of points is the set of affine points, i.e. points of PG(3,q) not in H_{∞} and the set \mathcal{L} of lines is the set of the lines through a point of \mathcal{O} not lying in H_{∞} . This incidence structure is well-known to be a GQ(q-1, q+1) (see for example [33, Theorem 3.1.3]).

We will now construct an identifying code in $T_2^*(\mathcal{O})$. In $T_2^*(\mathcal{O})$, the neighbourhood of a point P is composed of a cone $P\mathcal{C}$ (all the lines going through P and a point of \mathcal{C}) and the line PN, where the points of H_{∞} are removed. The common neighbours of two adjacent vertices are the q-2 points lying on the unique line incident with these two vertices. In the case of non adjacent vertices, we first determine the intersection of their two cones.

Lemma 21. Consider two distinct affine points P and Q such that $PQ \cap H_{\infty} \notin \mathcal{O}$. The intersection of the two cones PC and QC consists of the points of the conic C and of points lying in a plane containing N and $PQ \cap H_{\infty}$.

Proof. Consider two distinct affine points P(1, a, b, c) and $Q(1, \alpha, \beta, \gamma)$ such that $PQ \cap H_{\infty} \notin \mathcal{O}$. Consider the cones $P\mathcal{C}$ and $Q\mathcal{C}$ in PG(3, q). It is clear that the conic \mathcal{C} belongs to $P\mathcal{C} \cap Q\mathcal{C}$. Consider now a point $V(1, v_1, v_2, v_3)$ not lying in H_{∞} . Then V belongs to

 $P\mathcal{C}$ if and only if

$$(0, a - v_1, b - v_2, c - v_3) \in \mathcal{C}$$

$$\iff (a - v_1)(c - v_3) - (b - v_2)^2 = 0$$

$$\iff (ac - b^2) - cv_1 - av_3 + (v_1v_3 - v_2^2) = 0.$$

A similar computation holds for $V \in Q\mathcal{C}$. Hence $V \in P\mathcal{C} \cap Q\mathcal{C}$ implies that

$$(ac - b2) - (\alpha \gamma - \beta2) - (c - \gamma)v_1 - (a - \alpha)v_3 = 0.$$

So V lies in the plane π of equation $((ac-b^2) - (\alpha\gamma - \beta^2))X_0 - (c-\gamma)X_1 - (a-\alpha)X_3 = 0$. Consider the intersection of H_{∞} and π . It is the line ℓ satisfying the equations $X_0 = 0$ and $-(c-\gamma)X_1 - (a-\alpha)X_3 = 0$. Clearly, the line ℓ contains the nucleus N(0, 0, 1, 0) and also the point $PQ \cap H_{\infty} = (0, a-\alpha, b-\beta, c-\gamma)$.

Remark 22. In the previous statement, the points, arising as the intersection of the two cones, lie in a plane containing N and $PQ \cap H_{\infty}$, and they actually form a conic \mathcal{C}' . Since the two quadratic cones intersect in an algebraic curve of degree 4 which already contains the conic \mathcal{C} , the remaining curve Γ of degree 2 is either a conic \mathcal{C}' , either a line with multiplicity 2 or two lines. The last two cases are in contradiction with the fact that P and Q are two distinct points with $PQ \cap H_{\infty} \notin \mathcal{C} \cup \{N\}$. So it follows that $\Gamma = \mathcal{C}'$.

Corollary 23. Consider two distinct non adjacent vertices P and Q of $T_2^*(\mathcal{O})$. Their common neighbours are q points lying in a plane containing N and $PQ \cap H_{\infty}$, a point of the line PN and a point of the line QN.

Proof. Let P and Q be two distinct non adjacent vertices of $T_2^*(\mathcal{O})$. From the structure of the $\mathrm{GQ}(q-1,q+1)$, P and Q have q+2 common neighbours. Consider the lines PNand QN. They intersect only in N. Since P (respectively Q) has a unique projection P'on QN (resp. Q' on PN), P' and Q' are two common neighbours. The q other common neighbours come from the intersection of the two cones $P\mathcal{C}$ and $Q\mathcal{C}$. Hence, from the previous lemma, they lie on a plane containing N and $PQ \cap H_{\infty}$.

Theorem 24. The affine points of three lines of $T_2^*(\mathcal{O})$ containing N and spanning PG(3,q) form an identifying code of $T_2^*(\mathcal{O})$.

Proof. Consider three lines ℓ_1, ℓ_2, ℓ_3 of $T_2^*(\mathcal{O})$ containing N and spanning PG(3, q). The points of these lines form a dominating set since any point is either on one of these lines or has a unique projection on each line ℓ_i . As each point has a unique projection on each line ℓ_i , it is clear that two points on these lines are always separated. Similarly, a point incident with a line ℓ_i is always separated from a point not incident with ℓ_1, ℓ_2 , or ℓ_3 .

Consider now two points S_1 and S_2 that do not lie on the lines ℓ_i . Assume that these points are not separated. In other words, assume that $Q_1 \in \ell_1$, $Q_2 \in \ell_2$ and $Q_3 \in \ell_3$ are common neighbours of S_1 and S_2 . If S_1 and S_2 are adjacent, then their common neighbours lie on the same line S_1S_2 . Hence Q_1, Q_2 and Q_3 are collinear, a contradiction since ℓ_1, ℓ_2, ℓ_3 span PG(3, q). If S_1 and S_2 are not adjacent, then either Q_1, Q_2, Q_3 all lie in the plane, which is uniquely defined by the previous corollary, that contains the nucleus N and $S_1S_2 \cap H_{\infty}$, or at least one of them lies in the plane containing S_1, S_2 and N. In the first case, the three points Q_1, Q_2, Q_3 are all in the same plane containing N. Hence, ℓ_1, ℓ_2, ℓ_3 are coplanar which is a contradiction. In the second case, suppose that Q_1 lies in the plane containing S_1, S_2 and N. It follows that Q_1 is incident with the line S_1N or S_2N . It implies that either $S_1 \in \ell_1$ or $S_2 \in \ell_1$, which is a contradiction.

Therefore the set of points on ℓ_1, ℓ_2, ℓ_3 is an identifying code of $T_2^*(\mathcal{O})$.

Proof of Proposition 20. Let ℓ_1, ℓ_2 and ℓ_3 be three lines incident with N and spanning PG(3,q). Consider the set C consisting of the points of $T_2^*(\mathcal{O})$ on ℓ_1, ℓ_2, ℓ_3 . By Theorem 24, this set is an identifying code of size 3q. Let Q_1 be a point on ℓ_1 and Q_2, Q_3 be its projections on respectively ℓ_2 and ℓ_3 . The set $C \setminus \{Q_1, Q_2, Q_3\}$ is still a dominating set. Indeed, a point P that does not lie on the lines ℓ_i can not have Q_1, Q_2 and Q_3 as neighbours. Otherwise, Q_2 would have two projections on the line Q_1P , namely Q_1 and P.

Moreover, we have a one-to-one correspondence between the sets

$$(N[P] \cap C) \setminus \{Q_1, Q_2, Q_3\}$$
 and $N[P] \cap C$

since we can easily determine which vertices are eventually missing in the first sets. Hence, $C \setminus \{Q_1, Q_2, Q_3\}$ is an identifying code of $T_2^*(\mathcal{O})$ of size 3q - 3.

The next proposition gives lower bounds on the size of an identifying code in any adjacency graph of a GQ(q-1, q+1). In particular, our previous construction is optimal for q = 4 and close to a constant for the other cases.

Proposition 25. Let q be a power of 2. Any identifying code of a GQ(q-1, q+1) has size at least 3q-7. Moreover, it has size at least 9 = 3q-3 if q = 4, 19 = 3q-5 if q = 8, 42 = 3q-6 if q = 16 and 90 = 3q-6 if q = 32.

Proof. To prove this proposition, we use Proposition 3. Any identifying code C of a GQ(q-1, q+1), with $|C| < q^2 + q - 2$ satisfies the inequality

$$q^3 \leqslant \frac{|C|^2}{6} + \frac{(2(q^2+q-2)+5)|C|}{6}.$$

Hence, $|C|^2 + (2q^2 + 2q + 1)|C| - 6q^3 \ge 0$. If there exists an identifying code of size 3q - 8, then the right-hand side of the inequality is equal to

$$(3q-8)^2 + (2q^2 + 2q + 1)(3q - 8) - 6q^3 = -q^2 - 61q + 56$$

which is negative for all $q \ge 32$. This is a contradiction. Therefore, any identifying code of a GQ(q-1, q+1) has size at least 3q-7. For small values of q, we can obtain a better bound using the same inequality. Since the expression $(3q-c)^2 + (2q^2+2q+1)(3q-c) - 6q^3$ is

negative for $(q, c) \in \{(4, 5), (8, 6), (16, 7), (32, 7)\}$, any identifying code of a GQ(q-1, q+1) has size at least

$$\begin{cases} 8 = 3q - 4 & \text{if } q = 4 \\ 19 = 3q - 5 & \text{if } q = 8 \\ 42 = 3q - 6 & \text{if } q = 16 \\ 90 = 3q - 6 & \text{if } q = 32 \end{cases}$$

We can slightly improve the bound for q = 4 using a technical analysis. The details can be found on the arXiv version of our paper: arXiv:1411.5275v1.

5.3.2 Identifying codes in a parabolic quadric which is a GQ(q,q)

Proposition 26. Let q be a prime power. There exists a GQ(q,q) with an identifying code of size $5q - 2 = \Theta(n^{1/3})$ where n is the number of vertices.

Before giving the proof, we will consider a particular construction of a GQ(q, q) and give some structural properties.

Let q be a prime power. Let Q be the set of points of PG(4,q) that satisfy the equation $X_0^2 + X_1X_2 + X_3X_4 = 0$ (Q is a parabolic quadric).

Lemma 27 ([26, 33]). The incidence structure Q(4, q) obtained from the points of Q and lines of Q (i.e. lines of PG(4, q) included in Q) is a generalized quadrangle GQ(q, q). Moreover, the closed neighbourhood of a point A of Q(4, q) is exactly the intersection between a hyperplane π_A (called the tangent hyperplane) and Q.

Lemma 28. Let A and B be two non adjacent points of Q. The common neighbours of A and B are coplanar.

Proof. Let π_A (respectively π_B) be the hyperplane containing all the neighbours of A (resp. B). Since A and B are non adjacent, π_A and π_B are two distinct hyperplanes (of dimension 3). The common neighbours of A and B are all located in the intersection of π_A and π_B which is a plane.

Proof of Proposition 26. We will construct an identifying code for Q(4,q), which is, by Lemma 27, a GQ(q,q). Consider a hyperplane $\pi = PG(3,q)$ intersecting Q(4,q) in a hyperbolic quadric $Q^+(3,q)$ (for example the hyperplane $X_0 = 0$). The hyperbolic quadric is isomorphic to a grid $K_{q+1} \Box K_{q+1}$.

Consider three lines ℓ_0 , ℓ_1 , ℓ_2 of $Q^+(3,q)$ that are pairwise not intersecting. Consider two distinct points $P_1, P_2 \in \ell_2$ and take lines M_1 and M_2 through P_1 and P_2 respectively, both not contained in the $Q^+(3,q)$ and hence not lying in the 3-space π .

The set of 3(q+1) + 2q = 5q + 3 points $S = \ell_0 \cup \ell_1 \cup \ell_2 \cup M_1 \cup M_2$ is an identifying code. Since it contains a whole line, it is a dominating set. A point A on a line N_1 of Sis clearly separated from all the points that are not on N_1 since it is adjacent to all the points of N_1 . The point A is also separated from all the other points of N_1 since they have different projection on any line N_2 of S not intersecting N_1 . Hence all the points of S are separated from all the other points. Consider now a point of $Q^+(3,q) \setminus S$. It has exactly three neighbours on ℓ_0, ℓ_1, ℓ_2 (that are collinear). Two points of $Q^+(3,q) \setminus S$ with the same projections on ℓ_0, ℓ_1, ℓ_2 are necessarily collinear. Hence they have different neighbours on M_1 (if the projection on ℓ_2 is not P_1) or on M_2 (otherwise). Hence any point of $Q^+(3,q) \setminus S$ has a unique set of neighbours.

A point A that is not in $Q^+(3,q)$ has four or five neighbours in $\ell_0 \cup \ell_1 \cup \ell_2 \cup M_1 \cup M_2$. Since A does not lie in $Q^+(3,q)$, the three points on ℓ_0 , ℓ_1 and ℓ_2 are not collinear, hence they span a plane, that is contained in π . The only points of M_1 and M_2 that could be contained in this plane are the intersection of M_1 and M_2 with π which is exactly the points P_1 and P_2 . Since P_1 and P_2 are both in ℓ_2 they cannot be both in the neighbourhood of A. Finally, the neighbours of A in S are not coplanar. Using Lemma 28, A is separated from all the other vertices.

To conclude the proof, note that as before we can remove a point on each line of S and still have an identifying code (remove a point on ℓ_0 , which does not have P_1 or P_2 as a neighbour, and remove its 4 distinct projections on the other lines).

The next proposition gives a lower bound on the size of any identifying code of a GQ(q,q). In particular, the order of our previous construction is optimal. The proof is similar to the proof of Proposition 25.

Proposition 29. Let q be a prime power. Any identifying code of a GQ(q,q) has size at least 3q - 4.

5.3.3 Identifying codes in an elliptic quadric which is a $GQ(q, q^2)$

Proposition 30. Let q be a prime power. There exists a $GQ(q, q^2)$ with an identifying code of size $5q = \Theta(n^{1/4})$ where n is the number of vertices.

Before giving the proof, we will consider a particular construction of a $GQ(q, q^2)$ and give some structural properties.

Let q be a prime power. Let Q be the set of points of PG(5,q) that satisfy the equation $f(X_0, X_1) + X_2X_3 + X_4X_5 = 0$ where $f(X_0, X_1) = dX_0^2 + X_0X_1 + X_1^2$, $d \in \mathbb{F}_q$, is an irreducible binary quadratic form over \mathbb{F}_q (Q is an elliptic quadric).

Lemma 31 ([26, 33]). The incidence structure $Q^{-}(5,q)$ obtained from the $(q^3 + 1)(q + 1)$ points of Q and the $(q^3 + 1)(q^2 + 1)$ lines of Q (i.e. lines of PG(5,q) included in Q) is a generalized quadrangle $GQ(q,q^2)$. Moreover, the closed neighbourhood of a point A of $Q^{-}(5,q)$ is exactly the intersection between a hyperplane π_A (the tangent hyperplane of A) and Q.

Lemma 32. Let A and B be two non adjacent points of Q. The common neighbours of A and B lie in a 3-dimensional space.

Proof. Let π_A (respectively π_B) be the hyperplane containing all the neighbours of A (resp. B). Since A and B are non adjacent, π_A and π_B are two distinct hyperplanes (of dimension 4). The common neighbours of A and B are all located in the intersection of π_A and π_B which is a 3-dimensional space.

Proof of Proposition 30. We will construct an identifying code for $Q^-(5,q)$ which is a generalized quadrangle $GQ(q,q^2)$. Consider a line ℓ_0 of $Q^-(5,q)$, take two distinct 3-spaces π_1 and π_2 of PG(5,q) intersecting each other only in ℓ_0 such that $\pi_i \cap Q^-(5,q) = Q^+(3,q)$. Take two lines ℓ_1, ℓ_2 in $\pi_1 \cap Q^-(5,q)$ such that ℓ_0, ℓ_1 and ℓ_2 are pairwise non-intersecting. Using the geometry, one can always consider two lines ℓ_3, ℓ_4 in $\pi_2 \cap Q^-(5,q)$ such that ℓ_0, ℓ_1 and ℓ_4 are pairwise non-intersecting.

We will prove that the set of 5(q+1) = 5q+5 points of $S = \{\ell_i\}_{i=0,\dots,4}$ is an identifying code. Since S contains a whole line, the set S is a dominating set.

A point A on a line N_1 of S is clearly separated from all the points that are not on N_1 since it is adjacent to all the points of N_1 . The point A is also separated from all the other points of N_1 since they have different projections on any line N_2 of S not intersecting N_1 . Hence all the points of S are separated from all the other points.

Any point of $(\pi_1 \cap Q^-(5,q)) \setminus S$ has exactly three neighbours on ℓ_0, ℓ_1, ℓ_2 (that are collinear). Moreover, two points of $(\pi_1 \cap Q^-(5,q)) \setminus S$ with the same projection on ℓ_0, ℓ_1, ℓ_2 are necessarily collinear. Hence, they have different neighbours on ℓ_3 . It follows that all the points of $(\pi_1 \cap Q^-(5,q)) \setminus S$ are separated from all the other points. Equivalently, also all the points of $(\pi_2 \cap Q^-(5,q)) \setminus S$ are separated from all the other points.

A point $P \in Q^{-}(5,q)$ not in $\pi_1 \cup \pi_2$ has five neighbours in S. Since P does not lie in π_1 , the three points on ℓ_0 , ℓ_1 and ℓ_2 are not collinear, hence they span a plane of π_1 , containing one point of ℓ_0 . Since P does not lie in π_2 , the three points on ℓ_0 , ℓ_3 and ℓ_4 are not collinear, hence they span a plane of π_2 , containing one point of ℓ_0 . Now it is clear that the five neighbours of P span a 4-space. Using Lemma 32 it follows that the point P is separated by S from all other points.

To conclude the proof, note that as before we can remove a point on each line of S and still have an identifying code (remove a point on ℓ_0 and remove its 4 distinct projections on the lines $\ell_1, \ell_2, \ell_3, \ell_4$).

The next proposition gives a lower bound on the size of any identifying code of a $GQ(q, q^2)$. In particular, the order of our previous construction is optimal. The proof is similar to the proof of Proposition 25.

Proposition 33. Let q be a prime power. Any identifying code of a $GQ(q, q^2)$ has size at least 3q + 2.

5.3.4 Identifying codes in a Hermitian variety which is a $GQ(q^2, q)$

Proposition 34. Let q be a prime power. There exists a $GQ(q^2, q)$ with an identifying code of size $5q^2 - 2 = \Theta(n^{2/5})$ where n is the number of vertices.

Before giving the proof, we will consider a particular construction of a $GQ(q^2, q)$ and give some structural properties.

Let q be a prime power. Let H be the set of points of $PG(3,q^2)$ that satisfy the equation $X_0^{q+1} + X_1^{q+1} + X_2^{q+1} + X_3^{q+1} = 0$ (H is a Hermitian variety).

Lemma 35 ([26, 33]). The incidence structure $H(3, q^2)$ obtained from the $(q^3 + 1)(q^2 + 1)$ points of H and the $(q^3 + 1)(q + 1)$ lines of H (i.e. lines of $PG(3, q^2)$ included in H) is

a generalized quadrangle $GQ(q^2, q)$. Moreover, the closed neighbourhood of a point A of $H(3, q^2)$ is exactly the intersection between a plane π_A (the tangent hyperplane of A) and H.

It is well known that the dual of $H(3,q^2)$ is $Q^{-}(5,q)$, see [33, 3.2.3].

Lemma 36. Let A and B be two non adjacent points of H. The common neighbours of A and B lie on a line.

Proof. Let π_A (respectively π_B) be the hyperplane containing all the neighbours of A (resp. B). Since A and B are non adjacent, π_A and π_B are two distinct planes. The common neighbours of A and B are all located in the intersection of π_A and π_B which is a line.

Proof of Proposition 34. We will construct an identifying code for $H(3, q^2)$ which is a generalized quadrangle $GQ(q^2, q)$.

Consider three disjoint lines L_0, L_1, L_2 , two distinct points $P_1, P_2 \in L_0$ and two lines M_1 and M_2 containing P_1 and P_2 respectively, and not intersecting L_1 or L_2 . The set $\mathcal{S} = L_0 \cup L_1 \cup L_2 \cup M_1 \cup M_2$ of $|\mathcal{S}| = 5q^2 + 3$ points will be an identifying code.

Since \mathcal{S} contains a whole line, the set \mathcal{S} is a dominating set.

A point A on a line N_1 of \mathcal{S} is clearly separated from all the points that are not on N_1 since it is adjacent to all the points of N_1 . The point A is also separated from all the other points of N_1 since they have different projections on any line N_2 of \mathcal{S} not intersecting N_1 . Hence all the points of \mathcal{S} are separated from all the other points.

If two points R and Q have the same neighbourhood on $\{L_0, L_1, L_2\}$, then this neighbourhood consists of collinear points by Lemma 36. If the line containing these points also contains P_1 , then the projections of R and Q on the line M_2 are different. If the line would contain P_2 , then the projections of R and Q on the line M_1 are different. Hence, S is a separating set.

To conclude the proof, note that as before we can remove a point on each line of S and still have an identifying code (remove a point on L_1 , that is not a neighbour of P_1 or P_2 , and remove its 4 distinct projections on the lines L_0, L_2, M_1, M_2).

The next proposition gives a lower bound on the size of any identifying code of a $GQ(q^2, q)$. In particular, the order of our previous construction is optimal. The proof is similar to the proof of Proposition 25.

Proposition 37. Let q be a prime power. Any identifying code of a $GQ(q^2, q)$ has size at least $2q^2 - 2$.

6 Conclusion and Perspectives

We provide identifying codes for several vertex-transitive families of graphs which have size of the same order as the fractional value. Since the graphs considered have diameter 2, our results can be extended to locating-dominating sets and to metric dimension, providing new constructions of optimal order for such sets in some families of strongly regular graphs.

Paley graphs are an example of a family of graphs for which the optimal order for the size of identifying codes is at a logarithmic factor of the fractional value. However, the fractional value is bounded by a constant. It would be interesting to exhibit a family of graphs for which the optimal values of integer and fractional identifying codes do not have the same order and such that the fractional value is not bounded by a constant.

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