# Inverse Perron values and connectivity of a uniform hypergraph 

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#### Abstract

In this paper, we show that a uniform hypergraph $\mathcal{G}$ is connected if and only if one of its inverse Perron values is larger than 0 . We give some bounds on the bipartition width, isoperimetric number and eccentricities of $\mathcal{G}$ in terms of inverse Perron values. By using the inverse Perron values, we give an estimation of the edge connectivity of a 2-design, and determine the explicit edge connectivity of a symmetric design. Moreover, relations between the inverse Perron values and resistance distance of a connected graph are presented.


Mathematics Subject Classifications: 05C50, 05C65, 05C40, 05C12, 15A69

## 1 Introduction

Let $V(\mathcal{G})$ and $E(\mathcal{G})$ denote the vertex set and edge set of a hypergraph $\mathcal{G}$, respectively. $\mathcal{G}$ is $k$-uniform if $|e|=k$ for each $e \in E(\mathcal{G})$. In particular, 2-uniform hypergraphs are usual graphs. For $i \in V(\mathcal{G}), E_{i}(\mathcal{G})$ denotes the set of edges containing $i$, and $d_{i}=\left|E_{i}(\mathcal{G})\right|$

[^0]denotes the degree of $i$. The adjacency tensor [8] of a $k$-uniform hypergraph $\mathcal{G}$, denoted by $\mathcal{A}_{\mathcal{G}}$, is an order $k$ dimension $|V(\mathcal{G})|$ tensor with entries
\[

a_{i_{1} i_{2} \cdots i_{k}}= $$
\begin{cases}\frac{1}{(k-1)!}, & \text { if }\left\{i_{1}, i_{2}, \ldots, i_{k}\right\} \in E(\mathcal{G}), \\ 0, & \text { otherwise. }\end{cases}
$$
\]

The Laplacian tensor [27] of $\mathcal{G}$ is $\mathcal{L}_{\mathcal{G}}=\mathcal{D}_{\mathcal{G}}-\mathcal{A}_{\mathcal{G}}$, where $\mathcal{D}_{\mathcal{G}}$ is the diagonal tensor of vertex degrees of $\mathcal{G}$. Recently, the research on spectral hypergraph theory via tensors has attracted much attention [7-10,14,19,24]. The spectral properties of the Laplacian tensor of hypergraphs are studied in [13,25,27,29,35].

For an order $k$ dimension $n$ tensor $\mathcal{T}=\left(t_{i_{1} i_{2} \cdots i_{k}}\right)$, let $\mathcal{T} \mathbf{x}^{k}=\sum_{i_{1}, \ldots, i_{k}=1}^{n} t_{i_{1} i_{2} \cdots i_{k}} x_{i_{1}} \cdots x_{i_{k}}$. The algebraic connectivity of a graph plays important roles in spectral graph theory [11]. Analogue to the algebraic connectivity of a graph, Qi [27] defined the analytic connectivity of a $k$-uniform hypergraph $\mathcal{G}$ as

$$
\alpha(\mathcal{G})=\min _{j=1, \ldots, n} \min \left\{\mathcal{L}_{\mathcal{G}} \mathbf{x}^{k}: \mathbf{x} \in \mathbb{R}_{+}^{n}, \sum_{i=1}^{n} x_{i}^{k}=1, x_{j}=0\right\},
$$

where $n=|V(G)|, \mathbb{R}_{+}^{n}$ denotes the set of nonnegative vectors of dimension $n$. Qi proved that $\mathcal{G}$ is connected if and only if $\alpha(\mathcal{G})>0$. In [20], some bounds on $\alpha(\mathcal{G})$ were presented in terms of degree, vertex connectivity, diameter and isoperimetric number. A feasible trust region algorithm of $\alpha(\mathcal{G})$ was given in [9].

For any vertex $j$ of a $k$-uniform hypergraph $\mathcal{G}$, we define the inverse Perron value of $j$ as

$$
\alpha_{j}(\mathcal{G})=\min \left\{\mathcal{L}_{\mathcal{G}} \mathbf{x}^{k}: \mathbf{x} \in \mathbb{R}_{+}^{n}, \sum_{i=1}^{n} x_{i}^{k}=1, x_{j}=0\right\} .
$$

Clearly, the analytic connectivity $\alpha(\mathcal{G})=\min _{j \in V(\mathcal{G})} \alpha_{j}(\mathcal{G})$ is the minimum inverse Perron value. For a connected graph $G, \alpha_{j}(G)$ is the minimum eigenvalue of $\mathcal{L}_{G}(j)$, where $\mathcal{L}_{G}(j)$ is the principal submatrix of $\mathcal{L}_{G}$ obtained by deleting the row and column corresponding to $j$. $\mathcal{L}_{G}(j)$ is nonsingular and its inverse $\mathcal{L}_{G}(j)^{-1}$ is a nonnegative matrix [16]. It is easy to see that $\alpha_{j}^{-1}(G)$ is the spectral radius of $\mathcal{L}_{G}(j)^{-1}$, which is called the Perron value of $G$. All inverse Perron values of a tree $T$ can determine the algebraic connectivity of $T$ $[1,15]$.

The resistance distance $[17,34]$ is a distance function on graphs. For two vertices $i, j$ in a connected graph $G$, the resistance distance between $i$ and $j$, denoted by $r_{i j}(G)$, is defined to be the effective resistance between them when unit resistors are placed on every edge of $G$. The Kirchhoff index $[17,33]$ of $G$, denoted by $\operatorname{Kf}(G)$, is defined as the sum of resistance distances between all pairs of vertices in $G$, i.e., $K f(G)=\sum_{\{i, j\} \subseteq V(G)} r_{i j}(G) . K f(G)$ is a global robustness index. The resistance distance and Kirchhoff index in graphs have been investigated extensively in mathematical and chemical literatures [3,4,6,12,23,31,36].

This paper is organized as follows. In Section 2, some auxiliary lemmas are introduced. In Section 3, we show that a uniform hypergraph $\mathcal{G}$ is connected if and only if one of its inverse Perron values is larger than 0 , and some inequalities among the inverse Perron values, bipartition width, isoperimetric number and eccentricities of $\mathcal{G}$ are established. Partial results improve some bounds in [20, 27]. We also use the inverse Perron values to estimate the edge connectivity of 2-designs. In Section 4, some inequalities among the inverse Perron values, resistance distance and Kirchhoff index of a connected graph are presented.

## 2 Preliminaries

For a positive integer $n$, let $[n]=\{1,2, \ldots, n\}$. An order $m$ dimension $n$ tensor $\mathcal{T}=$ $\left(t_{i_{1} \cdots i_{m}}\right)$ consists of $n^{m}$ entries, where $i_{j} \in[n], j \in[m]$. When $m=2, T$ is an $n \times n$ matrix. Let $\mathbb{R}^{[m, n]}$ denote the set of order $m$ dimension $n$ real tensors, and let $\mathbb{R}_{+}^{n}$ denote the cone of nonnegative vectors in $\mathbb{R}^{n}$. For $\mathcal{T}=\left(t_{i_{1} i_{2} \cdots i_{m}}\right) \in \mathbb{R}^{[m, n]}$ and $\mathbf{x}=\left(x_{1}, \ldots, x_{n}\right)^{\mathrm{T}} \in \mathbb{R}^{n}$, let $\mathcal{T} \mathrm{x}^{m-1} \in \mathbb{R}^{n}$ denote the vector whose $i$-th component is

$$
\left(\mathcal{T} \mathbf{x}^{m-1}\right)_{i}=\sum_{i_{2}, i_{3}, \ldots, i_{m}=1}^{n} t_{i i_{2} \cdots i_{m}} x_{i_{2}} x_{i_{3}} \cdots x_{i_{m}},
$$

and let $\mathbf{x}^{[m-1]}=\left(x_{1}^{m-1}, \ldots, x_{n}^{m-1}\right)^{\mathrm{T}}$. In 2005, Qi [26] and Lim [21] proposed the concept of eigenvalues of tensors, independently. For $\mathcal{T}=\left(t_{i_{1} i_{2} \cdots i_{m}}\right) \in \mathbb{R}^{[m, n]}$, if there exist a number $\lambda \in \mathbb{R}$ and a nonzero vector $\mathbf{x}=\left(x_{1}, \ldots, x_{n}\right)^{\mathrm{T}} \in \mathbb{R}^{n}$ such that $\mathcal{T} \mathbf{x}^{m-1}=\lambda \mathbf{x}^{[m-1]}$, then $\lambda$ is called an $H$-eigenvalue of $\mathcal{T}$, $\mathbf{x}$ is called an $H$-eigenvector of $\mathcal{T}$ corresponding to $\lambda$.

For a vertex $j$ of a $k$-uniform hypergraph $\mathcal{G}$, let $\mathcal{L}_{\mathcal{G}}(j) \in \mathbb{R}^{[k, n-1]}$ denote the principal subtensor of $\mathcal{L}_{\mathcal{G}} \in \mathbb{R}^{[k, n]}$ with index set $V(\mathcal{G}) \backslash\{j\}$. By Lemma 2.3 in [32], we know that $\alpha_{j}(\mathcal{G})$ is the smallest H -eigenvalue of $\mathcal{L}_{\mathcal{G}}(j)$ for any $j \in V(\mathcal{G})$.

A path $\mathcal{P}$ of a uniform hypergraph $\mathcal{G}$ is an alternating sequence of vertices and edges $v_{0} e_{1} v_{1} e_{2} \cdots v_{l-1} e_{l} v_{l}$, where $v_{0}, \ldots, v_{l}$ are distinct vertices of $\mathcal{G}, e_{1}, \ldots, e_{l}$ are distinct edges of $\mathcal{G}$ and $v_{i-1}, v_{i} \in e_{i}$, for $i=1, \ldots, l$. The number of edges in $\mathcal{P}$ is the length of $\mathcal{P}$. For all $u, v \in V(\mathcal{G})$, if there exists a path starting at $u$ and terminating at $v$, then $\mathcal{G}$ is said to be connected [5].

Lemma 1. [27] The uniform hypergraph $\mathcal{G}$ is connected if and only if $\alpha(\mathcal{G})>0$.
Let $\mathcal{G}$ be a $k$-uniform hypergraph, $S \neq \emptyset$ be a proper subset of $V(\mathcal{G})$. Denote $\bar{S}=$ $V(\mathcal{G}) \backslash S$. The edge-cut set $E(S, \bar{S})$ consists of edges whose vertices are in both $S$ and $\bar{S}$. The minimum cardinality of such an edge-cut set is called edge connectivity of $\mathcal{G}$, denote by $e(\mathcal{G})$.

Lemma 2. [27] Let $\mathcal{G}$ be a $k$-uniform hypergraph with $n$ vertices. Then

$$
e(\mathcal{G}) \geqslant \frac{n}{k} \alpha(\mathcal{G}) .
$$

The $\{1\}$-inverse of a matrix $M$ is a matrix $X$ such that $M X M=M$. Let $M^{(1)}$ denote any $\{1\}$-inverse of $M$, and let $(M)_{i j}$ denote the $(i, j)$-entry of $M$.
Lemma 3. [2, 34] Let $G$ be a connected graph. Then

$$
r_{i j}(G)=\left(\mathcal{L}_{G}^{(1)}\right)_{i i}+\left(\mathcal{L}_{G}^{(1)}\right)_{j j}-\left(\mathcal{L}_{G}^{(1)}\right)_{i j}-\left(\mathcal{L}_{G}^{(1)}\right)_{j i} .
$$

Let $\operatorname{tr}(A)$ denote the trace of the square matrix $A$, and let $\mathbf{e}$ denote an all-ones column vector.
Lemma 4. [30] Let $G$ be a connected graph of order n. Then

$$
K f(G)=n \operatorname{tr}\left(\mathcal{L}_{G}^{(1)}\right)-\mathbf{e}^{\top} \mathcal{L}_{G}^{(1)} \mathbf{e}
$$

Lemma 5. [2] Let $G$ be a connected graph with $n$ vertices and $i \in[n]$. Let $\mathcal{L}_{G}=$ $\left(\begin{array}{ccc}L_{1} & \mathbf{x} & L_{2} \\ \mathbf{x}^{\mathrm{T}} & d_{i} & \mathbf{y} \\ L_{2}{ }^{\mathrm{T}} & \mathbf{y}^{\mathrm{T}} & L_{3}\end{array}\right)$, where $L_{1} \in \mathbb{R}^{(i-1) \times(i-1)}, L_{3} \in \mathbb{R}^{(n-i) \times(n-i)}, \mathbf{x} \in \mathbb{R}^{i-1}, \mathbf{y}^{\mathrm{T}} \in \mathbb{R}^{n-i}$. Suppose $\mathcal{L}_{G}(i)^{-1}=\left(\begin{array}{cc}\widetilde{L_{1}} & \widetilde{L_{2}} \\ \widetilde{L_{2}} & \widetilde{L_{3}}\end{array}\right)$, where $\widetilde{L_{1}} \in \mathbb{R}^{(i-1) \times(i-1)}$, $\widetilde{L_{3}} \in \mathbb{R}^{(n-i) \times(n-i)}$. Then $\left(\begin{array}{ccc}\widetilde{L_{1}} & \mathbf{0} & \widetilde{L_{2}} \\ \mathbf{0} & 0 & \mathbf{0} \\ \widetilde{L_{2}} & \mathbf{0} & \widetilde{L_{3}}\end{array}\right)$ is a symmetric $\{1\}$-inverse of $\mathcal{L}_{G}$.

## 3 Inverse Perron values of uniform hypergraphs

In the following theorem, the relationship between inverse Perron values and connectivity of a hypergraph is presented.
Theorem 6. Let $\mathcal{G}$ be a $k$-uniform hypergraph. Then the following statements are equivalent:
(1) $\mathcal{G}$ is connected.
(2) $\alpha_{j}(\mathcal{G})>0$ for all $j \in V(\mathcal{G})$.
(3) $\alpha_{j}(\mathcal{G})>0$ for some $j \in V(\mathcal{G})$.

Proof. $(1) \Longrightarrow(2)$. If $\mathcal{G}$ is connected, then by Lemma 1, we know that $\alpha_{j}(\mathcal{G})>0$ for all $j \in V(\mathcal{G})$.
$(2) \Longrightarrow(3)$. Obviously.
$(3) \Longrightarrow(1)$. Suppose that $\mathcal{G}$ is disconnected. For any $j \in V(\mathcal{G})$, let $\mathcal{G}_{1}$ be the component of $\mathcal{G}$ such that $j \notin V\left(\mathcal{G}_{1}\right)$. Let $\mathbf{x}=\left(x_{1}, \ldots, x_{|V(\mathcal{G})|}\right)^{\mathrm{T}}$ be the vector satisfying

$$
x_{i}= \begin{cases}\left|V\left(\mathcal{G}_{1}\right)\right|^{-\frac{1}{k}}, & \text { if } i \in V\left(\mathcal{G}_{1}\right) \\ 0, & \text { otherwise }\end{cases}
$$

Clearly, we have $\sum_{i=1}^{n} x_{i}^{k}=1$. Then we have $0 \leqslant \alpha_{j}(\mathcal{G}) \leqslant \mathcal{L}_{\mathcal{G}} \mathbf{x}^{k}=0$ for any $j \in V(\mathcal{G})$, a contradiction to (3). Hence $\mathcal{G}$ is connected if (3) holds.

The bipartition width of a hypergraph $\mathcal{G}$ is defined as [18, 28]

$$
\operatorname{bw}(\mathcal{G})=\min \left\{|E(S, \bar{S})|: S \subseteq V(\mathcal{G}),|S|=\left\lfloor\frac{n}{2}\right\rfloor\right\}
$$

where $\left\lfloor\frac{n}{2}\right\rfloor$ denotes the maximum integer not larger than $\frac{n}{2}$. The computation of $\mathrm{bw}(\mathcal{G})$ is very difficult even for the graph case. In [22], Mohar and Poljak used the algebraic connectivity to obtain a lower bound on the bipartition width of a graph. In the following theorem, we use the inverse Perron values to obtain a lower bound on the bipartition width of a uniform hypergraph.

Theorem 7. Let $\mathcal{G}$ be a $k$-uniform hypergraph with $n$ vertices. Then

$$
\operatorname{bw}(\mathcal{G}) \geqslant \frac{n+(-1)^{n}}{k(n+1)} \sum_{j=1}^{n} \alpha_{j}(\mathcal{G})
$$

Proof. Suppose that $S_{0} \subseteq V(\mathcal{G})$ satisfying $\left|S_{0}\right|=\left\lfloor\frac{n}{2}\right\rfloor$ and $\left|E\left(S_{0}, \overline{S_{0}}\right)\right|=\operatorname{bw}(\mathcal{G})$. Let $\mathbf{x}=\left(x_{1}, \ldots, x_{n}\right)^{\mathrm{T}}$ be the vector satisfying

$$
x_{i}= \begin{cases}\left|S_{0}\right|^{-\frac{1}{k}}, & i \in S_{0} \\ 0, & i \in \overline{S_{0}}\end{cases}
$$

Then $\sum_{i=1}^{n} x_{i}^{k}=1$. For $j \in \overline{S_{0}}$, we get

$$
\begin{align*}
\alpha_{j}(\mathcal{G}) & \leqslant \mathcal{L}_{\mathcal{G}} \mathbf{x}^{k}=\sum_{\left\{i_{1}, \ldots, i_{k}\right\} \in E(\mathcal{G})}\left(x_{i_{1}}^{k}+\cdots+x_{i_{k}}^{k}-k x_{i_{1}} \cdots x_{i_{k}}\right) \\
\alpha_{j}(\mathcal{G}) & \leqslant \sum_{\left\{i_{1}, \ldots, i_{k}\right\} \in E\left(S_{0}, \overline{S_{0}}\right)}\left(x_{i_{1}}^{k}+\cdots+x_{i_{k}}^{k}-k x_{i_{1}} \cdots x_{i_{k}}\right) \\
& =\frac{1}{\left|S_{0}\right|} \sum_{e \in E\left(S_{0}, \overline{S_{0}}\right)}\left|e \cap S_{0}\right|=\frac{t\left(S_{0}\right) \mathrm{bw}(\mathcal{G})}{\left|S_{0}\right|} \tag{1}
\end{align*}
$$

where $t\left(S_{0}\right)=\frac{1}{\mid E\left(S_{0}, \overline{S_{0}}\right)} \sum_{e \in E\left(S_{0}, \overline{S_{0}}\right)}\left|e \cap S_{0}\right|$.
Similarly, for $j \in S_{0}$, we obtain

$$
\begin{equation*}
\alpha_{j}(\mathcal{G}) \leqslant \frac{\left(k-t\left(S_{0}\right)\right) \operatorname{bw}(\mathcal{G})}{\left|\overline{S_{0}}\right|} . \tag{2}
\end{equation*}
$$

Combining (1) and (2), we get

$$
\sum_{j=1}^{n} \alpha_{j}(\mathcal{G})=\sum_{j \in S_{0}} \alpha_{j}(\mathcal{G})+\sum_{j \in \overline{S_{0}}} \alpha_{j}(\mathcal{G}) \leqslant \frac{\left|S_{0}\right|\left(k-t\left(S_{0}\right)\right) \operatorname{bw}(\mathcal{G})}{\left|\overline{S_{0}}\right|}+\frac{\left|\overline{S_{0}}\right| t\left(S_{0}\right) \operatorname{bw}(\mathcal{G})}{\left|S_{0}\right|}
$$

If $n$ is even, then $\left|S_{0}\right|=\left|\overline{S_{0}}\right|$ and $\operatorname{bw}(\mathcal{G}) \geqslant \frac{1}{k} \sum_{j=1}^{n} \alpha_{j}(\mathcal{G})$. If $n$ is odd, then $\left|S_{0}\right|=\left|\overline{S_{0}}\right|-1=$ $\frac{n-1}{2}$ and

$$
\sum_{j=1}^{n} \alpha_{j}(\mathcal{G}) \leqslant k \frac{\mid \overline{\left|\overline{S_{0}}\right|}}{\left|S_{0}\right|} \operatorname{bw}(\mathcal{G})=\frac{k(n+1) \operatorname{bw}(\mathcal{G})}{n-1}, \quad \operatorname{bw}(\mathcal{G}) \geqslant \frac{n-1}{k(n+1)} \sum_{j=1}^{n} \alpha_{j}(\mathcal{G})
$$

The isoperimetric number of a $k$-uniform hypergraph $\mathcal{G}$ is defined as

$$
i(\mathcal{G})=\min \left\{\frac{|E(S, \bar{S})|}{|S|}: S \subseteq V(\mathcal{G}), 0<|S| \leqslant \frac{|V(\mathcal{G})|}{2}\right\} .
$$

Let $\beta(\mathcal{G})=\max _{j \in V(\mathcal{G})} \alpha_{j}(\mathcal{G})$ denote the maximum inverse Perron value of $\mathcal{G}$. In [20], it was shown that $i(\mathcal{G}) \geqslant \frac{2}{k} \alpha(\mathcal{G})$. We improve it as follows.

Theorem 8. Let $\mathcal{G}$ be a $k$-uniform hypergraph. Then

$$
i(\mathcal{G}) \geqslant \frac{\alpha(\mathcal{G})+\beta(\mathcal{G})}{k} .
$$

Proof. Suppose that $S_{1} \subseteq V(\mathcal{G})$ satisfying $0<\left|S_{1}\right| \leqslant \frac{|V(\mathcal{G})|}{2}$ and $\frac{\left|E\left(S_{1}, \overline{S_{1}}\right)\right|}{\left|S_{1}\right|}=i(\mathcal{G})$. Let $\mathbf{x}=\left(x_{1}, \ldots, x_{n}\right)^{\mathrm{T}}$ be the vector satisfying

$$
x_{i}= \begin{cases}\left|S_{1}\right|^{-\frac{1}{k}}, & i \in S_{1}, \\ 0, & i \in \overline{S_{1}} .\end{cases}
$$

Then $\sum_{i=1}^{n} x_{i}^{k}=1$. For $j \in \overline{S_{1}}$, we obtain

$$
\begin{equation*}
\alpha_{j}(\mathcal{G}) \leqslant \mathcal{L}_{\mathcal{G}} \mathbf{x}^{k}=\frac{t\left(S_{1}\right)\left|E\left(S_{1}, \overline{S_{1}}\right)\right|}{\left|S_{1}\right|}=t\left(S_{1}\right) i(\mathcal{G}), \tag{3}
\end{equation*}
$$

where $t\left(S_{1}\right)=\frac{1}{\left|E\left(S_{1}, \overline{S_{1}}\right)\right|} \sum_{e \in E\left(S_{1}, \overline{S_{1}}\right)}\left|e \cap S_{1}\right|$.
Similarly, for $j \in S_{1}$, we get

$$
\begin{equation*}
\alpha_{j}(\mathcal{G}) \leqslant \frac{\left(k-t\left(S_{1}\right)\right)\left|E\left(S_{1}, \overline{S_{1}}\right)\right|}{\left|\overline{S_{1}}\right|} \leqslant\left(k-t\left(S_{1}\right)\right) i(\mathcal{G}) . \tag{4}
\end{equation*}
$$

Let $\alpha_{s}(\mathcal{G})=\beta(\mathcal{G})$. If $s \in \overline{S_{1}}$, by (3), we get

$$
\beta(\mathcal{G})=\alpha_{s}(\mathcal{G}) \leqslant t\left(S_{1}\right) i(\mathcal{G}) .
$$

From (4), we have

$$
\alpha(\mathcal{G})=\min _{j \in V(\mathcal{G})} \alpha_{j}(\mathcal{G}) \leqslant \min _{j \in S_{1}} \alpha_{j}(\mathcal{G}) \leqslant\left(k-t\left(S_{1}\right)\right) i(\mathcal{G}) .
$$

Then

$$
\alpha(\mathcal{G})+\beta(\mathcal{G}) \leqslant t\left(S_{1}\right) i(\mathcal{G})+\left(k-t\left(S_{1}\right)\right) i(\mathcal{G})=k i(\mathcal{G}) .
$$

Similarly, if $s \in S_{1}$, we can also obtain $\alpha(\mathcal{G})+\beta(\mathcal{G}) \leqslant k i(\mathcal{G})$.
From the above discussion, we get $i(\mathcal{G}) \geqslant \frac{\alpha(\mathcal{G})+\beta(\mathcal{G})}{k}$.
The distance $d(u, v)$ between two distinct vertices $u$ and $v$ of $\mathcal{G}$ is the length of the shortest path connecting them. The eccentricity of a vertex $v$ is $\operatorname{ecc}(v)=\max \{d(u, v)$ : $u \in V(\mathcal{G})\}$. The diameter and radius of $\mathcal{G}$ are defined as $\operatorname{diam}(\mathcal{G})=\max _{v \in V(\mathcal{G})} \operatorname{ecc}(v)$ and $\operatorname{rad}(\mathcal{G})=\min _{v \in V(\mathcal{G})} \operatorname{ecc}(v)$, respectively.

Theorem 9. Let $\mathcal{G}$ be a connected $k$-uniform hypergraph with $n$ vertices. Then

$$
\operatorname{ecc}(j) \geqslant \frac{k}{2(k-1)(n-1) \alpha_{j}(\mathcal{G})}, j \in V(\mathcal{G}) .
$$

Proof. For $j \in V(\mathcal{G})$, let $\mathbf{x}=\left(x_{1}, \ldots, x_{n}\right)^{\mathrm{T}} \in \mathbb{R}_{+}^{n}$ satisfying $x_{j}=0, \sum_{i=1}^{n} x_{i}^{k}=1$ and $\alpha_{j}(\mathcal{G})=\mathcal{L}_{\mathcal{G}} \mathbf{x}^{k}$. Then

$$
\begin{equation*}
\alpha_{j}(\mathcal{G})=\mathcal{L}_{\mathcal{G}} \mathbf{x}^{k}=\sum_{\left\{i_{1}, \ldots, i_{k}\right\} \in E(\mathcal{G})}\left(x_{i_{1}}^{k}+\cdots+x_{i_{k}}^{k}-k x_{i_{1}} \cdots x_{i_{k}}\right) . \tag{5}
\end{equation*}
$$

From AM-GM inequality, it yields that

$$
\begin{equation*}
\sum_{1 \leqslant s<t \leqslant k} x_{i_{s}}^{\frac{k}{2}} x_{i_{t}}^{\frac{k}{2}} \geqslant \frac{k(k-1)}{2}\left(\prod_{1 \leqslant s<t \leqslant k} x_{i_{s}}^{\frac{k}{2}} x_{i_{t}}^{\frac{k}{2}}\right)^{\frac{2}{k(k-1)}}=\frac{k(k-1)}{2} x_{i_{1}} \cdots x_{i_{k}} \tag{6}
\end{equation*}
$$

By (5) and (6), we have

$$
\begin{align*}
\alpha_{j}(\mathcal{G}) & \geqslant \sum_{\left\{i_{1}, \ldots, i_{k}\right\} \in E(\mathcal{G})}\left(x_{i_{1}}^{k}+\cdots+x_{i_{k}}^{k}-\frac{2}{k-1} \sum_{1 \leqslant s<t \leqslant k} x_{i_{s}}^{\frac{k}{2}} x_{i_{t}}^{\frac{k}{2}}\right) \\
& =\frac{1}{k-1} \sum_{\left\{i_{1}, \ldots, i_{k}\right\} \in E(\mathcal{G})} \sum_{1 \leqslant s<t \leqslant k}\left(x_{i_{s}}^{\frac{k}{2}}-x_{i_{t}}^{\frac{k}{2}}\right)^{2} \\
& =\frac{1}{k-1} \sum_{e \in E(\mathcal{G})} \sum_{s, t \in e}\left(x_{s}^{\frac{k}{2}}-x_{t}^{\frac{k}{2}}\right)^{2} . \tag{7}
\end{align*}
$$

Let $v_{0} \in\left\{i \mid x_{i}=\max _{p \in V(\mathcal{G})} x_{p}\right\}$. Let $\mathcal{P}=v_{0} e_{1} v_{1} e_{2} \cdots v_{l-1} e_{l} v_{l}$ be the shortest path from vertex $v_{0}$ to vertex $v_{l}=j$. Then $x_{v_{0}}^{k} \geqslant \frac{1}{n-1}, x_{v_{l}}=0$ and

$$
\sum_{e \in E(\mathcal{G})} \sum_{s, t \in e}\left(x_{s}^{\frac{k}{2}}-x_{t}^{\frac{k}{2}}\right)^{2} \geqslant \sum_{e \in E(\mathcal{P})} \sum_{s, t \in e}\left(x_{s}^{\frac{k}{2}}-x_{t}^{\frac{k}{2}}\right)^{2}
$$

$$
\begin{aligned}
& \geqslant \sum_{i=1}^{l}\left(\left(x_{v_{i-1}}^{\frac{k}{2}}-x_{v_{i}}^{\frac{k}{2}}\right)^{2}+\sum_{u_{j} \in e_{i} \backslash\left\{v_{i-1}, v_{i}\right\}}\left(\left(x_{v_{i-1}}^{\frac{k}{2}}-x_{u_{j}}^{\frac{k}{2}}\right)^{2}+\left(x_{u_{j}}^{\frac{k}{2}}-x_{v_{i}}^{\frac{k}{2}}\right)^{2}\right)\right) \\
& \geqslant \sum_{i=1}^{l}\left(\left(x_{v_{i-1}}^{\frac{k}{2}}-x_{v_{i}}^{\frac{k}{2}}\right)^{2}+\frac{1}{2} \sum_{u_{j} \in e_{i} \backslash\left\{v_{i-1}, v_{i}\right\}}\left(x_{v_{i-1}}^{\frac{k}{2}}-x_{u_{j}}^{\frac{k}{2}}+x_{u_{j}}^{\frac{k}{2}}-x_{v_{i}}^{\frac{k}{2}}\right)^{2}\right) \\
& =\sum_{i=1}^{l}\left(\left(x_{v_{i-1}}^{\frac{k}{2}}-x_{v_{i}}^{\frac{k}{2}}\right)^{2}+\frac{k-2}{2}\left(x_{v_{i-1}}^{\frac{k}{2}}-x_{v_{i}}^{\frac{k}{2}}\right)^{2}\right) \\
& =\frac{k}{2} \sum_{i=1}^{l}\left(x_{v_{i-1}}^{\frac{k}{2}}-x_{v_{i}}^{\frac{k}{2}}\right)^{2} .
\end{aligned}
$$

By Cauchy-Schwarz inequality, we obtain

$$
\begin{align*}
& \sum_{e \in E(\mathcal{G})} \sum_{s, t \in e}\left(x_{s}^{\frac{k}{2}}-x_{t}^{\frac{k}{2}}\right)^{2} \geqslant \frac{k}{2} \sum_{i=1}^{l}\left(x_{v_{i-1}}^{\frac{k}{2}}-x_{v_{i}}^{\frac{k}{2}}\right)^{2} \geqslant \frac{k}{2 l}\left(\sum_{i=1}^{l}\left(x_{v_{i-1}}^{\frac{k}{2}}-x_{v_{i}}^{\frac{k}{2}}\right)^{2}\right. \\
= & \frac{k}{2 l}\left(x_{v_{0}}^{\frac{k}{2}}-x_{v_{l}}^{\frac{k}{2}}\right)^{2} \geqslant \frac{k}{2 \operatorname{ecc}(j)}\left(x_{v_{0}}^{\frac{k}{2}}-x_{v_{l}}^{\frac{k}{2}}\right)^{2} \geqslant \frac{k}{2(n-1) \operatorname{ecc}(j)} \tag{8}
\end{align*}
$$

From (7) and (8), it yields that

$$
\alpha_{j}(\mathcal{G}) \geqslant \frac{k}{2(k-1)(n-1) \operatorname{ecc}(j)}, \quad \operatorname{ecc}(j) \geqslant \frac{k}{2(k-1)(n-1) \alpha_{j}(\mathcal{G})}
$$

For a connected $k$-uniform hypergraph $\mathcal{G}$ with $n$ vertices, [20] showed that

$$
\operatorname{diam}(\mathcal{G}) \geqslant \frac{4}{n^{2}(k-1) \alpha(\mathcal{G})}
$$

By Theorem 9, we obtain the following improved result.
Corollary 10. Let $\mathcal{G}$ be a connected $k$-uniform hypergraph with $n$ vertices. Then

$$
\operatorname{diam}(\mathcal{G}) \geqslant \frac{k}{2(k-1)(n-1) \alpha(\mathcal{G})}, \quad \operatorname{rad}(\mathcal{G}) \geqslant \frac{k}{2(k-1)(n-1) \beta(\mathcal{G})}
$$

In [27], it was shown that $\alpha(\mathcal{G}) \leqslant \delta$, where $\delta$ is the minimum degree of $\mathcal{G}$. We improve it as follows.

Theorem 11. Let $\mathcal{G}$ be a $k$-uniform hypergraph with $n$ vertices. Then

$$
\alpha_{j}(\mathcal{G}) \leqslant \frac{(k-1) d_{j}}{n-1}, j \in V(\mathcal{G})
$$

Proof. For $j \in V(\mathcal{G})$, let $\mathbf{x}=\left(x_{1}, \ldots, x_{n}\right)^{\mathrm{T}}$ be the vector satisfying

$$
x_{i}= \begin{cases}(n-1)^{-\frac{1}{k}}, & i \neq j, \\ 0, & i=j\end{cases}
$$

Then $\sum_{i=1}^{n} x_{i}^{k}=1$, and we get

$$
\begin{aligned}
\alpha_{j}(\mathcal{G}) & \leqslant \mathcal{L}_{\mathcal{G}} \mathbf{x}^{k}=\sum_{\left\{i_{1}, \ldots, i_{k}\right\} \in E(\mathcal{G})}\left(x_{i_{1}}^{k}+\cdots+x_{i_{k}}^{k}-k x_{i_{1}} \cdots x_{i_{k}}\right) \\
& =\sum_{\left\{i_{1}, \ldots, i_{k}\right\} \in E_{j}(\mathcal{G})}\left(x_{i_{1}}^{k}+\cdots+x_{i_{k}}^{k}\right)=\frac{(k-1) d_{j}}{n-1},
\end{aligned}
$$

where $E_{j}(\mathcal{G})$ denotes the set of edges containing $j$.
By Theorem 11, we obtain the following result.
Corollary 12. Let $\mathcal{G}$ be a $k$-uniform hypergraph with $n$ vertices and $m$ edges. Then

$$
\sum_{j=1}^{n} \alpha_{j}(\mathcal{G}) \leqslant \frac{(k-1) k m}{n-1}, j \in V(\mathcal{G})
$$

Let $\mathcal{G}$ be a $k$-uniform hypergraph. For $x, y \in V(\mathcal{G})$, let $c(x, y)=\mid\{e \in E(\mathcal{G}): x, y \in$ $e\} \mid$. A $2-(n, b, k, r, \lambda)$ design can be regarded as a $k$-uniform $r$-regular hypergraph $\mathcal{G}$ on $n$ vertices, $b$ edges, and $c(x, y)=\lambda$ for any pair of distinct $x, y \in V(\mathcal{G})$. A 2-design satisfying $n=b$ is called a symmetric design.

Theorem 13. Let $\mathcal{G}$ be a connected $k$-uniform hypergraph with $n$ vertices. Then $\mathcal{G}$ is a 2 -design if and only if $\alpha_{1}(\mathcal{G})=\cdots=\alpha_{n}(\mathcal{G})=\frac{\Delta(k-1)}{n-1}$, where $\Delta$ is the maximum degree of $\mathcal{G}$.

Proof. We first prove the necessity. If $\mathcal{G}$ is a $2-(n, b, k, r, \lambda)$ design, then $\lambda(n-1)=r(k-1)$ and $\Delta=r=d_{1}=\cdots=d_{n}$. For any $j \in V(\mathcal{G})$, by Theorem 11, we have

$$
\begin{equation*}
\alpha_{j}(\mathcal{G}) \leqslant \frac{r(k-1)}{n-1}=\lambda . \tag{9}
\end{equation*}
$$

Let $\mathbf{x}=\left(x_{1}, \ldots, x_{n}\right)^{\mathrm{T}} \in \mathbb{R}_{+}^{n}$ satisfying $x_{j}=0, \sum_{i=1}^{n} x_{i}^{k}=1$ and $\alpha_{j}(\mathcal{G})=\mathcal{L}_{\mathcal{G}} \mathbf{x}^{k}$. Then we get

$$
\begin{equation*}
\alpha_{j}(\mathcal{G})=\mathcal{L}_{\mathcal{G}} \mathbf{x}^{k} \geqslant \sum_{\left\{i_{1}, \ldots, i_{k}\right\} \in E_{j}(\mathcal{G})}\left(x_{i_{1}}^{k}+\cdots+x_{i_{k}}^{k}-k x_{i_{1}} \cdots x_{i_{k}}\right)=\lambda \sum_{i \neq j} x_{i}^{k}=\lambda . \tag{10}
\end{equation*}
$$

Combining (9) and (10), we get

$$
\alpha_{1}(\mathcal{G})=\cdots=\alpha_{n}(\mathcal{G})=\lambda=\frac{r(k-1)}{n-1}=\frac{\Delta(k-1)}{n-1} .
$$

Next we prove the sufficiency. Let $\alpha_{1}(\mathcal{G})=\cdots=\alpha_{n}(\mathcal{G})=\frac{\Delta(k-1)}{n-1}$. From Theorem 11, we obtain $d_{1}=\cdots=d_{n}=\Delta$. Let $\mathbf{z}=\left((n-1)^{-\frac{1}{k}}, \ldots,(n-1)^{-\frac{1}{k}}\right)^{\mathrm{T}} \in \mathbb{R}_{+}^{n-1}$. For $j \in V(\mathcal{G})$, let $\mathbf{y}=\left(y_{1}, \ldots, y_{n}\right)^{\mathrm{T}} \in \mathbb{R}_{+}^{n}$ be a vector such that $y_{i}=0$ if $i=j$ and $y_{i}=(n-1)^{-\frac{1}{k}}$ otherwise. Then

$$
\begin{aligned}
\mathcal{L}_{\mathcal{G}} \mathbf{y}^{k} & =\sum_{\left\{i_{1}, \ldots, i_{k}\right\} \in E(\mathcal{G})}\left(y_{i_{1}}^{k}+\cdots+y_{i_{k}}^{k}-k y_{i_{1}} \cdots y_{i_{k}}\right)=\sum_{\left\{i_{1}, \ldots, i_{k}\right\} \in E_{j}(\mathcal{G})}\left(y_{i_{1}}^{k}+\cdots+y_{i_{k}}^{k}\right) \\
& =\frac{\Delta(k-1)}{n-1}=\alpha_{j}(\mathcal{G})=\alpha(\mathcal{G}) .
\end{aligned}
$$

We know that $\alpha(\mathcal{G})=\alpha_{j}(\mathcal{G})$ is the smallest H-eigenvalue of $\mathcal{L}_{\mathcal{G}}(j)$. Since $\mathcal{L}_{\mathcal{G}}(j) \mathbf{z}^{k}=$ $\mathcal{L}_{\mathcal{G}} \mathbf{y}^{k}=\alpha(\mathcal{G}), \mathbf{z}$ is an H-eigenvector corresponding to $\alpha(\mathcal{G})$, that is

$$
\alpha(\mathcal{G}) \mathbf{z}^{[k-1]}=\mathcal{L}_{\mathcal{G}}(j) \mathbf{z}^{k-1}
$$

For all $i \in V(\mathcal{G}) \backslash\{j\}$, we have

$$
\begin{aligned}
\alpha(\mathcal{G}) & =\frac{1}{z_{i}^{k-1}}\left(\mathcal{L}_{\mathcal{G}}(j) \mathbf{z}^{k-1}\right)_{i}=\frac{1}{z_{i}^{k-1}} \sum_{i_{2}, \ldots . i_{k} \neq j}\left(\mathcal{L}_{\mathcal{G}}(j)\right)_{i i_{2} \cdots i_{k}} z_{i_{2}} \cdots z_{i_{k}} \\
& =\sum_{i_{2}, \ldots, i_{k} \neq j}\left(\mathcal{L}_{\mathcal{G}}\right)_{i i_{2} \cdots i_{k}}=c(i, j) .
\end{aligned}
$$

So $c(i, j)=\alpha(\mathcal{G})$ for any pair of distinct $i, j \in V(\mathcal{G})$, which implies that $\mathcal{G}$ is a 2-design.
We give an estimation of the edge connectivity of a 2-design as follows.
Theorem 14. Let $\mathcal{G}$ be a $2-(n, b, k, r, \lambda)$ design. Then

$$
\frac{n \lambda}{k} \leqslant e(\mathcal{G}) \leqslant \frac{(n-1) \lambda}{k-1}
$$

Moreover, if $\mathcal{G}$ is a symmetric design, then $e(\mathcal{G})=k=r$.
Proof. Since $\mathcal{G}$ is a 2- $(n, b, k, r, \lambda)$ design, we have $\lambda(n-1)=r(k-1)$. By Theorem 13, we have

$$
\alpha(\mathcal{G})=\frac{r(k-1)}{n-1}=\lambda .
$$

It follows from Lemma 2 that

$$
\begin{equation*}
\frac{n \lambda}{k}=\frac{n}{k} \alpha(\mathcal{G}) \leqslant e(\mathcal{G}) \leqslant r=\frac{(n-1) \lambda}{k-1} . \tag{11}
\end{equation*}
$$

Moreover, if $\mathcal{G}$ is a symmetric design, then $n=b$. Since $n r=b k$, we have $r=k$. From $\lambda(n-1)=r(k-1)$ and (11), we have

$$
\frac{n(k-1)}{n-1} \leqslant e(\mathcal{G}) \leqslant k
$$

Since $e(\mathcal{G})$ is a positive integer, we get $e(\mathcal{G})=k=r$.

## 4 Inverse Perron values and resistance distance of graphs

For a vertex $i$ of a connected graph $G$, we define its resistance eccentricity as $r_{i}(G)=$ $\max _{j \in V(G)} r_{i j}$.

Theorem 15. Let $G$ be a connected graph. For any $i \in V(G)$, we have

$$
r_{i}(G) \leqslant \frac{1}{\alpha_{i}(G)} .
$$

Proof. Without loss of generality, assume that $i$ is the vertex corresponding to the last row of the Laplacian matrix $\mathcal{L}_{G}$. Since $\alpha_{i}(G)$ is the minimum eigenvalue of the principal submatrix $\mathcal{L}_{G}(i), \alpha_{i}^{-1}(G)$ is the spectral radius of the symmetric nonnegative matrix $\mathcal{L}_{G}(i)^{-1}$. So $\alpha_{i}^{-1}(G) \geqslant \max _{j \neq i}\left(\mathcal{L}_{G}(i)^{-1}\right)_{j j}$.

By Lemmas 5 and 3, we get $r_{i j}(G)=\left(\mathcal{L}_{G}(i)^{-1}\right)_{j j}$ for any $j \neq i$. Hence

$$
\begin{aligned}
\alpha_{i}^{-1}(G) & \geqslant \max _{j \neq i}\left(\mathcal{L}_{G}(i)^{-1}\right)_{j j}=r_{i}(G), \\
r_{i}(G) & \leqslant \frac{1}{\alpha_{i}(G)} .
\end{aligned}
$$

For a vertex $i$ of a connected graph $G$, its resistance centrality is defined as $K f_{i}(G)=$ $\sum_{j \in V(G)} r_{i j}(G)$. It is used to measure the centrality of a network [4]. Note that $K f(G)=$ $\sum_{\{i, j\} \subseteq V(G)} r_{i j}(G)=\frac{1}{2} \sum_{i \in V(G)} K f_{i}(G)$.

Theorem 16. Let $G$ be a connected graph with $n$ vertices. For any $i \in V(G)$, we have

$$
n K f_{i}(G)-K f(G) \leqslant \frac{n-1}{\alpha_{i}(G)} .
$$

Proof. Note that $\alpha_{i}^{-1}(G)$ is the maximum eigenvalue of the symmetric matrix $\mathcal{L}_{G}(i)^{-1}$. Let $\mathbf{e}$ be the all-ones column vector, then

$$
\alpha_{i}^{-1}(G) \geqslant \frac{\mathbf{e}^{\top} \mathcal{L}_{G}(i)^{-1} \mathbf{e}}{\mathbf{e}^{\top} \mathbf{e}}=\frac{\mathbf{e}^{\top} \mathcal{L}_{G}(i)^{-1} \mathbf{e}}{n-1} .
$$

By Lemmas 5 and 4, we have

$$
K f(G)=n \operatorname{tr}\left(\mathcal{L}_{G}(i)^{-1}\right)-\mathbf{e}^{\top} \mathcal{L}_{G}(i)^{-1} \mathbf{e} .
$$

From Lemmas 5 and 3, we get $r_{i j}(G)=\left(\mathcal{L}_{G}(i)^{-1}\right)_{j j}$ for any $j \neq i$. Hence $\operatorname{tr}\left(\mathcal{L}_{G}(i)^{-1}\right)=$ $K f_{i}(G)$ and

$$
K f(G)=n K f_{i}(G)-\mathbf{e}^{\top} \mathcal{L}_{G}(i)^{-1} \mathbf{e} .
$$

By $\alpha_{i}^{-1}(G) \geqslant \frac{\mathbf{e}^{\top} \mathcal{L}_{G}(i)^{-1} \mathbf{e}}{n-1}$ we get

$$
\begin{aligned}
\alpha_{i}^{-1}(G) \geqslant \frac{\mathbf{e}^{\top} \mathcal{L}_{G}(i)^{-1} \mathbf{e}}{n-1} & =\frac{n K f_{i}(G)-K f(G)}{n-1}, \\
n K f_{i}(G)-K f(G) & \leqslant \frac{n-1}{\alpha_{i}(G)} .
\end{aligned}
$$

Corollary 17. Let $G$ be a connected graph with $n$ vertices. Then

$$
K f(G) \leqslant \frac{n-1}{n} \sum_{i=1}^{n} \alpha_{i}^{-1}(G) .
$$

Proof. By Theorem 16, we have

$$
\begin{gathered}
\sum_{i=1}^{n} \frac{n-1}{\alpha_{i}(G)} \geqslant \sum_{i=1}^{n}\left(n K f_{i}(G)-K f(G)\right)=n K f(G), \\
K f(G) \leqslant \frac{n-1}{n} \sum_{i=1}^{n} \alpha_{i}^{-1}(G) .
\end{gathered}
$$

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