

Structure of Tight $(k, 0)$ -Stable Graphs

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Abstract

We say that a graph G is (k, ℓ) -stable if removing k vertices from it reduces its independence number by at most ℓ . We say that G is tight (k, ℓ) -stable if it is (k, ℓ) -stable and its independence number equals $\lfloor \frac{n-k+1}{2} \rfloor + \ell$, the maximum possible, where n is the vertex number of G . Answering a question of Dong and Wu, we show that every tight $(2, 0)$ -stable graph with odd vertex number must be an odd cycle. Moreover, we show that for all $k \geq 3$, every tight $(k, 0)$ -stable graph has at most $k + 6$ vertices.

Mathematics Subject Classifications: 05C69

1 Introduction

The resilience of graph properties is a fundamental question in graph theory. Motivated by studies on the Erdős–Rogers function, Dong and Wu [3] investigated the resilience of graph independence number with respect to removing vertices. For a graph $G = (V, E)$ and vertices $v_1, \dots, v_k \in V$, we let $G \setminus \{v_1, \dots, v_k\}$ denote the induced subgraph of G on $V \setminus \{v_1, \dots, v_k\}$. For integers $k > \ell \geq 0$, we say that G is (k, ℓ) -stable if for any k vertices $v_1, \dots, v_k \in V$, we have $\alpha(G \setminus \{v_1, \dots, v_k\}) \geq \alpha(G) - \ell$.

A result in [3] states that any (k, ℓ) -stable graph G on n vertices satisfies

$$\alpha(G) \leq \lfloor \frac{n-k+1}{2} \rfloor + \ell.$$

A (k, ℓ) -stable graph for which equality holds (i.e., $\alpha(G) = \lfloor \frac{n-k+1}{2} \rfloor + \ell$) is called *tight (k, ℓ) -stable*. When $\ell = 0$, it is easily seen that every K_{k+1} is tight $(k, 0)$ -stable. When $\ell > 0$, one can always obtain a tight (k, ℓ) -stable graph by taking the disjoint union of a tight $(k-1, \ell-1)$ -stable graph with an isolated vertex. Starting with $K_{k-\ell+1}$, this yields a tight (k, ℓ) -stable graph on $k+1$ vertices for any $k > \ell \geq 0$.

Suppose n is any integer greater than k . Does an n -vertex (k, ℓ) -stable graph always exist? The answer is “yes” when $(k, \ell) = (1, 0)$. Indeed, when n is even, any n -vertex

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balanced bipartite graph that contains a perfect matching is tight $(1,0)$ -stable. When n is odd, one can always take an $(n - 1)$ -vertex tight $(1,0)$ -stable graph and add an extra vertex adjacent to all its vertices, to form an n -vertex tight $(1,0)$ -stable graph. In general, by taking the disjoint union of a tight $(1,0)$ -stable graph with ℓ isolated vertices, we immediately obtain examples of tight $(\ell + 1, \ell)$ -stable graphs for arbitrary ℓ on any number of vertices $n > \ell + 1$.

Going one step further, we consider the case where $(k, \ell) = (2, 0)$. When n is even, one can find multiple examples of n -vertex tight $(2, 0)$ -stable graphs, such as a vertex-disjoint union of two odd cycles, or an even subdivision of K_4 . (We say that G' is an *even subdivision* of G if we can obtain G' from G by iteratively performing the following two-step operation: (i) take edge $uv \in E$ and two new vertices $u', v' \notin V$; (ii) replace V by $V \cup \{u', v'\}$ and E by $(E \setminus \{uv\}) \cup \{uu', u'v', v'v\}$.) However, when n is odd, the only example known so far is the n -cycle C_n .

Dong and Wu [3, Section 8] asked whether C_n is the only n -vertex tight $(2, 0)$ -stable graph when n is odd. We answer this question in the affirmative. Moreover, we will show the following structural properties on tight $(k, 0)$ -stable graphs for $k = 1$ and $k = 2$.

Theorem 1. *Let G be a tight $(k, 0)$ -stable graph on n vertices.*

- (a) *If $k = 1$ and n is even, then G contains a perfect matching.*
- (b) *If $k = 1$ and n is odd, then G has a spanning subgraph that is a vertex-disjoint union of an odd cycle and a (possibly empty) matching.*
- (c) *If $k = 2$ and n is odd, then G is an odd cycle.*
- (d) *If $k = 2$ and n is even, then G has a spanning subgraph that is either a vertex-disjoint union of two odd cycles, or an even subdivision of K_4 .*

Remark 2. The authors of [3] conjectured that every tight $(2,0)$ -stable graph is Hamiltonian. Here we point out that this is not the case, as every even subdivision of K_4 is tight $(2,0)$ -stable, but not every such subdivision is Hamiltonian.

Note that for every $k = 1, 2$ and $n > k$, one can always find a tight $(k, 0)$ -stable graph with n vertices. We show that this becomes different for $k \geq 3$. In particular, a tight $(3, 0)$ -stable graph has at most 9 vertices.

Theorem 3. *Let G be a tight $(3, 0)$ -stable graph. Then G has a spanning subgraph that is among the five graphs K_4 , K_5 , H_7 , T_9 , H_9 as in Figure 1.*

Observe that if G is tight $(k, 0)$ -stable, then for any vertex $v \in V$, $G \setminus \{v\}$ is tight $(k - 1, 0)$ -stable. Thus, Theorem 3 immediately gives the following.

Corollary 4. *For all $k \geq 3$, any tight $(k, 0)$ -stable graph has at most $k + 6$ vertices.*

We will prove Theorem 1(a)–(c) in Section 2. Our proof of Theorem 1(d) and Theorem 3 utilizes properties of α -critical graphs, which are graphs whose independence number is affected by any edge removal. In Section 3, we introduce the notion of α -criticality and prove these parts. Finally, in Section 4, we discuss some remaining questions about (k, ℓ) -stable graphs.

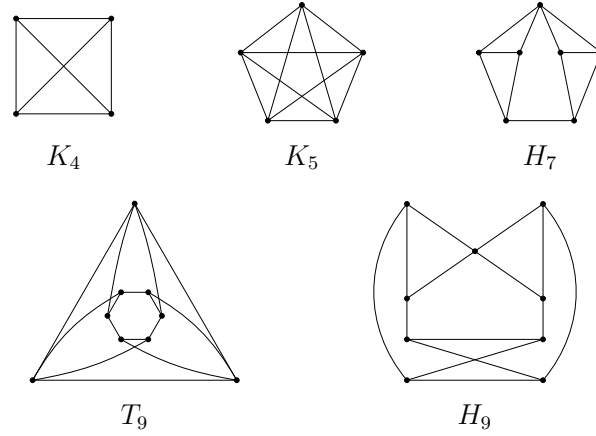


Figure 1: The five graphs listed in Theorem 3

2 Proof of Theorem 1(a)–(c)

We start by stating the following fact on $(1,0)$ -stable graphs that was proved in [3]. For completeness, we also include a proof of this result.

Lemma 5. *Let $G = (V, E)$ be a $(1,0)$ -stable graph, and let $A \subseteq V$ be a maximum independent set in G . Then there exists a matching of size $|A|$ between A and $V \setminus A$.*

Proof. It suffices to show that Hall's condition holds from A to $V \setminus A$. For every subset $S \subseteq A$, we use $N(S)$ to denote the neighborhood of S in G , which is a subset of $V \setminus A$ as A is independent. By contradiction, suppose there exists $Z \subseteq A$ such that $Z \neq \emptyset$ and $|N(Z)| < |Z|$. Without loss of generality, we may assume that Z is minimal. Take any $z \in Z$. Since $\alpha(G) = \alpha(G \setminus \{z\})$, there exists another maximum independent set A' in G that does not contain z .

Let $X_1 = Z \cap A'$ and $X_2 = Z \setminus A'$. Define $U = (A' \setminus N(X_2)) \cup X_2$. Since A' is independent, $X_2 \subseteq Z \subseteq A$ is independent and $A' \setminus N(X_2)$ does not contain any neighbors of X_2 , we know that $U = (A' \setminus N(X_2)) \cup X_2$ is independent.

Note that Z is a disjoint union of X_1 and X_2 . Since $X_1 \subseteq A'$ and A' is independent, for every $a \in A'$, we cannot have $a \in N(X_1)$, so $a \notin N(X_2)$ if and only if $a \notin N(Z) \setminus N(X_1)$. Hence we have $U = (A' \setminus (N(Z) \setminus N(X_1))) \cup X_2$. Since X_2 and A' are disjoint, this gives

$$\begin{aligned} |U| &= |A' \setminus (N(Z) \setminus N(X_1))| + |X_2| \\ &\geq |A'| - |N(Z) \setminus N(X_1)| + |X_2| \\ &= |A'| - |N(Z)| + |N(X_1)| + |X_2|. \end{aligned}$$

Since $z \in Z \setminus A'$, we have $X_1 \subsetneq Z$, so $|N(X_1)| \geq |X_1|$ by minimality of Z . Thus, we have

$$|U| \geq |A'| - |N(Z)| + |X_1| + |X_2| = |A'| - |N(Z)| + |Z| > |A'|,$$

contradicting the fact that A' is a maximum independent set in G . □

With Theorem 5, we can go ahead and prove Theorem 1(a)–(c).

Proof of Theorem 1(a). Suppose $G = (V, E)$ is a tight $(1, 0)$ -stable graph on n vertices, with n even. Then $\alpha(G) = \lfloor \frac{n}{2} \rfloor = \frac{n}{2}$. Let $A \subseteq V$ be a maximum independent set, so that $|A| = |V \setminus A| = \frac{n}{2}$. By Theorem 5, there exists a matching from A to $V \setminus A$, which is a perfect matching in G . $\square$

Proof of Theorem 1(b). Suppose $G = (V, E)$ is a tight $(1, 0)$ -stable graph on n vertices, with n odd. Then $\alpha(G) = \lfloor \frac{n}{2} \rfloor = \frac{n-1}{2}$. Let $m = \alpha(G) = \frac{n-1}{2}$ and $A \subseteq V$ be a maximum independent set, so that $|A| = m$ and $|V \setminus A| = m + 1$. By Theorem 5, there exists a matching of size m from A to $V \setminus A$. Label $V = \{a_1, \dots, a_m, b_1, \dots, b_m, c\}$ such that $A = \{a_1, \dots, a_m\}$, and $a_i b_i \in E$ for every $i \in [m]$. Let $B = \{b_1, \dots, b_m\}$.

For every $b_i \in B$, we say that b_i has property $(*)$ if there exists $\{i_1, \dots, i_s\} \subseteq [m]$ such that $i_s = i$, and $c - a_{i_1} - b_{i_1} - \dots - a_{i_s} - b_{i_s}$ is a path in G . Consider the partition $[m] = X \cup Y$ given by

$$\begin{aligned} X &= \{i \in [m] : b_i \text{ has property } (*)\}, \\ Y &= \{i \in [m] : b_i \text{ does not have property } (*)\}. \end{aligned}$$

Observe that there is no edge between $\{a_i : i \in Y\}$ and $\{b_i : i \in X\} \cup \{c\}$. If for some $i_0 \in Y$, a_{i_0} is adjacent to some vertex in $\{b_i : i \in X\} \cup \{c\}$, then b_{i_0} would have property $(*)$, contradicting the definition of Y . Since $\{a_i : i \in Y\} \subseteq A$ is independent, to avoid the independent set $\{a_i : i \in Y\} \cup \{b_i : i \in X\} \cup \{c\}$ (as it has size $m + 1$), there must be some edge within $\{b_i : i \in X\} \cup \{c\}$. One can then check that no matter where this edge occurs, it will create a spanning subgraph of G that is a vertex-disjoint union of one odd cycle and a (possibly empty) matching (see Figure 2 for an illustration). $\square$

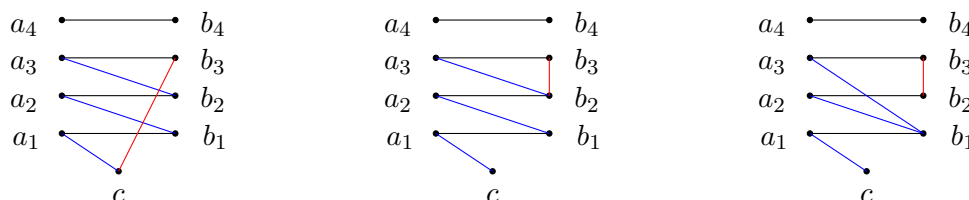


Figure 2: Some canonical cases in Theorem 1(b)

Proof of Theorem 1(c). Suppose $G = (V, E)$ is a tight $(2, 0)$ -stable graph on n vertices, with n odd. Then $\alpha(G) = \lfloor \frac{n-1}{2} \rfloor = \frac{n-1}{2} = \lfloor \frac{n}{2} \rfloor$. In particular, G is tight $(1, 0)$ -stable. By Theorem 1(b), G has a spanning subgraph H that is a vertex-disjoint union of one odd cycle and a (possibly empty) matching.

We first verify that $H = C_n$. By contradiction, suppose H is a vertex-disjoint union of a nonempty matching $e_1, \dots, e_s$ and an odd cycle C_{n-2s} , with $s \geq 1$. Then every independent set of size $\frac{n-1}{2}$ in G must include one vertex from each of $e_1, \dots, e_s$. Thus, removing

the two vertices in e_1 will destroy all maximum independent sets in G , contradicting the fact that G is $(2,0)$ -stable. Hence $H = C_n$. If $G \neq H$, i.e., G is an odd cycle plus some extra chords, then we can find another spanning subgraph H' of G that is a vertex-disjoint union of a smaller odd cycle and a nonempty matching, which by the argument above implies that G is not $(2,0)$ -stable. Thus, we must have $G = H = C_n$. $\square$

3 Proof of Theorem 1(d) and Theorem 3

In this section, we prove Theorem 1(d) and Theorem 3. As mentioned earlier, we first introduce the concept of α -critical graphs.

Definition 6. For graph $G = (V, E)$ and edge $uv \in E$, we let $G - uv$ denote the graph whose vertex set is V and edge set is $E \setminus \{uv\}$.

Definition 7. We say that $G = (V, E)$ is α -critical if for every edge $uv \in E$, we have $\alpha(G - uv) > \alpha(G)$.

We will utilize the following results, by Andrásfai [2] and Surányi [6], on connected α -critical graphs with independence number close to $n/2$. A survey on these results can be found at [5, Chapter 18]. A proof of Theorem 9 can also be found at [7].

Theorem 8 (Andrásfai). *Let $G = (V, E)$ be a connected α -critical graph with $|V| = 2\alpha(G) + 2$. Then G is an even subdivision of K_4 .*

Theorem 9 (Surányi). *Let $G = (V, E)$ be a connected α -critical graph with $|V| = 2\alpha(G) + 3$ and minimum degree at least 3. Then G must be one of K_5 , H_7 , H_9 or T_9 as in Theorem 3.*

Proof of Theorem 1(d). Suppose $G = (V, E)$ is a tight $(2,0)$ -stable graph on n vertices, with n even. By a greedy removal of edges, we can obtain a spanning subgraph G' of G , such that $\alpha(G') = \alpha(G) = n/2 - 1$ and G' is α -critical. Since G is $(2,0)$ -stable, so is the subgraph G' .

Let $G_1, \dots, G_t$ be the connected components of G' . For every $i \in [t]$, since G_i is $(2,0)$ -stable, we have $\alpha(G_i) \leq \left\lfloor \frac{|V(G_i)|-1}{2} \right\rfloor \leq \frac{|V(G_i)|-1}{2}$. This gives

$$\frac{n}{2} - 1 = \alpha(G') = \alpha(G_1) + \dots + \alpha(G_t) \leq \frac{1}{2}(|V(G_1)| + \dots + |V(G_t)| - t) = \frac{n-t}{2},$$

so $t \leq 2$.

If $t = 1$, then G' is a connected α -critical graph with $|V(G')| = 2\alpha(G') + 2$. By Theorem 8, G' is an even subdivision of K_4 .

If $t = 2$, then G' is a vertex-disjoint union of G_1 and G_2 , each of which has $\alpha(G_i) = \frac{|V(G_i)|-1}{2}$. This implies that both G_1 and G_2 are tight $(2,0)$ -stable graphs with odd vertex number. By Theorem 1(c), G' is a vertex-disjoint union of two odd cycles. $\square$

We now move on to prove Theorem 3.

Proof of Theorem 3. Suppose $G = (V, E)$ is a tight $(3, 0)$ -stable graph on n vertices.

If n is even, then $\alpha(G) = \lfloor \frac{n-2}{2} \rfloor = \frac{n}{2} - 1$. Fix any vertex $v \in V$. Since G is $(3, 0)$ -stable, $G \setminus \{v\}$ is $(2, 0)$ -stable. Moreover, since $\alpha(G \setminus \{v\}) = \frac{n}{2} - 1 = \lfloor \frac{(n-1)-1}{2} \rfloor$, we know that $G \setminus \{v\}$ is tight $(2, 0)$ -stable. By Theorem 1(c), $G \setminus \{v\}$ is an odd cycle. We therefore know that $G \setminus \{v\}$ is an odd cycle for every $v \in V$. The only graph that has this property is the 4-vertex complete graph K_4 .

If n is odd, then $\alpha(G) = \lfloor \frac{n-2}{2} \rfloor = \frac{n-3}{2}$. Again, by a greedy removal of edges, we can obtain a spanning subgraph G' of G , such that $\alpha(G') = \alpha(G) = \frac{n-3}{2}$ and G' is α -critical. Since G is $(3, 0)$ -stable, so is the subgraph G' . Let $G_1, \dots, G_t$ be the connected components of G' . For every $i \in [t]$, since G_i is $(3, 0)$ -stable, we have $\alpha(G_i) \leq \lfloor \frac{|V(G_i)|-2}{2} \rfloor \leq \frac{|V(G_i)|-2}{2}$. This gives

$$\frac{n-3}{2} = \alpha(G') = \alpha(G_1) + \dots + \alpha(G_t) \leq \frac{1}{2}(|V(G_1)| + \dots + |V(G_t)| - 2t) = \frac{n-2t}{2},$$

so $t = 1$. Therefore, G' is a connected α -critical graph with $|V(G')| = 2\alpha(G') + 3$.

We further note that G' has minimum degree at least 3. By contradiction, if G' has a vertex v of degree ≤ 2 , then by removing v and its neighbors from G' , we are able to remove at most 3 vertices from G' and reduce its independence number, which means that G' is not $(3, 0)$ -stable. Hence G' is a connected α -critical graph with $|V(G')| = 2\alpha(G') + 3$ and minimum degree at least 3. By Theorem 9, G' must be one of K_5 , H_7 , H_9 or T_9 . $\square$

4 Further questions

In this work, we investigated the structure of n -vertex $(k, 0)$ -stable graphs with independence number $\alpha = \lfloor \frac{n-k+1}{2} \rfloor$. Our results show that such graphs can be arbitrarily large for $k = 1, 2$ but are very sharply bounded in size when $k \geq 3$. While the cliques K_{k+1} and K_{k+2} are tight $(k, 0)$ -stable, we do not know any other natural infinite family of graphs G_k that is tight $(k, 0)$ -stable for each $k \geq 3$. Thus, we ask the following.

Question 10. Does there exist a positive integer k_0 such that, for all $k \geq k_0$, the only tight $(k, 0)$ -stable graphs are K_{k+1} and K_{k+2} ?

Our proofs suggest that there might be some connections between tight (k, ℓ) -stable graphs – whose independence number is resilient under vertex removal, and α -critical graphs – whose independence number is susceptible to edge removal. It would be interesting to understand these connections further.

Recall that every $(k, 0)$ -stable graph on n vertices has independence number at most $\lfloor \frac{n-k+1}{2} \rfloor$; Corollary 4 implies that for a fixed k , this upper bound cannot be attained for sufficiently large n . In the opposite direction, Dong and Wu [3] constructed a sequence of n -vertex $(3, 0)$ -stable graphs with independence number $n/2 - O(\sqrt{n})$. This was extended by Alon [1] who showed that for every $k > l \geq 0$, there exists a sequence of n -vertex (k, ℓ) -stable graphs with independence number $n/2 - o(n)$. For $k = 3$, we ask whether we can improve the $O(\sqrt{n})$ gap to a constant.

Question 11. Does there exist $c > 0$ such that there is a sequence of $(3, 0)$ -stable graphs G , with vertex number $n \rightarrow \infty$ and $\alpha(G) \geq |V(G)|/2 - c$?

Remark 12. We remark that Questions 10 and 11 were both resolved in the recent paper by Liu, Song, and Wang [4]. Question 10 was answered in the positive, while Question 11 was answered in the negative. The paper also made further progress in understanding tight (k, ℓ) -stable graphs for general ℓ .

Acknowledgments

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